

## Description

- Extracting features from an object for recognition
- ❶ Boundary Descriptors
- ❷ Regional Descriptors

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## ❶ Boundary Descriptors

- Chain Codes
- Signatures
- Polygonal approximations
- Shape Numbers
- Fourier Descriptors

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## Chain codes

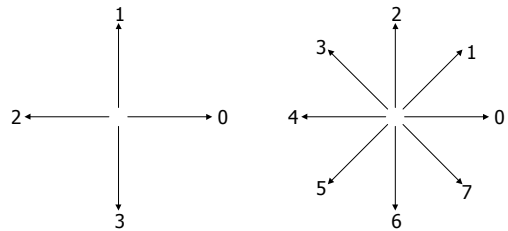
- Represents a boundary as a set of straight line segments of specified length and direction
- Usually a rectangular grid using 4- or 8-connectivity
- Length established by grid resolution
- Direction by code

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## 4-directional code 8-directional code



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## Why grid?

- If coded by pixel
- resulting chain code is too long
- small noises change code, unrelated to boundary

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## Grid procedure:

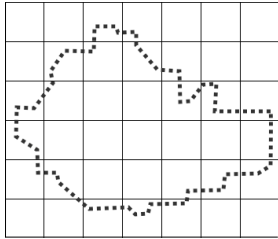
- Select a grid spacing
- As the boundary is traversed, a boundary point is assigned to each node of the large grid, depending on the proximity of the original boundary to that node
- Code the path using the direction code

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## Digital Boundary with resampling grid superimposed

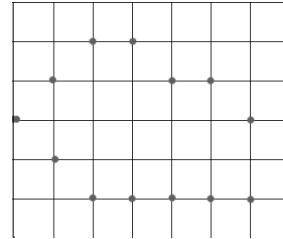


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## Result of resampling

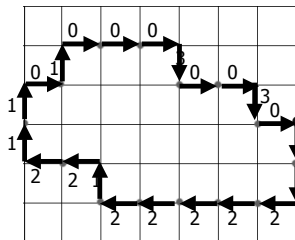


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## 4-directional chain code



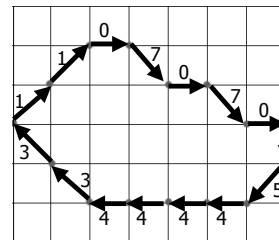
33222221221101  
00030030

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## 8-directional chain code



654444331107070

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## Crack code?

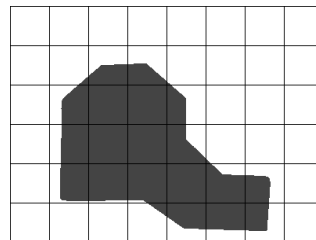
- Taking directions along boundary, considered as a **crack code** in some references, since crack between object and background is used
- Chain code treated as along pixels by them
- A contour pixel is an object pixel that has a background (non-object) pixel as one or more of its 4-connected neighbors

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## Freeman's chain code

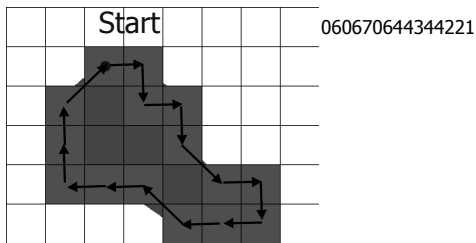


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## Freeman's chain code



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## How to make the code for a contour **unique**?

- Treat it as a circular sequence of direction numbers and redefine the starting point so that the resulting sequence forms an integer of minimum magnitude
- 3322222122110100030030
- becomes
- 0003003033222221221101

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## Run code

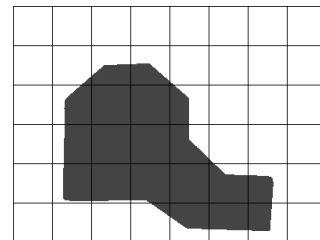
- based on coding the consecutive pixels along a row
- give the starting position of the run and the ending position of the run
- Various alternatives possible for coding

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## Run code illustration

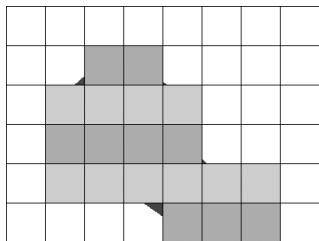


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## Run code illustration



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## Signatures

- A one dimensional representation of a boundary
- Distance vs Angle
- Tangent, Reference line angle vs boundary position
- Slope density function

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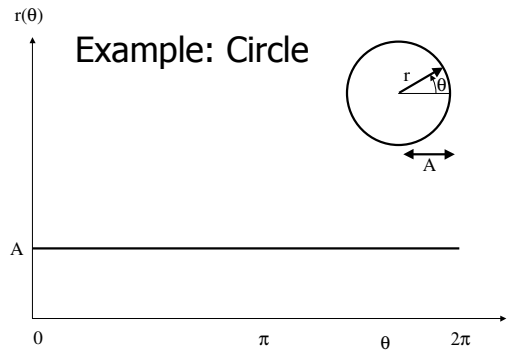
## Distance vs Angle

