

- Discrete Time Signals

- c. Classification of sequences

- c2. Energy and Power Signals

- total energy of a sequence $x[n]$

$$E_x = \sum_{n=-\infty}^{\infty} |x[n]|^2$$

- average power of a periodic sequence

$$P_x = \lim_{k \rightarrow \infty} \frac{1}{2k+1} \sum_{n=-k}^k |x[n]|^2$$

- average power of an aperiodic sequence

$$P_x = \frac{1}{N} \sum_{n=0}^{N-1} |\tilde{x}[n]|^2$$



- Discrete Time Signals

- c. Classification of sequences

- c3. Other types

- bounded sequence

$$|x[n]| \leq B_x < \infty$$

- absolutely summable

$$\sum_{n=-\infty}^{\infty} |x[n]| < \infty$$

- square summable (finite energy)

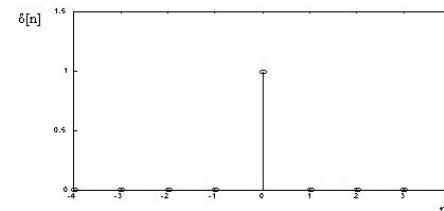
$$\sum_{n=-\infty}^{\infty} |x[n]|^2 < \infty$$



- Sequence รูปแบบเฉพาะ

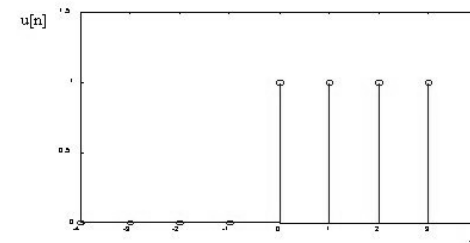
- a. unit sample sequence

$$\delta[n] = \begin{cases} 1, & n = 0 \\ 0, & n \neq 0 \end{cases} \quad \delta[n - k] = \begin{cases} 1, & n = k \\ 0, & n \neq k \end{cases}$$



- b. unit step sequence

$$u[n] = \begin{cases} 1, & n \geq 0 \\ 0, & n < 0 \end{cases} \quad u[n] = \sum_{n=0}^{\infty} \delta[n]$$



$$\delta[n] = u[n] - u[n - 1]$$

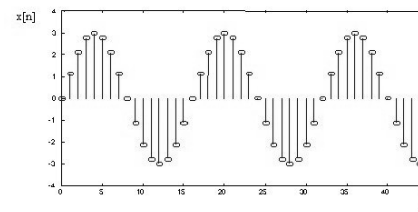


- Sequence รูปแบบเฉพาะ

c. Sinusoidal and Exponential sequences

Real sinusoidal sequence

$$x[n] = A \cos(\omega_0 n + \phi), \quad -\infty < n < \infty$$



$$x[n] = x_i[n] + x_q[n] \quad x_i[n] = A \cos(\phi) \cos(\omega_0 n) \quad x_q[n] = -A \sin(\phi) \sin(\omega_0 n)$$

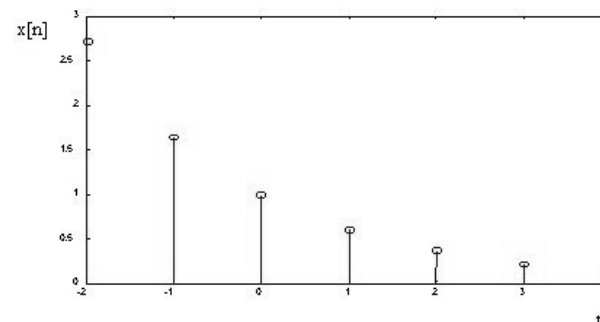
Exponential sequence

$$x[n] = A \alpha^n, \quad -\infty < n < \infty$$

$$\alpha = e^{(\sigma_0 + j\omega_0)}, \quad A = |A| e^{j\phi}$$

$$x[n] = A e^{(\sigma_0 + j\omega_0)n} = |A| e^{\sigma_0 n} e^{j(\omega_0 n + \phi)}$$

$$x[n] = |A| e^{\sigma_0 n} \cos(\omega_0 n + \phi) + j |A| e^{\sigma_0 n} \sin(\omega_0 n + \phi)$$



Discrete Time Signals and Systems in Time-Domain 2

- Sequence รูปแบบเฉพาะ
- c. Sinusoidal and Exponential
- Real sinusoidal sequence

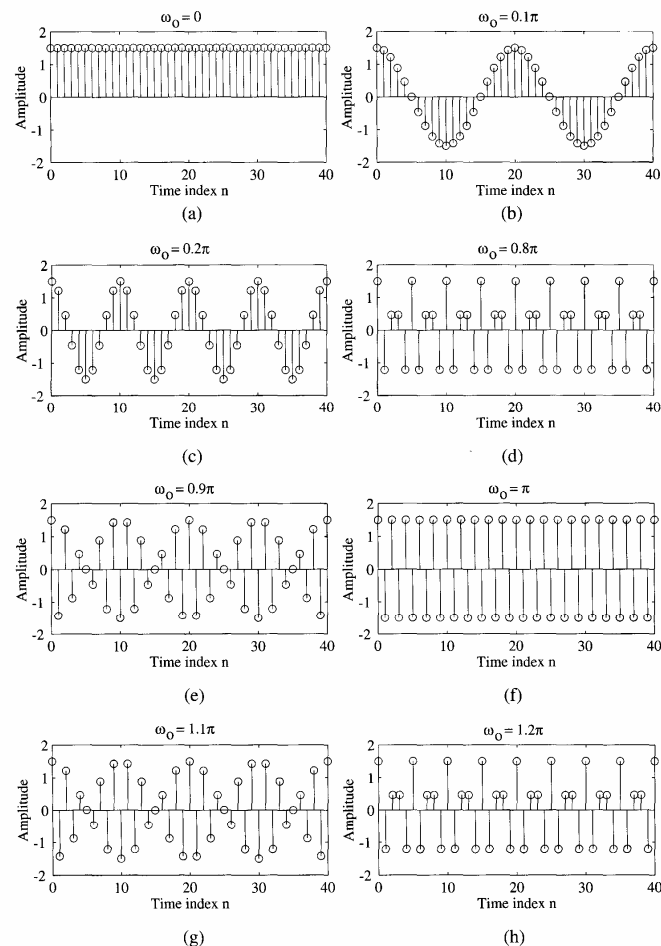


Figure 2.15: A family of sinusoidal sequences given by $x[n] = 1.5 \cos \omega_0 n$: (a) $\omega_0 = 0$, (b) $\omega_0 = 0.1\pi$, (c) $\omega_0 = 0.2\pi$, (d) $\omega_0 = 0.8\pi$, (e) $\omega_0 = 0.9\pi$, (f) $\omega_0 = \pi$, (g) $\omega_0 = 1.1\pi$, and (h) $\omega_0 = 1.2\pi$.



