

Z Transform

Rational Z-Transform

The inverse of the z-transform

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Rational Z-Transform

Poles and Zeros

The *poles* of a z-transform are the values of z for which if $X(z)=\infty$
The *zeros* of a z-transform are the values of z for which if $X(z)=0$

$X(z)$ is in rational function form

$$X(z) = \frac{N(z)}{D(z)} = \frac{b_0 + b_1 z^{-1} + \dots + b_M z^{-M}}{a_0 + a_1 z^{-1} + \dots + a_N z^{-N}} = \frac{\sum_{k=0}^M b_k z^{-k}}{\sum_{k=0}^N a_k z^{-k}}$$

$$X(z) = \frac{N(z)}{D(z)} = \frac{b_0}{a_0} z^{-M+N} \frac{(z-z_1)(z-z_2)\dots(z-z_M)}{(z-p_1)(z-p_2)\dots(z-p_N)}$$

$$X(z) = \frac{N(z)}{D(z)} = G z^{N-M} \frac{\prod_{k=1}^M (z-z_k)}{\prod_{k=1}^N (z-p_k)}$$

M finite zeros at

$$z = z_1, z_2, \dots, z_M$$

N finite poles at

$$z = p_1, p_2, \dots, p_N$$

And $|N-M|$ zeros if $N>M$ or poles if $M>N$ at the origin $z=0$

Rational Z-Transform

Poles and Zeros

We can represent $X(z)$ graphically by a pole-zero plot in complex plane.

Shows the location of poles by (x)

Shows the location of zeros by (o).

Definition of ROC of a z-transform should not contain any poles.

Example:

Determine the pole-zero plot for the signal

$$x(n) = a^n u(n)$$

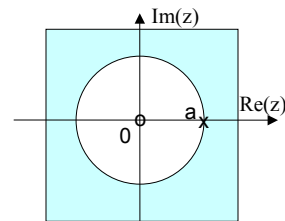
The z-transform is

$$X(z) = \frac{1}{1 - az^{-1}} = \frac{z}{z - a}$$

One zero at $z_1 = 0$

One pole at $p_1 = a$.

$p_1 = a$ is not included in the ROC



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Rational Z-Transform

Example.2:

Determine the pole-zero plot for the signal

$$x(n) = \begin{cases} a^n & 0 \leq n \leq 7 \\ 0 & \text{elsewhere} \end{cases}$$

$$a > 0$$

The z-transform is

$$X(z) = \sum_{n=0}^7 (az^{-1})^n = \frac{1 - (az^{-1})^8}{1 - az^{-1}} = \frac{z^8 - a^8}{z^7(z - a)}$$

$$X(z) = \frac{(z - z_1)(z - z_2) \dots (z - z_7)}{z^7}$$

The zeros

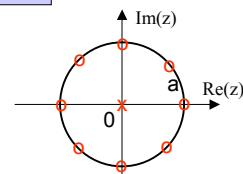
$$z_k = ae^{j2\pi k/M}$$

$$z_1 = ae^{j2\pi/8} \quad z_2 = ae^{j4\pi/8}$$

$$z_7 = ae^{j14\pi/8}$$

the poles at $p=0$

ROC: the entire z-plane except $z=0$



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Rational Z-Transform

Pole Location and Time-Domain behavior for Causal Signals

For the signal

$$x(n) = a^n u(n) \quad a > 0$$

The z-transform is

$$X(z) = \frac{1}{1 - az^{-1}} = \frac{z}{z - a}$$

One zero at $z_1=0$. One pole at $p_1=a$.

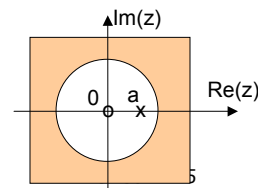
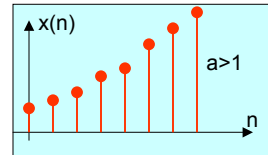
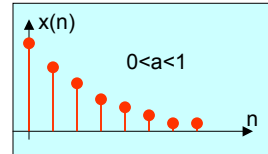
The signal is decaying $0 < a < 1$

The signal is fixed if $a=1$

The signal is growing if $a > 1$

The signal alternates if a is negative

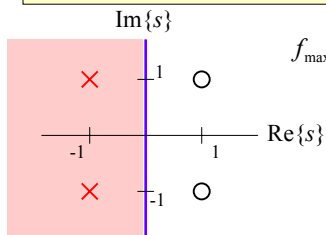
Causal signals with poles outside the unit circle become unbounded.



