

Applied Mathematics 307 – Differential Equations for Engineers

1. Separable : $f(x)dx = g(t)dt \leftarrow$ form

2. Linear First Order ODE : $\frac{dx}{dt} + p(t)x = q(t) \leftarrow$ form

$$\text{Integrating Factor (IF)} = \mu(t) = e^{\int p(t)dt}; x\mu = \int q\mu dt + c$$

3. Bernoulli's DE : $\frac{dx}{dt} + p(t)x = q(t)x^n, n \neq 0, 1 \leftarrow$ form

$$\text{Use transformation : } V = x^{1-n}, \frac{dV}{dt} = \dots \frac{dx}{dt}$$

$\mapsto$ reduces DE to linear, first order in dep. var V

$\mapsto$ NOTE : linear and Bernoulli has 3 terms!

4. Homogeneous DE : $\frac{dx}{dt} = f(t, x) \leftarrow$ form

NOTE: homogeneous function of degree n (of 2 variables) : $f(\lambda t, \lambda x) = \lambda^n f(t, x), \lambda \in \mathbb{R}$

$\mapsto$ here, $n = 0 \Leftrightarrow f(t, x)$ is homog. function of degree

Use transformation : $x = vt, \frac{dx}{dt} = v + \dots \frac{dv}{dt}$ (chain rule : v is a function not const!)

5. Exact DE :

NOTE : Exact differential : $M(t, x)dt + N(t, x)dx$ is exact if it is total differential of $f(t, x)$

(ie, $df = M(t, x)dt + N(t, x)dx$)

NOTE : Exact DE : DE $M(t, x)dt + N(t, x)dx = 0$ is exact if $M(t, x)dt + N(t, x)dx$ is exact

$\mapsto$ Test for exactness : DE is exact if $\frac{\partial M}{\partial x} = \frac{\partial N}{\partial t} \leftarrow$ opposite variables (M with x etc.)

$M(t, x)dt + N(t, x)dx = 0$ (exact DE) $\leftarrow$ formdd

$F(t, x) = c, F(t, x)$ is sum of 2 partial integrals $\int M(t, x)dt$, & $\int N(t, x)dx$ w/out repeating common terms

5.1 Integrating factor for non – exact DE : non exact DE : $M(t, x)dt + N(t, x)dx = 0$

$\mu = \mu(t, x)$ is IF of DE if DE becomes exact upon multiplying both sides of DE by $\mu(t, x)$

6. DE of n^{th} order reducible to first order : $\frac{d^n x}{dt^n} + p(t)\frac{d^{n-1}x}{dt^{n-1}} = q(t) \leftarrow$ form (note consecutive deg)

Use transformation : $V = \frac{d^{n-1}x}{dt^{n-1}}, \frac{dV}{dt} = \dots \mapsto$ use c_1 and c_2 instead of just c

Newton's Law of Cooling (or Heating): $\left\{ \begin{array}{l} \frac{dx}{dt} = k(x-m), \quad x(t_1) = x_1 \mapsto \text{for finding } k \\ x(t_0) = x_0 \mapsto \text{for finding } c \end{array} \right.$

3 methods to solving: 1) $D: \text{Let } x-m=U \rightarrow x'=U'$

$$(U') = kU \rightarrow (D-k)U = 0 \quad U = x-m = ce^{kt} \rightarrow x = ce^{kt} + m$$

2) linear

3) separable (strongly not recommended!)

Mixture Problem: $\left\{ \begin{array}{l} \frac{dx}{dt} = \text{rate IN} - \text{rate OUT} = r_i c_i - r_o c_o, \quad x = x(t) = \text{amount}, \quad r = \left[\frac{\text{vol}}{\text{time}} \right] \\ x(t_0) = x_0 \\ c_o = \frac{x}{V} = \frac{x}{V_0 + (r_i - r_o)t} \mapsto \therefore V = V_0 + (r_i - r_o)t \end{array} \right.$

– linear, n^{th} order o.d.e.: $a_0(t) \frac{d^n x}{dt^n} + a_1(t) \frac{d^{n-1} x}{dt^{n-1}} + \dots + a_{n-1}(t) \frac{dx}{dt} + a_n(t)x = E(t)$

– if $a_0, a_1, \dots, a_n \in \mathbb{R}$ constants, then is special case: $L = P(D), P(D)x = E(t)$

– homogeneous differential equation if $E(t) = 0$

– differential operator "L": $Lx = E(t), L = a_0 D^n + a_1 D^{n-1} + \dots + a_{n-1} D + a_n, D = \frac{d}{dt}, \dots$

– linear combination, Wronskian, fundamental set $P(D) \rightarrow P(r)$ (characteristic polynomial)

– $L = P(D)$ if $a_0, a_1, \dots, a_n$ in L are constant coefficients

– linear independence: $c_1 = c_2 = \dots = c_n = 0$ (trivial solution) or $W(h_1, h_2, \dots, h_n)(t_0) \neq 0 \forall t_0 \in \mathbb{Z}$
 $\mapsto$ if $W = 0$, may or may not be independent!!