Discrete Time Signals and Systems in Time-Domain 2

- Sequence $x[n]$
- c. Sinusoidal and Exponential sequences

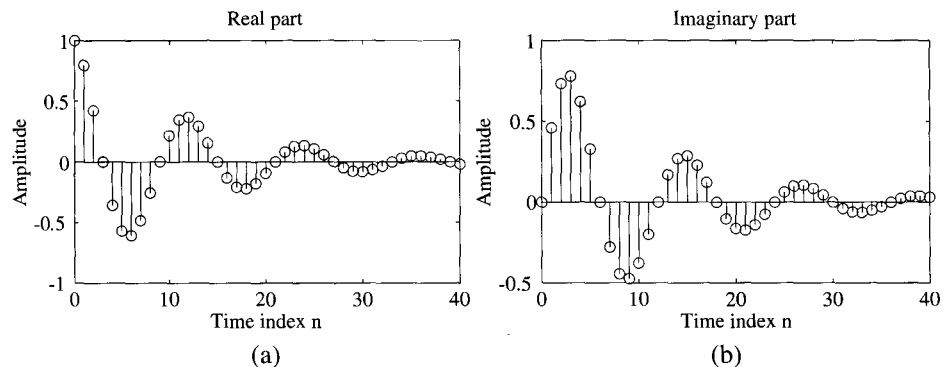


Figure 2.16: A complex exponential sequence $x[n] = e^{(-1/12 + j\pi/6)n}$. (a) Real part and (b) imaginary part.

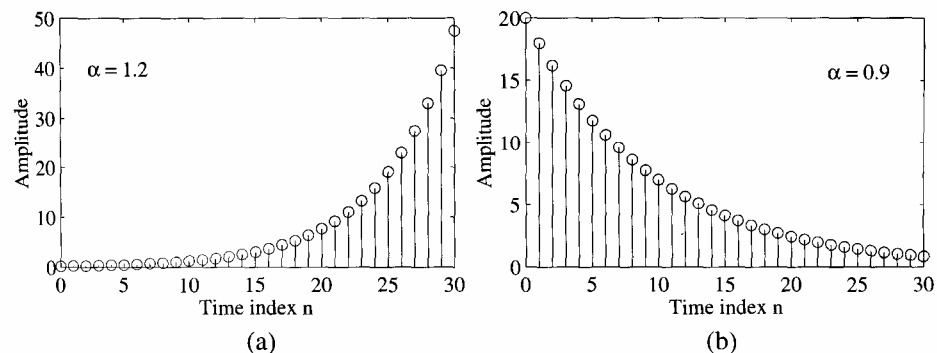


Figure 2.17: Examples of real exponential sequences: (a) $x[n] = 0.2(1.2)^n$, (b) $x[n] = 20(0.9)^n$.



- Sequence รูปแบบเฉพาะ

d. Representation of arbitrary sequence using unit sample sequence

$$x[n] = 0.5\delta[n + 2] + 1.5\delta[n - 1] - \delta[n - 2] + 2\delta[n - 4]$$



- Sampling Process
at discrete-time constant t_n

$$t_n = nT = \frac{n}{F_T} = \frac{2\pi n}{\Omega_T}$$

Ex2.12 Determine the discrete-time signal $v[n]$ obtained by uniformly sampling at a sampling rate of 200 Hz a continuous-time signal $v_a(t)$ composed of a weighted Sum of five sinusoidal signals of various frequencies, as given below:

$$v_a(t) = 6\cos(60\pi t) + 3\sin(300\pi t) + 2\cos(340\pi t) \\ + 4\cos(500\pi t) + 10\sin(660\pi t).$$