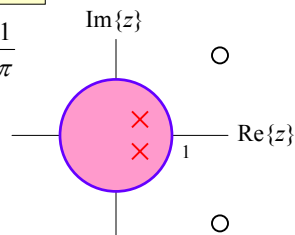
Rational Z-Transform

Pole Location and Time-Domain behavior for Causal Signals

Impulse invariance mapping is $z = e^{sT}$



$$f_{\max} = \frac{1}{2\pi} \Rightarrow f_s > \frac{1}{\pi}$$



$$s = -1 \pm j \Rightarrow z = 0.198 \pm j 0.31 \quad (T = 1 \text{ s})$$

$$s = 1 \pm j \Rightarrow z = 1.469 \pm j 2.287 \quad (T = 1 \text{ s})$$

$$s = j 2 \pi f$$

Laplace Domain	Z Domain
Left-hand plane	Inside unit circle
Imaginary axis	Unit circle
Right-hand plane	Outside unit circle

Rational Z-Transform

The system Function of a Linear Time –Invariant System

The input sequence $x(n]$

The output sequence $y(n]$

The relationship in the z-domain

$$Y(z) = H(z)X(z)$$

$H(z)$ is obtained

$$H(z) = \frac{Y(z)}{X(z)}$$

is called *system function*

$$H(z) = \sum_{n=-\infty}^{\infty} h(n)z^{-n}$$

We can take the inverse of z-transform to find $h(n)$.

$H(z)$ can be obtained from a linear constant-coefficient difference equation.

$$y(n) = -\sum_{k=1}^N a_k y(n-k) + \sum_{k=0}^N b_k x(n-k)$$

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Rational Z-Transform

$H(z)$ can be obtained from a linear constant-coefficient difference equation.

$$y(n) = -\sum_{k=1}^N a_k y(n-k) + \sum_{k=0}^N b_k x(n-k)$$

The z-transform

$$Y(z) = -\sum_{k=1}^N a_k Y(z)z^{-k} + \sum_{k=0}^N b_k X(z)z^{-k}$$

$$Y(z) \left(1 + \sum_{k=1}^N a_k z^{-k} \right) = \sum_{k=0}^N b_k X(z)z^{-k}$$

$$H(z) = \frac{Y(z)}{X(z)} = \frac{\sum_{k=0}^N b_k z^{-k}}{\left(1 + \sum_{k=1}^N a_k z^{-k} \right)}$$

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Rational Z-Transform

Example:

$$y(n) = \frac{1}{2}y(n-1) + 2x(n)$$

The z-transform from the difference equation

$$Y(z) = \frac{1}{2}Y(z)z^{-1} + 2X(z)$$

The system function

$$H(z) = \frac{Y(z)}{X(z)} = \frac{2}{1 - \frac{1}{2}z^{-1}}$$

The system has one pole at and one zero at
The inverse z-transform

$$h(n) = 2\left(\frac{1}{2}\right)^n u(n)$$

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The inverse of the z-transform

The inverse z-transform is formally given by

$$x(n) = \frac{1}{2\pi j} \oint_C X(z) z^{n-1} dz$$

There are three methods for evaluation of inverse z-transform

1. Direct evaluation by Contour integration (using Cauchy residue theorem)
2. Expansion into a series of term in the variable and
3. Partial-fraction expansion and table lookup.