- Plot the distance from the centroid to the boundary as a function of angle
- To make it independent of size, normalize the  $r(\theta)$  curve to, say, unit maximum value

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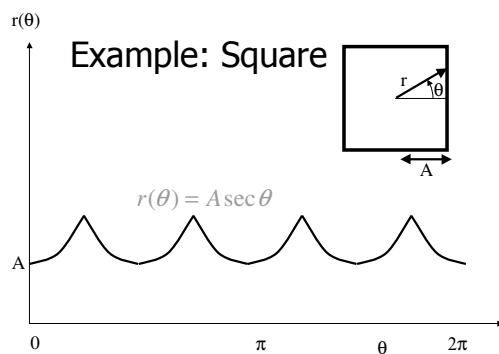
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## How to differentiate signatures?

- Easier, since signatures are one dimensional
- Compute its moments

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## Polygonal Approximations

- A boundary approximated by polygon
- Arbitrary accuracy possible, but
- Aim: Capture the essence of the shape with fewest possible segments
- Nontrivial, time consuming

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## Polygonal Approximations...

- Minimum Perimeter Polygons
- Merging techniques
- Splitting

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## Minimum Perimeter polygons

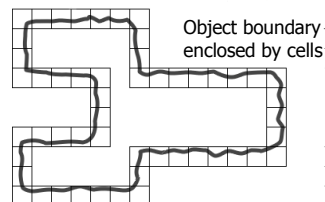
- Enclose a boundary by a set of concatenated cells
- Imagine the boundary as a rubberband contained within the walls
- Allow the rubberband to shrink, producing a polygon of minimum perimeter

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## Example

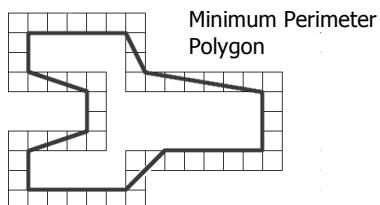


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## Example



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## Merging

- Merge points along a boundary until the error exceeds a preset threshold

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## Splitting

- Subdivide a segment until a given criteria is satisfied
- Example criteria: Maximum perpendicular distance from a boundary segment to the line joining its two endpoints not exceed a preset threshold

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## Shape Numbers

- First difference of smallest magnitude
- Count the number of directions (counterclockwise) that separate two adjacent elements of the code
- The first element of the difference is computed by using the transition between the last and first components of the chain

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## Example

- First difference of the 4-directional chain code 10103322 is
- 3133030

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## Fourier descriptors

- Uses the discrete one dimensional Fourier transform to describe a two-dimensional boundary

$$F(u) = \frac{1}{N} \sum_{x=0}^{N-1} f(x) e^{-j2\pi ux/N}$$

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## Regional Descriptors

- Simple Descriptors
- Texture
- Skeleton of a region
- Moment Invariants

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## Simple Descriptors

- Area
- Eccentricity
- Perimeter
- Compactness
- Euler number

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## Texture

- Provides quantitative measures of properties such as smoothness, coarseness, and regularity
- ❶ Statistical
  - Yields characterizations: Smooth, coarse, etc
- ❷ Structural
  - Deals with arrangement of primitives: Regularly spaced lines, etc

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## Statistical

- Moments of the intensity histogram
- Let  $z$  denote discrete image intensity
- $p(z_i), i=1,2,\dots,L$  be the corresponding histogram, where  $L$  is the number of levels

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## Moments

- The nth moment of  $z$  about the mean is defined as

$$\mu_n(z) = \sum_{i=1}^L (z_i - m_i)^n p(z_i)$$

- where  $m$  is the mean value of  $z$

$$m = \sum_{i=1}^L z_i p(z_i)$$

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## Moments...

- $\mu_0 = 1$
- $\mu_1 = 0$
- $\mu_2 =$  variance, denoted by  $\sigma^2(z)$
- $\mu_3$  is a measure of skewness
- $\mu_4$  is a measure of its relative flatness
- $\mu_5, \mu_6$  provide further quantitative discrimination of texture content

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4 9 2  
3 5 7  
8 1 6

4 3 2  
3 4 3  
2 1 3

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## A relative smoothness

$$R = 1 - \frac{1}{1 + \sigma^2(z)}$$

- For areas of constant intensity,  $R=0$
- For large values of  $\sigma^2$ ,  $R$  approaches 1

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## Skeleton of a region

- Reduces a region to a graph
- By thinning, or skeletonizing

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## Medial Axis Transformation

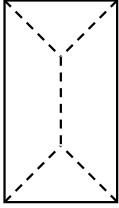
- The MAT of a region with border  $B$
- For each point  $p$  in  $R$ , we find its closest neighbour  $B$ .
- If  $p$  has more than one such neighbour, then it is said to belong to the medial axis of  $R$
- Closest can use different distances

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## Medial axes



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## Methods

- Direct implementation of above is computationally prohibitive
- Several algorithms proposed

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