- Discrete-Time Systems
 - Simple Discrete-Time Systems

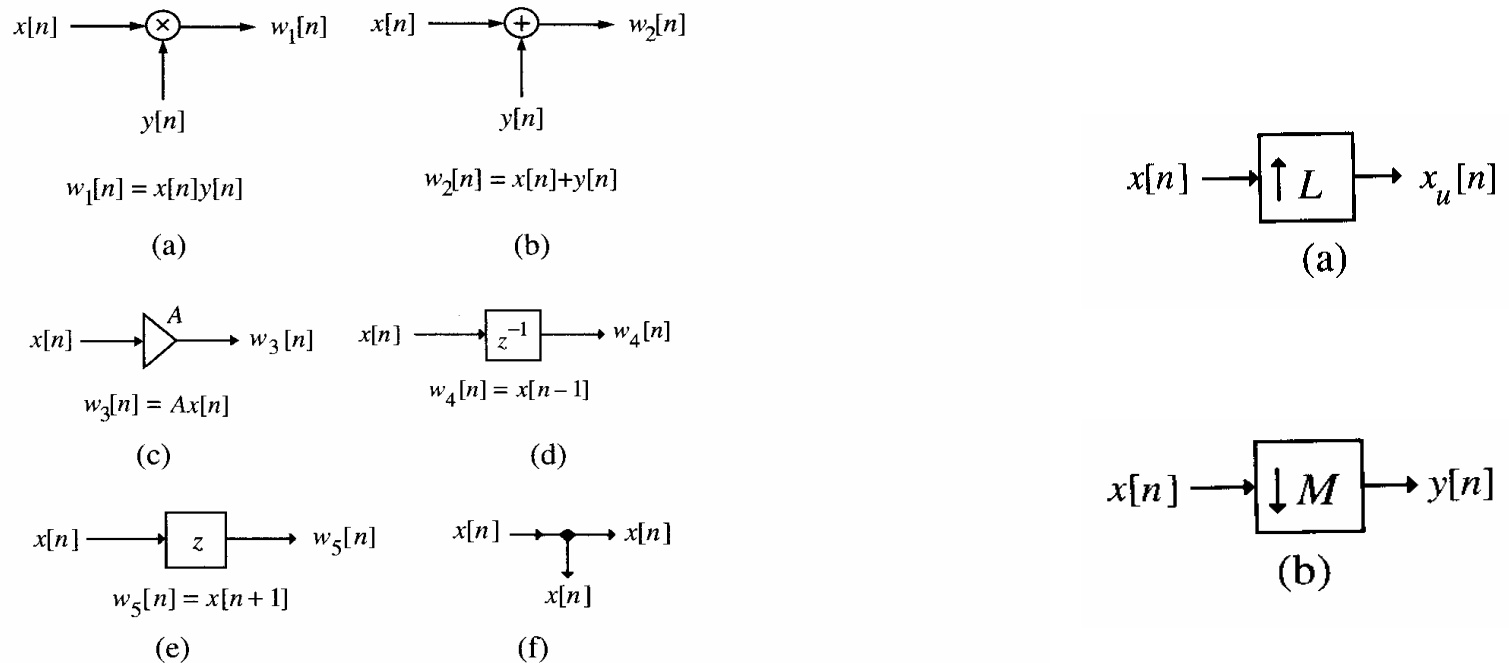


Figure 2.5: Schematic representations of basic operations on sequences: (a) modulator, (b) adder, (c) multiplier, (d) unit delay, (e) unit advance, and (f) pick-off node.



- Discrete-Time Systems

b. Complex Discrete-Time Systems

MA

AR

ARMA

Accumulator

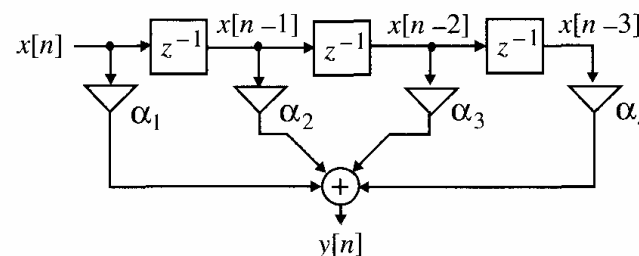


Figure 2.6: Discrete-time system of Example 2.3.

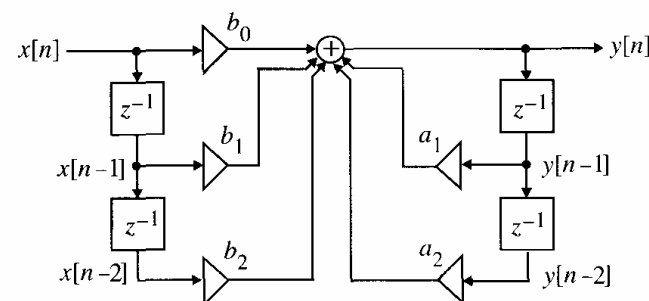


Figure 2.7: Discrete-time system of Example 2.4.



- Discrete-Time Systems
 - b. Classification of Discrete-Time Systems
 - b1. Linear System

$x_1[n]$ produces $y_1[n]$

$x_2[n]$ produces $y_2[n]$

$x[n] = \alpha x_1[n] + \beta x_2[n]$ must produce $y[n] = \alpha y_1[n] + \beta y_2[n]$



- Discrete-Time Systems
 - b. Classification of Discrete-Time Systems
 - b2. Time Invariant System

$x_1[n]$ produces $y_1[n]$

$x[n] = x_1[n - n_0]$ must produce $y[n] = y_1[n - n_0]$



- Discrete-Time Systems
- b. Classification of Discrete-Time Systems
- b3. Linear Time Invariant (LTI) System

รวมคุณสมบัติของทั้ง **linear** และ **Time invariant**

$x_1[n]$ produces $y_1[n]$

$x_2[n]$ produces $y_2[n]$

$x[n] = \alpha x_1[n - n_0] + \beta x_2[n - m_0]$ must produce

$y[n] = \alpha y_1[n - n_0] + \beta y_2[n - m_0]$



- Discrete-Time Systems

- b. Classification of Discrete-Time Systems

- b4. Causal System

ผลตอบของแต่ละจุดตัวอย่าง จะขึ้นอยู่กับขาเข้าก่อนหน้าหรือที่เวลานั้นเท่านั้น

causal $y[n] = \alpha_1 x[n] + \alpha_2 x[n-1] + \alpha_3 \delta[n-2]$

non-causal $y[n] = \alpha_1 x[n] + \alpha_2 x[n+1] + \alpha_3 \delta[n-1]$



- Discrete-Time Systems
- b. Classification of Discrete-Time Systems
- b5. Stable System

ทุกๆ bounded input จะให้ bounded output

$$|x[n]| < B_x \Rightarrow |y[n]| < B_y$$



- Discrete-Time Systems
- b. Classification of Discrete-Time Systems
- b6. Passive and Lossless Systems

Passive
$$\sum_{n=-\infty}^{\infty} |y[n]|^2 \leq \sum_{n=-\infty}^{\infty} |x[n]|^2 < \infty$$

Lossless
$$\sum_{n=-\infty}^{\infty} |y[n]|^2 = \sum_{n=-\infty}^{\infty} |x[n]|^2$$