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The inverse of the z-transform

The Inverse z-transform by Power Series Expansion

$$X(z) = \sum_{n=-\infty}^{\infty} c_n z^{-n}$$

With given ROC:

Example: Using Power Series Expansion to determine the inverse z-transform of

$$X(z) = \frac{1}{1 - 1.5z^{-1} + 0.5z^{-2}}$$

a. ROC: $|z| > 1$

b. ROC: $|z| < 0.5$

```
>> y=[1];
>> h=[1 -1.5 0.5];
>> n=7;
>> y=[y zeros(1,n-1)];
//y={1,0,0,0,0,0,0}
>> [x,r]=deconv(y,h)
x = 1.0000 1.5000 1.7500 1.8750 1.9375 1.9688
r = 0 0 0
0 0 0
1.9844 -0.9844
```

$x(0) = 1, x(1) = 1.5, x(2) = 1.75, x(3) = 1.875, x(4) = 1.9375$ 307-11 11

The inverse of the z-transform

a. Since the ROC is the exterior of the circle, we can expect $x(n)$ to be a causal.

$$\begin{array}{r} 1 + \frac{3}{2}z^{-1} + \frac{7}{4}z^{-2} + \frac{15}{8}z^{-3} + \frac{31}{16}z^{-4} + \dots \\ 1 - \frac{3}{2}z^{-1} + \frac{1}{2}z^{-2} \overline{) 1} \\ \underline{1 - \frac{3}{2}z^{-1} + \frac{1}{2}z^{-2}} \\ \frac{3}{2}z^{-1} - \frac{1}{2}z^{-2} \\ \underline{\frac{3}{2}z^{-1} - \frac{9}{4}z^{-2} + \frac{3}{4}z^{-3}} \\ \frac{7}{4}z^{-2} - \frac{3}{4}z^{-3} \\ \underline{\frac{7}{4}z^{-2} - \frac{21}{8}z^{-3} + \frac{7}{8}z^{-4}} \\ \frac{15}{8}z^{-3} - \frac{7}{8}z^{-4} \\ \underline{\frac{15}{8}z^{-3} - \frac{45}{16}z^{-4} + \frac{15}{16}z^{-5}} \\ \frac{31}{16}z^{-4} - \frac{15}{16}z^{-5} \end{array}$$

Therefore .

$$X(z) = 1 + \frac{3}{2}z^{-1} + \frac{7}{4}z^{-2} + \frac{15}{8}z^{-3} + \frac{31}{16}z^{-4} + \dots$$

$x(n)$ can be obtained as

$$x(n) = \left\{ 1, \frac{3}{2}, \frac{7}{4}, \frac{15}{8}, \frac{31}{16}, \dots \right\}$$

↑

The inverse of the z-transform

b. ROC is the interior of a circle. The signal $x(n]$ is anticausal.
The long division in the following way.

$$\begin{array}{r}
 2z^2 + 6z^3 + 4z^4 + 30z^5 + \dots \\
 \frac{1}{2}z^{-2} - \frac{3}{2}z^{-1} + 1 \Big) 1 \\
 \underline{1 - 3z + 2z^2} \\
 3z - 2z^2 \\
 \underline{3z - 9z^2 + 6z^3} \\
 7z^2 - 6z^3 \\
 \underline{7z^2 - 21z^3 + 14z^4} \\
 15z^3 - 14z^4 \\
 \underline{15z^3 - 45z^4 + 30z^5} \\
 31z^4 - 30z^5
 \end{array}$$

Therefore,

$$X(z) = 2z^2 + 6z^3 + 14z^4 + 30z^5 + \dots$$

$x(n]$ can be obtained as

$$x(n) = \{\dots, 30, 14, 6, 2, 0, 0\}$$

↑

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The inverse of the z-transform

The inverse z-transform by Partial Fraction Expansion

We usually have $X(z)$ function in a rational function form

$$X(z) = \frac{N(z)}{D(z)} = \frac{b_0 + b_1z^{-1} + \dots + b_Mz^{-M}}{a_0 + a_1z^{-1} + \dots + a_Nz^{-N}}$$

A rational function is called proper if $M < N$.

A rational function is called improper if $M \geq N$.