– General solution: $P(D)x = E(t), E(t) = 0$

1. n distinct roots $r_1, r_2, \dots, r_n: h_1(t) = e^{r_1 t}, h_2(t) = e^{r_2 t}, \dots$

2. root α with multiplicity $k: h_1(t) = e^{\alpha t^0}, h_2(t) = e^{\alpha t^1}, \dots, h_k(t) = e^{\alpha t^k}$

3. complex conjugate roots $\alpha \pm i\beta: h_1(t) = e^{\alpha t} \cos \beta t, h_2(t) = e^{\alpha t} \sin \beta t$

– Exponential shift: $P(D)e^{\alpha t} x(t) = e^{\alpha t} P(D + \alpha)x(t)$

Euler's identity: $e^{\pm i\theta} = \cos \theta \pm i \sin \theta, \theta \in \mathbb{R}$

Steps

	#	UC function	UC set	1. $x_h(t) \rightarrow H = \{\dots\}$
	1.	$e^{\alpha t}, \alpha \neq 0$	$\{e^{\alpha t}\}$	2. $S_1, S_2, S_3, \dots$ – revise
– Particular solution:	2.	$\sin \beta t, \cos \beta t, \beta \neq 0$	$\{\sin \beta t, \cos \beta t\}$	3. $x_p = \text{l.c. of } S\text{'s using } k\text{'s}$
	3.	poly. deg n	$\{1, t, t^2, \dots, t^n\}$	4. solve $x_p, x_p', \dots$ sub into orig DE solve $k\text{'s as const coeff.}$
				5. $x(t) = x_h(t) + x_p(t)$

(– see Cauchy – Euler's DE of 2^{nd} order next page)

– Method of Variation of Parameters: 2^{nd} order DE $a_0 x'' + a_1 x' + a_2 x = E(t)$

use when h_1, h_2 are known, $E(t)$ not UC function (formulae on next page)

method of variation of parameters cont'd :

$$x(t) = c_1(t)h_1(t) + c_2(t)h_2(t); \quad c'_1(t) = \frac{\begin{vmatrix} 0 & h_2 \\ E(t) & h'_2 \end{vmatrix}}{W(h_1, h_2)}, \quad c'_2(t) = \frac{\begin{vmatrix} h_1 & 0 \\ h'_1 & E(t) \end{vmatrix}}{W(h_1, h_2)}$$

– Cauchy – Euler's DE of 2nd order : $a_0 t^2 \frac{d^2 x}{dt^2} + a_1 t \frac{dx}{dt} + a_2 x = 0, t > 0 \cup t < 0 \Leftrightarrow t \neq 0$

$\mapsto$ power of t matches derivative $\mapsto$ may have to * t to achieve form of CEDE

Use $x(t) = t^\alpha \rightarrow$ get indecial equation (quadratic)

General solution :

1. α_1, α_2 real and distinct : $x(t) = c_1 t^{\alpha_1} + c_2 t^{\alpha_2}, c_1, c_2 \in \mathbb{R}$

2. α_1, α_2 real equal roots : $h_1(t) = t^\alpha, h_2(t) = t^\alpha \ln t, t \in (0, \infty), c_1, c_2 \in \mathbb{R}$

3. $\alpha_{1,2} = \alpha \pm i\beta$: $x(t) = c_1 t^\alpha \cos(\beta \ln t) + c_2 t^\alpha \sin(\beta \ln t)$

– $D\bar{x} = A\bar{x} + \bar{E}(t)$

– Eigenvalues, Eigenvectors $\det(A - \lambda I) = 0, (A - \lambda I)\bar{v} = \bar{0} \rightarrow$ non – trivial

$\rightarrow$ if pick more than one, use $s, t \dots!$ $\rightarrow$ solve $\bar{v}$ using cross product of 2 rows (for $m=1$ only)

– General solution : $D\bar{x} = A\bar{x}, A \in \text{const } \mathbb{R}$

1. $\lambda \ni m=1$: $\vec{h}(t) = e^{\lambda t} \bar{v}$

2. conjugate pair $\lambda = \alpha \pm i\beta$: $\bar{h}_1(t) = \text{Re}(e^{\lambda t} \bar{v}), \bar{h}_2(t) = \text{Im}(e^{\lambda t} \bar{v})$

$\mapsto$ use / pick one of eigenvalue and corresponding eigenvector

$\mapsto$ apply Euler's identity

3a) $\lambda \ni m > 1$ but with different $\bar{v}$'s : $\bar{h}_i(t) = e^{\lambda t} \bar{v}_i, i = 1, 2, \dots, m \mapsto$ no * t !!

b) $\lambda \ni m=2 \cap$ one $\bar{v} = \bar{\alpha}$: $\bar{h}_1(t) = e^{\lambda t} \bar{\alpha}, \bar{h}_2(t) = e^{\lambda t} (t\bar{\alpha} + \bar{\beta}), (A - \lambda I)\bar{\beta} = \bar{\alpha}$