- Time-Domain Characterization of LTI system

- a. Input-Output relationship

$$y[n] = x[n] * h[n]$$

เมื่อ $h[n]$ เป็นผลตอบอิมพัลส์ของ LTI system



Discrete Time Signals and Systems in Time-Domain 2

• Time-Domain Characterization of a System

a. Input-Output relationship

$$y[n] = x[n] * h[n]$$

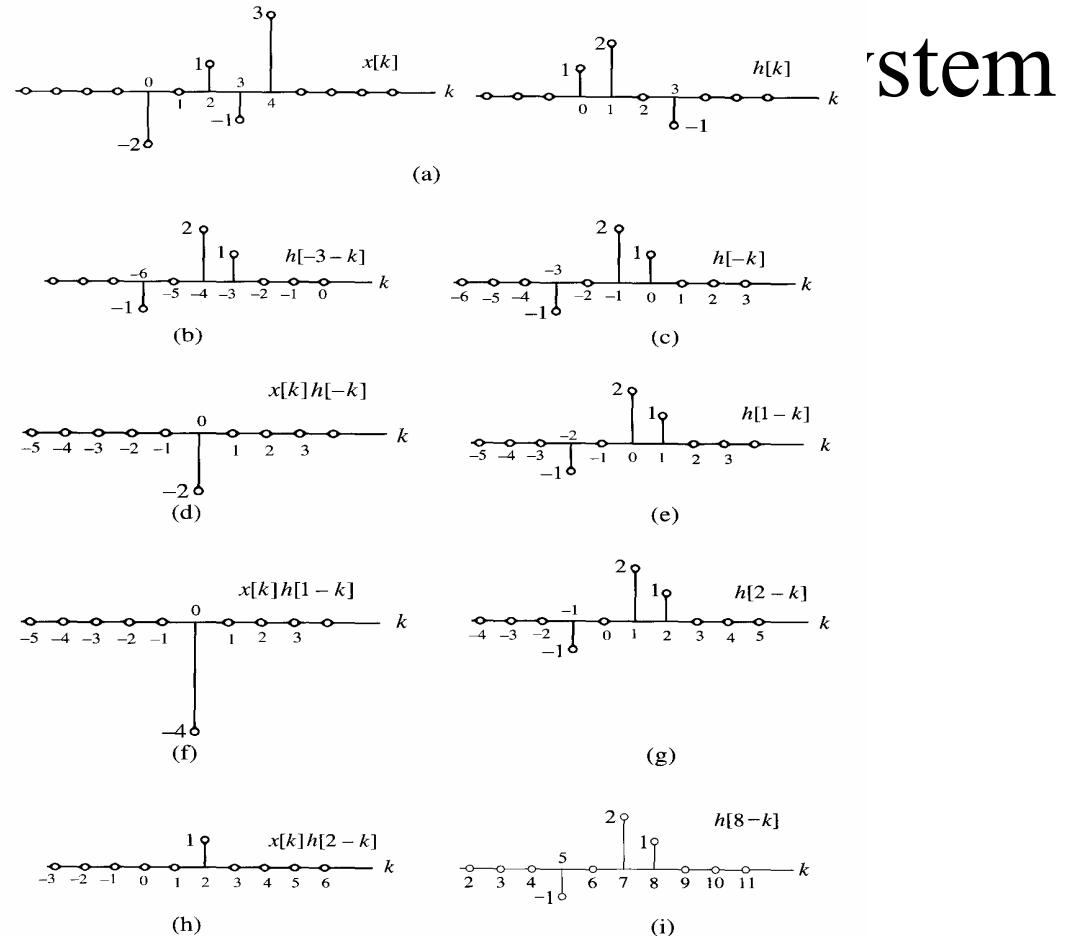


Figure 2.25: Illustration of the convolution process.



Discrete Time Signals and Systems in Time-Domain 2

• Time-Domain Characterization of a System

a. Input-Output relationship

$$y[n] = x[n] * h[n]$$

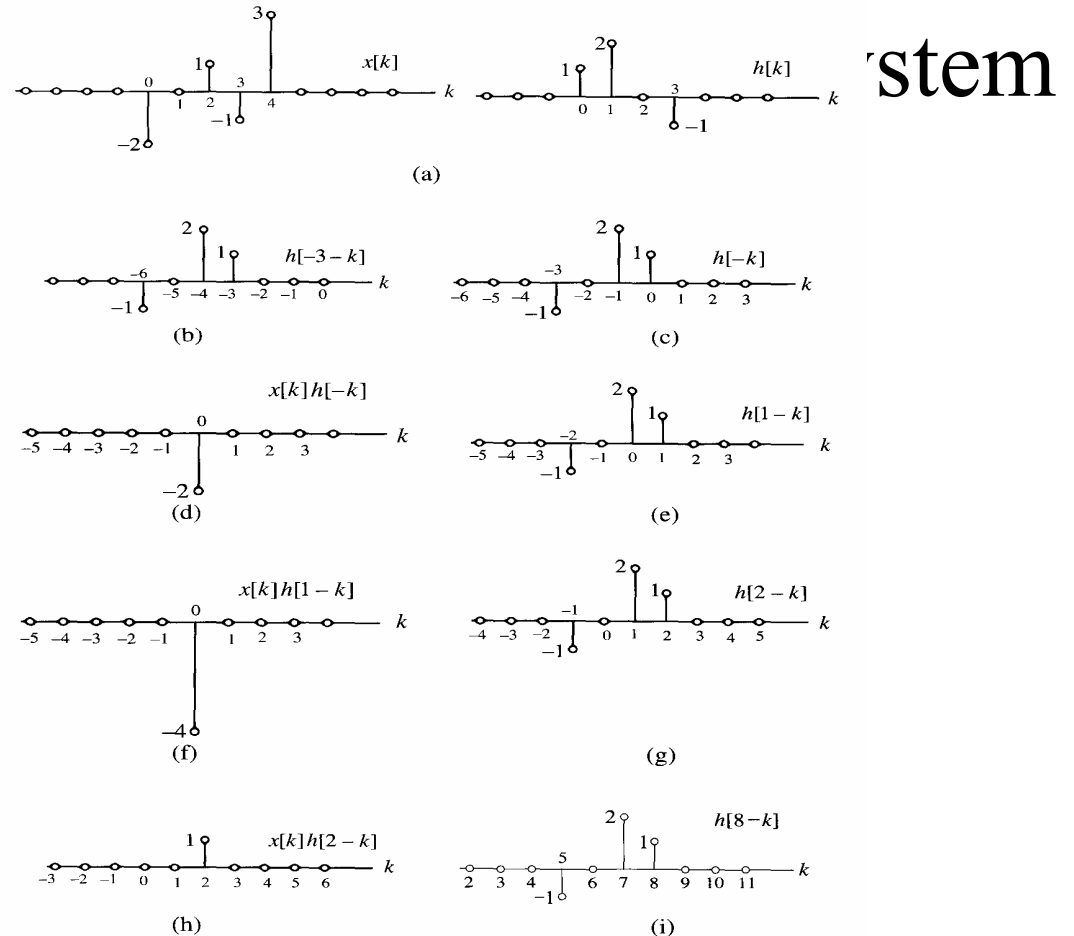


Figure 2.25: Illustration of the convolution process.



- Time-Domain Characterization of LTI system

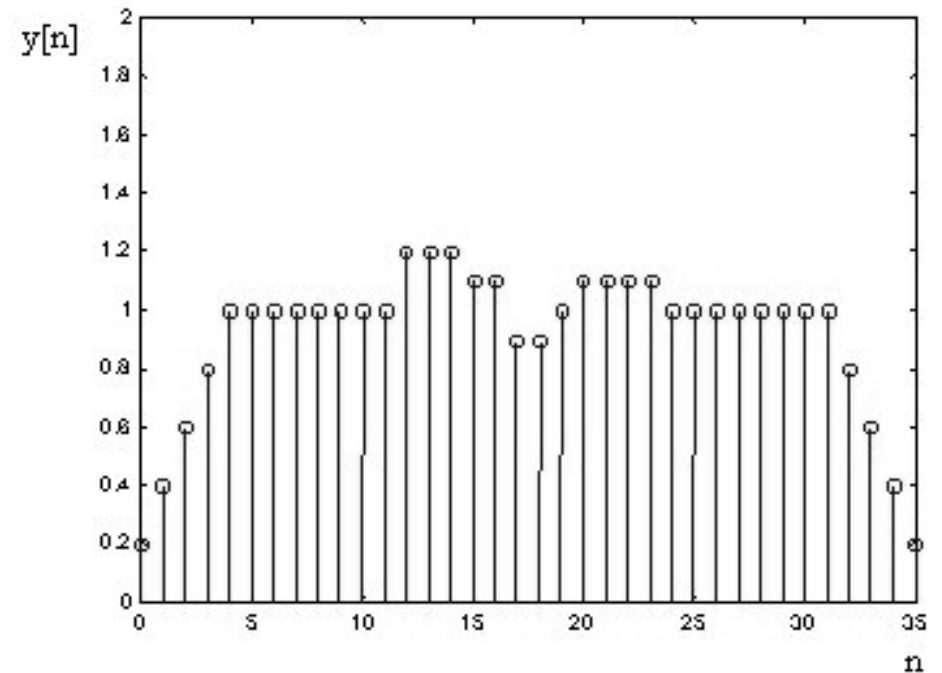
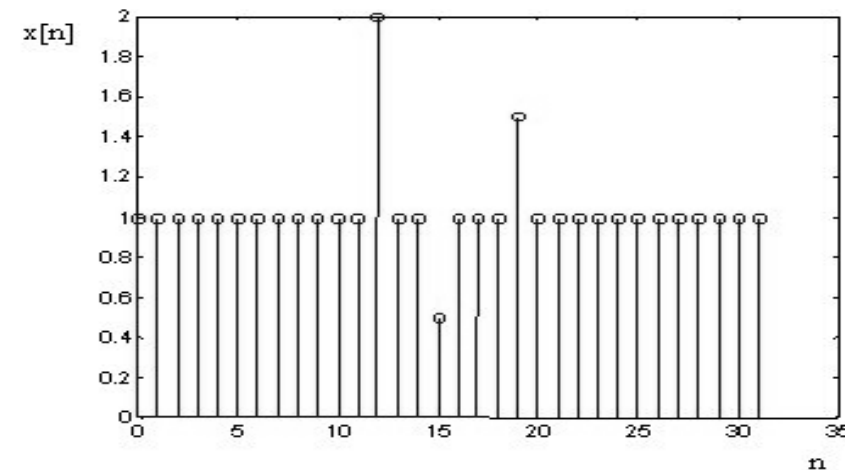
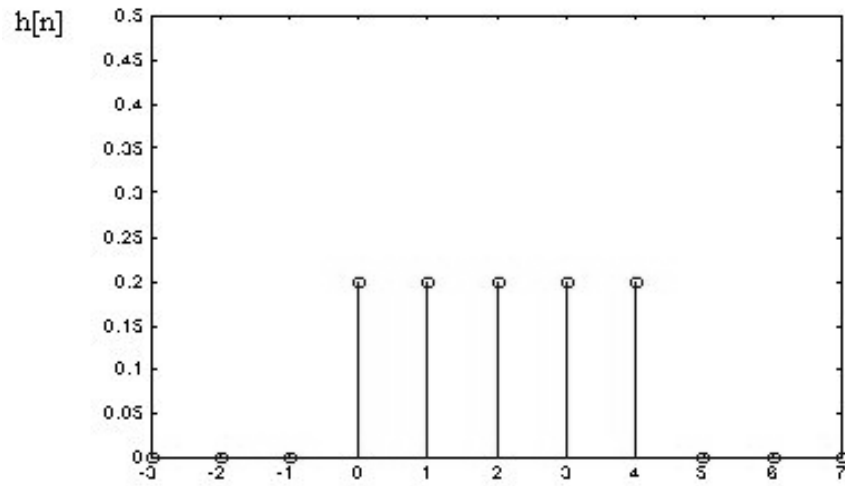
a. Input-Output relationship

$$y[n] = h[n] * x[n] = \sum_{k=-\infty}^{\infty} h[k]x[n-k]$$

x[n]:			2	1	-2				
h[-n]:	-1	2	1						y[0] = 2
h[1-n]:		-1	2	1					y[1] = 5
h[2-n]:			-1	2	1				y[2] = -2
h[3-n]:				-1	2	1			y[3] = -5
h[4-n]:					-1	2	1		y[4] = 2
h[5-n]:						-1	2	1	y[5] = 0



Discrete Time Signals and Systems in Time-Domain 2



- Time-Domain Characterization of LTI system

a. การเชื่อมต่อระบบ

Cascade

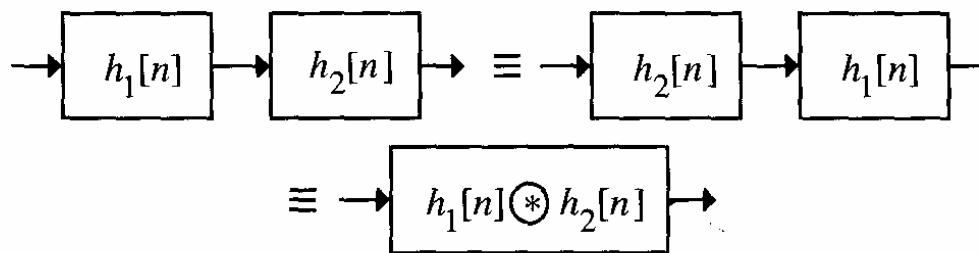


Figure 2.28: The cascade connection.

Parallel

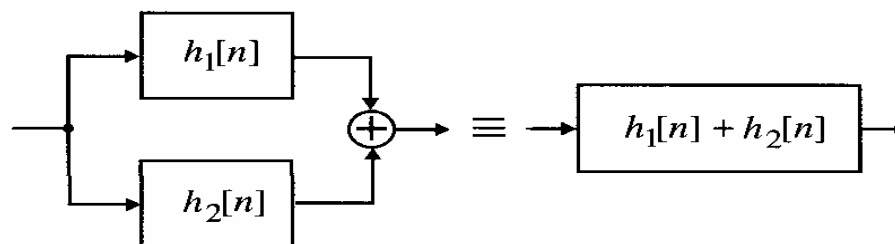


Figure 2.29: The parallel connection.