– Non – homogeneous system $D\bar{x} = A\bar{x} + \bar{E}(t)$: Method of variation of parameters

$$\bar{x}(t) = \bar{x}_h(t) + \bar{x}_p(t), B = \begin{bmatrix} \bar{h}_1 & \bar{h}_2 & \dots & \bar{h}_n \end{bmatrix}, \bar{C}'(t) = B^{-1} \bar{E}(t), \quad K = \begin{bmatrix} a & b \\ c & d \end{bmatrix}, K^{-1} = \frac{1}{\det K} \begin{bmatrix} d & -b \\ -c & a \end{bmatrix}$$

– $\mathcal{L}\{f(t)\} = \int_0^\infty e^{-st} f(t) dt$

– PFD by inspection : $\frac{1}{(s+\alpha)(s+\beta)} = \frac{1}{\beta-\alpha} \left(\frac{1}{s+\alpha} - \frac{1}{s+\beta} \right)$

– see $\mathcal{L}$ formula sheet

– 2 – piece function $f(t)$: $f(t) = \text{first piece} + (2^{\text{nd}} \text{ piece} - 1^{\text{st}} \text{ piece}) \cdot \text{switch}$

– Sequences

Test for monotonic sequence :

1. Difference Test : $a_{n+1} - a_n \geq 0, \forall n \geq n_0, \{a_n\}$ is increasing

2. Quotient Test : $\frac{a_{n+1}}{a_n} \geq 1, n \geq n_0, \{a_n\}$ is increasing $\mapsto \frac{a_{n+1}}{a_n} \leq 1 \Rightarrow$ decreasing $\mapsto$ use with factorial

3. Derivative Test : $f'(x) \geq 0, \{a_n\}$ increasing $\mapsto f'(x) \leq 0 \Rightarrow$ decreasing

– Infinite series $\mapsto$ must write determined by which method! (by $\dots$ test)

1. Divergence Test (n^{th} term test) : Failpoint : $\lim_{n \rightarrow \infty} a_n = 0$

2. Ratio Test : Failpoint : $\lim_{n \rightarrow \infty} \frac{a_{n+1}}{a_n} = 1 \mapsto$ use for factorial

3. Root Test : Failpoint : $\lim_{n \rightarrow \infty} \sqrt[n]{a_n} = 1$

4. Integral Test : Conditions : $f(x) > 0 \cap f(x)$ continuous $\cap$ decreasing

5. Comparison Test :

6. Limit Comparison Test : $\left. \begin{array}{l} \end{array} \right\}$ usually use for geometric or p -series

7. Leibnitz Test : Conditions : $\lim_{n \rightarrow \infty} a_n = 0 \cap$ decreasing

$$\lim_{n \rightarrow \infty} \left(1 + \frac{\alpha}{n}\right)^n = e^\alpha$$

$$\lim_{n \rightarrow \infty} \sqrt[n]{n^p} = 1, p \in \mathbb{R}$$

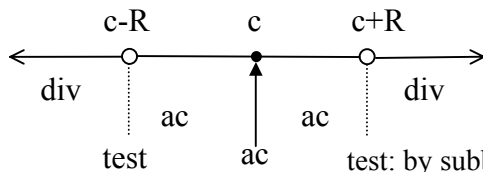
$$\sum_{n=1}^{\infty} \frac{1}{n^p} \begin{cases} \text{converges if } p > 1 \\ \text{diverges if } p \leq 1 \end{cases}$$

– Absolute / conditional convergence

$$\sum_{n=1}^{\infty} a_n \rightarrow \text{series of arbitrary terms} \begin{cases} \text{if } \sum_{n=1}^{\infty} |a_n| \text{ converges} \Rightarrow \text{absolutely convergent} \\ \text{if } \sum_{n=1}^{\infty} |a_n| \text{ diverges whereas } \sum_{n=1}^{\infty} a_n \text{ converges} \Rightarrow \text{conditionally conv.} \end{cases}$$

– Power series : $\sum_{n=0}^{\infty} a_n (t-c)^n$

$$L = \lim_{n \rightarrow \infty} \left| \frac{a_{n+1}}{a_n} \right|, R = \frac{1}{L}$$



– Power series solution to a DE at an ordinary point : $x(t) = \sum_{n=0}^{\infty} a_n (t-c)^n, a_0 \neq 0$

Steps : 1. $c = 0$ (unless otherwise stated), told to solve up to what power.

2. Expand power series up to that power.

3. $x = \dots, x' = \dots, x'' = \dots, \dots$, apply IVP (if any)

4. Sub step 3 into original DE. Solve $a_0, a_1, \dots$

5. Write $x = a_0 + a_1 t + a_2 t^2 + \dots = \dots$

– Taylor's series (a special power series) : if $f(x)$ is infinitely differentiable at some $t = c$, then the Taylor's series of f centred at " c " is the power series

$$f(x) = \sum_{n=0}^{\infty} a_n (t-c)^n, a_n = \frac{f^{(n)}(c)}{n!} \quad n = 0, 1, 2, \dots$$