• Time-Domain Characterization of LTI system

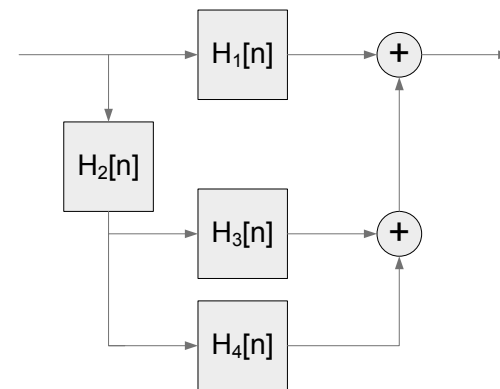
a. การเชื่อมต่อระบบ

Ex 2.27 Consider the discrete-time system composed of 4 discrete-time systems with impulse responses given by

$$h_1[n] = \delta[n] + \frac{1}{2}\delta[n-1], \quad h_2[n] = \frac{1}{2}\delta[n] - \frac{1}{4}\delta[n-1],$$

$$h_3[n] = 2\delta[n], \quad h_4[n] = -2\left(\frac{1}{2}\right)^n u[n].$$

Find the overall impulse response $h[n]$.



3.1 Discrete Time Fourier Transform – DTFT

- Fourier Transform ของ Discrete-Time sequence $x[n]$
- เป็นการแสดง sequence ในรูปแบบของ complex exponential sequence $\{e^{-j\omega n}\}$,
 ω เป็นตัวแปรความถี่ค่าจริง

Discrete-time Fourier Transform DTFT

$$X(e^{j\omega}) = \sum_{n=-\infty}^{\infty} x[n] e^{-j\omega n}$$



Definition

$$\begin{aligned} X(e^{j\omega}) &= \sum_{n=-\infty}^{\infty} x[n]e^{-j\omega n} \\ &= X_{re}(e^{j\omega}) + jX_{im}(e^{j\omega}) \\ &= |X(e^{j\omega})| e^{j\theta(\omega)} \end{aligned}$$

$$\text{เมื่อ } \theta(\omega) = \arg\{X(e^{j\omega})\}$$

$$|\cdot| = \text{magnitude function (spectrum)}$$

$$e^{j\theta(\omega)} = \text{phase function (spectrum)}$$

$$-\pi < \theta(\omega) < \pi \quad \text{เป็น principal value}$$



Ex 3.1For $\delta[n]$

$$\Delta(e^{j\omega}) = \sum_{n=-\infty}^{\infty} \delta[n] e^{(-j\omega n)} = 1$$

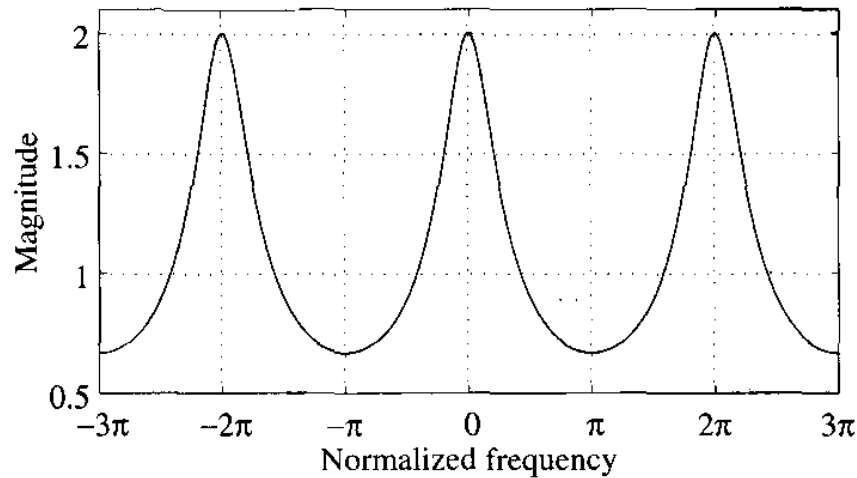
$$\sum_{n=-\infty}^{\infty} \delta[n - k] f[n] = f[k]$$



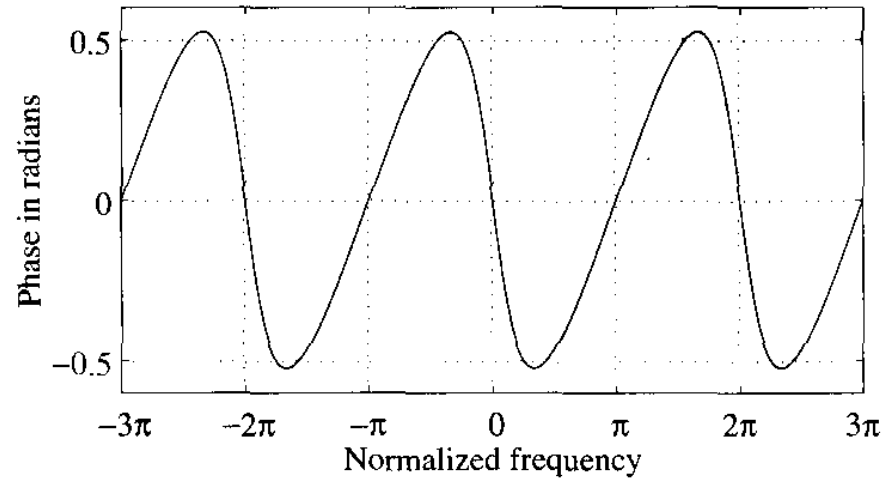
Ex 3.2 $x[n] = \alpha^n u[n] \quad : |\alpha| < 1$

$$\begin{aligned} X(e^{j\omega}) &= \sum_{n=-\infty}^{\infty} \alpha^n u[n] e^{-j\omega n} \\ &= \sum_{n=0}^{\infty} \alpha^n e^{-j\omega n} \\ &= \sum_{n=0}^{\infty} (\alpha e^{-j\omega})^n \\ &= \frac{1}{1 - \alpha e^{-j\omega}} \end{aligned}$$





(a)



(b)

Figure 3.1: Magnitude and phase of $X(e^{j\omega}) = 1/(1 - 0.5e^{-j\omega})$.



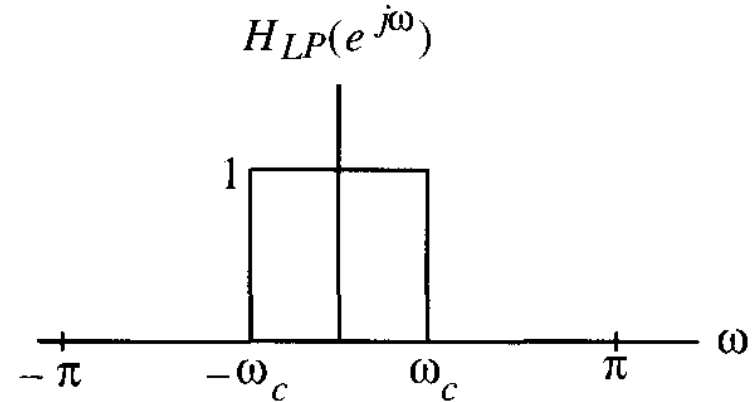
Inverse Discrete-time Fourier Transform IDTFT

$$x[n] = \frac{1}{2\pi} \int_{-\pi}^{\pi} X(e^{-j\omega}) e^{j\omega n} d\omega$$



Ex 3.3 Consider the DTFT

$$H_{LP}(e^{j\omega}) = \begin{cases} 1, & 0 \leq |\omega| \leq \omega_c \\ 0, & \omega_c \leq |\omega| \leq \pi \end{cases}$$



$$H_M(e^{j\omega}) = \sum_{n=-M}^M \frac{\sin \omega_c n}{\pi n} e^{-j\omega n}$$

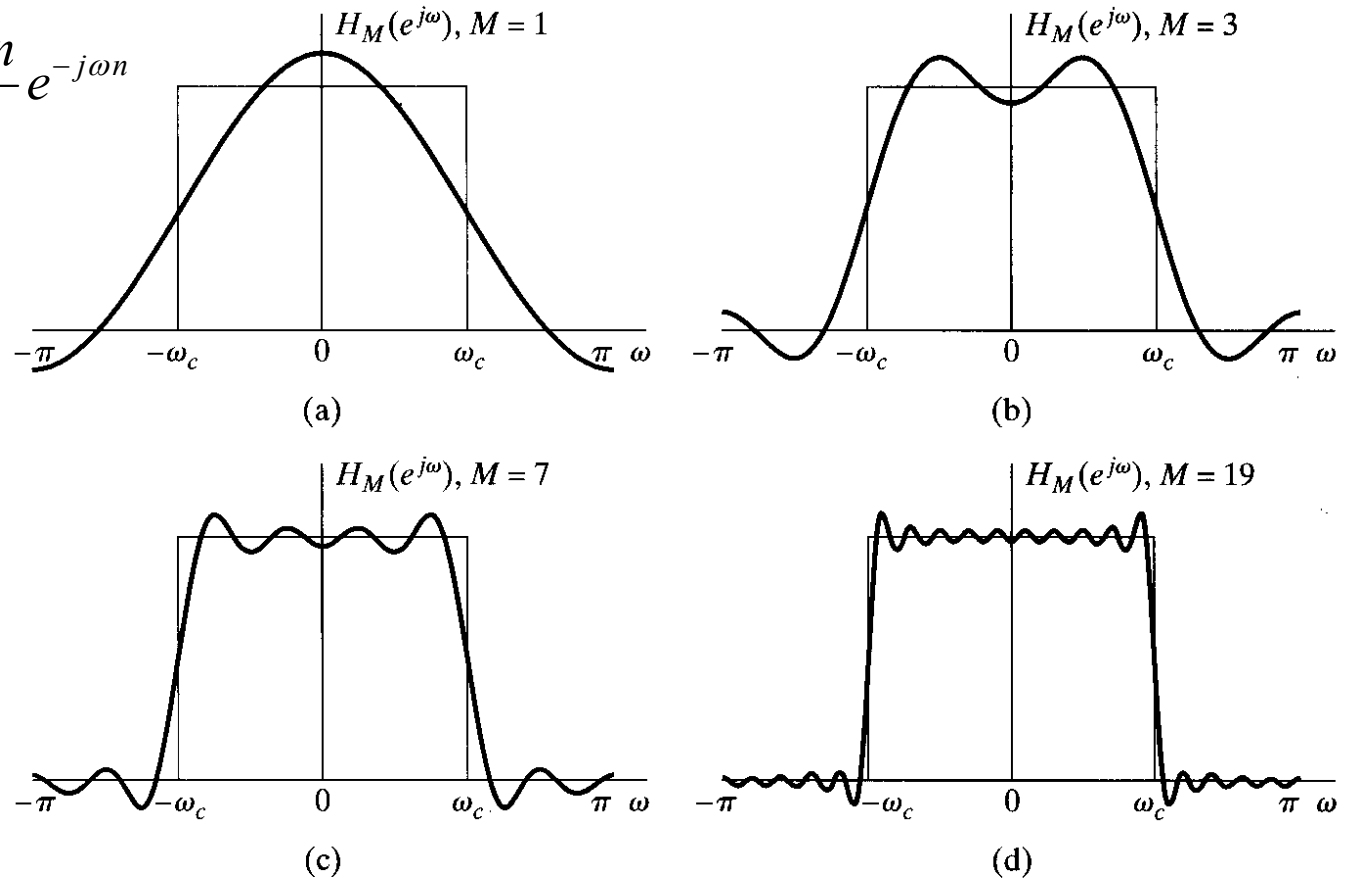


Figure 2.21 Convergence of the Fourier transform. The oscillatory behavior at $\omega = \omega_c$ is often called the Gibbs phenomenon.



Band-limited Signals

•full-band discrete-time signal $0 \leq |\omega| \leq \pi$

•bandlimited signal

lowpass discrete-time signal $0 \leq |\omega| \leq \omega_p \leq \pi$

Bandwidth $BW = \omega_p$

bandpass discrete-time signal $0 \leq \omega_L \leq |\omega| \leq \omega_H \leq \pi$

Bandwidth $BW = \omega_H - \omega_L$



DTFT Properties

TABLE 2.1 SYMMETRY PROPERTIES OF THE FOURIER TRANSFORM

Sequence $x[n]$	Fourier Transform $X(e^{j\omega})$
1. $x^*[n]$	$X^*(e^{-j\omega})$
2. $x^*[-n]$	$X^*(e^{j\omega})$
3. $\mathcal{R}e\{x[n]\}$	$X_e(e^{j\omega})$ (conjugate-symmetric part of $X(e^{j\omega})$)
4. $j\mathcal{I}m\{x[n]\}$	$X_o(e^{j\omega})$ (conjugate-antisymmetric part of $X(e^{j\omega})$)
5. $x_e[n]$ (conjugate-symmetric part of $x[n]$)	$X_R(e^{j\omega}) = \mathcal{R}e\{X(e^{j\omega})\}$
6. $x_o[n]$ (conjugate-antisymmetric part of $x[n]$)	$jX_I(e^{j\omega}) = j\mathcal{I}m\{X(e^{j\omega})\}$
<i>The following properties apply only when $x[n]$ is real:</i>	
7. Any real $x[n]$	$X(e^{j\omega}) = X^*(e^{-j\omega})$ (Fourier transform is conjugate symmetric)
8. Any real $x[n]$	$X_R(e^{j\omega}) = X_R(e^{-j\omega})$ (real part is even)
9. Any real $x[n]$	$X_I(e^{j\omega}) = -X_I(e^{-j\omega})$ (imaginary part is odd)
10. Any real $x[n]$	$ X(e^{j\omega}) = X(e^{-j\omega}) $ (magnitude is even)
11. Any real $x[n]$	$\angle X(e^{j\omega}) = -\angle X(e^{-j\omega})$ (phase is odd)
12. $x_e[n]$ (even part of $x[n]$)	$X_R(e^{j\omega})$
13. $x_o[n]$ (odd part of $x[n]$)	$jX_I(e^{j\omega})$



DTFT Properties

TABLE 2.2 FOURIER TRANSFORM THEOREMS

Sequence	Fourier Transform
$x[n]$	$X(e^{j\omega})$
$y[n]$	$Y(e^{j\omega})$
1. $ax[n] + by[n]$	$aX(e^{j\omega}) + bY(e^{j\omega})$
2. $x[n - n_d]$ (n_d an integer)	$e^{-j\omega n_d} X(e^{j\omega})$
3. $e^{j\omega_0 n} x[n]$	$X(e^{j(\omega - \omega_0)})$
4. $x[-n]$	$X(e^{-j\omega})$ $X^*(e^{j\omega})$ if $x[n]$ real.
5. $nx[n]$	$j \frac{dX(e^{j\omega})}{d\omega}$
6. $x[n] * y[n]$	$X(e^{j\omega})Y(e^{j\omega})$
7. $x[n]y[n]$	$\frac{1}{2\pi} \int_{-\pi}^{\pi} X(e^{j\theta})Y(e^{j(\omega - \theta)})d\theta$
Parseval's theorem:	
8. $\sum_{n=-\infty}^{\infty} x[n] ^2 = \frac{1}{2\pi} \int_{-\pi}^{\pi} X(e^{j\omega}) ^2 d\omega$	
9. $\sum_{n=-\infty}^{\infty} x[n]y^*[n] = \frac{1}{2\pi} \int_{-\pi}^{\pi} X(e^{j\omega})Y^*(e^{j\omega})d\omega$	



DTFT Properties

TABLE 2.3 FOURIER TRANSFORM PAIRS

Sequence	Fourier Transform
1. $\delta[n]$	1
2. $\delta[n - n_0]$	$e^{-j\omega n_0}$
3. 1 $(-\infty < n < \infty)$	$\sum_{k=-\infty}^{\infty} 2\pi \delta(\omega + 2\pi k)$
4. $a^n u[n]$ $(a < 1)$	$\frac{1}{1 - ae^{-j\omega}}$
5. $u[n]$	$\frac{1}{1 - e^{-j\omega}} + \sum_{k=-\infty}^{\infty} \pi \delta(\omega + 2\pi k)$
6. $(n + 1)a^n u[n]$ $(a < 1)$	$\frac{1}{(1 - ae^{-j\omega})^2}$
7. $\frac{r^n \sin \omega_p(n + 1)}{\sin \omega_p} u[n]$ $(r < 1)$	$\frac{1}{1 - 2r \cos \omega_p e^{-j\omega} + r^2 e^{-j2\omega}}$
8. $\frac{\sin \omega_c n}{\pi n}$	$X(e^{j\omega}) = \begin{cases} 1, & \omega < \omega_c, \\ 0, & \omega_c < \omega \leq \pi \end{cases}$
9. $x[n] = \begin{cases} 1, & 0 \leq n \leq M \\ 0, & \text{otherwise} \end{cases}$	$\frac{\sin[\omega(M + 1)/2]}{\sin(\omega/2)} e^{-j\omega M/2}$
10. $e^{j\omega_0 n}$	$\sum_{k=-\infty}^{\infty} 2\pi \delta(\omega - \omega_0 + 2\pi k)$
11. $\cos(\omega_0 n + \phi)$	$\sum_{k=-\infty}^{\infty} [\pi e^{j\phi} \delta(\omega - \omega_0 + 2\pi k) + \pi e^{-j\phi} \delta(\omega + \omega_0 + 2\pi k)]$



Ex 3.5 Determine the DTFT of the sequence $y[n] = (n + 1)\alpha^n u[n]$ $|\alpha| < 1$



Ex 3.6 Determine the DTFT $V(e^{j\omega})$ of the sequence $v[n]$ given by

$$d_0 v[n] + d_1 v[n-1] = p_0 \delta[n] + p_1 \delta[n-1] \quad |d_1 / d_0| < 1$$



Ex 3.7 Determine the impulse response of stable LTI system which input and output satisfy the constant-coefficient difference equation

$$y[n] - \frac{1}{2} y[n - 1] = x[n] - \frac{1}{4} x[n - 1]$$



Ex 3.8 Compute the energy of the sequence $h_{LP}[n]$ of Ex 3.3

$$H_{LP}(e^{i\omega}) = \begin{cases} 1, & 0 \leq |\omega| \leq \omega_c \\ 0, & \omega_c \leq |\omega| \leq \pi \end{cases}$$



3.2 Discrete Fourier Transform – DFT (Introduction)

- เฉพาะกรณีของ finite-length sequence $x[n]$, $0 \leq n \leq N-1$
- N ค่าของ $X(e^{j\omega})$ เรียกว่า frequency samples ที่จุดความถี่ต่างๆ กัน
 $\omega = \omega_k$, $0 \leq k \leq N-1$
- N ค่าของ $X(e^{j\omega})$ เพียงพอที่จะหา $x[n]$ ได้

Discrete Fourier Transform DFT

$$X[K] = \sum_{n=0}^{N-1} x[n] w_N^{kn} \quad 0 \leq k \leq N-1$$