An improper rational function ($M \geq N$) can be written as the sum of polynomial and a proper rational function.

$$X(z) = c_0 + c_1z^{-1} + \dots + c_{M-N}z^{-(M-N)} + \frac{N_1(z)}{D(z)}$$

Example:

$$X(z) = \frac{1 + 3z^{-1} + \frac{11}{6}z^{-2} + \frac{1}{3}z^{-3}}{1 + \frac{5}{6}z^{-1} + \frac{1}{6}z^{-2}}$$

$$X(z) = 1 + 2z^{-1} + \frac{\frac{1}{6}z^{-1}}{1 + \frac{5}{6}z^{-1} + \frac{1}{6}z^{-2}}$$

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The inverse of the z-transform

The inverse z-transform by Partial Fraction Expansion

Find the poles (denominator roots). We can have distinct real poles, distinct complex poles, multiple-order real poles, and multiple-order complex poles.

Distinct Poles: The poles are all different

$$X(z) = \frac{A_1}{1 - p_1 z^{-1}} + \frac{A_2}{1 - p_2 z^{-1}} + \dots + \frac{A_N}{1 - p_N z^{-1}}$$

We can determine coefficient using different methods. Let's give an example and use the of the methods

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The inverse of the z-transform

Example:

Determine the partial fraction expansion the following function

$$X(z) = \frac{1}{1 - 1.5z^{-1} + 0.5z^{-2}}$$

$$X(z) = \frac{1}{(1 - 1z^{-1})(1 - 0.5z^{-1})} = \frac{A_1}{1 - 1z^{-1}} + \frac{A_2}{1 - 0.5z^{-1}}$$

To find coefficients

$$A_1 = (1 - 1z^{-1})X(z) \Big|_{z^{-1}=1} = \frac{1}{(1 - 0.5z^{-1})} \Big|_{z^{-1}=1} = \frac{1}{1 - 0.5} = 2$$

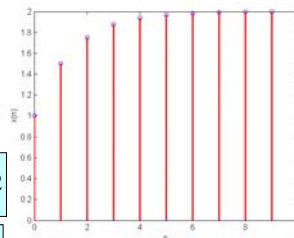
$$A_2 = (1 - 0.5z^{-1})X(z) \Big|_{z^{-1}=2} = \frac{1}{(1 - z^{-1})} \Big|_{z^{-1}=2} = \frac{1}{1 - 2} = -1$$

We have

$$X(z) = \frac{2}{1 - z^{-1}} - \frac{1}{1 - 0.5z^{-1}}$$

Assume that signal is causal
From the z-transform table

$$x(n) = [2 - (0.5)^n] u(n)$$



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The inverse of the z-transform

Using MatLab to find inverse z-transform

```
>> syms z n
>> iztrans(1/(1-1.5*z^-1+0.5*z^-2))
ans =
2-(1/2)^n
```

```
>> syms z n
>> ztrans(2-(1/2)^n)
ans =
2*z/(z-1)-2*z/(2*z-1)
```

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The inverse of the z-transform

Multiple – order poles:

If $X(z)$ has repeated poles. This time we use a different expansion.

Let's say $D(z)$ contains a repeated poles $(1 - pz^{-1})^r$. Then

$$X(z) = \frac{N(z)}{(1 - pz^{-1})^r D_1(z)}$$

$$= \frac{A_1}{(1 - pz^{-1})} + \frac{A_2 z^{-1}}{(1 - pz^{-1})^2} + \dots + \frac{A_{r-1} z^{-r+2}}{(1 - pz^{-1})^{r-1}} + \frac{A_r z^{-r+1}}{(1 - pz^{-1})^r} + \frac{N_1(z)}{D_1(z)}$$

To find A_1, A_2, \dots, A_r

$$A_1 = \frac{1}{(r-1)!} \frac{d^{r-1}}{dz^{r-1}} \left[\frac{z^{r-1} N(z)}{D_1(z)} \right] \bigg|_{z^{-1} = \frac{1}{p}}$$

$$A_2 = \frac{d}{dz} \left[\frac{z^{r-1} N(z)}{D_1(z)} \right] \bigg|_{z^{-1} = \frac{1}{p}}$$

$$A_r = \frac{z^{r-1} N(z)}{D_1(z)} \bigg|_{z^{-1} = \frac{1}{p}}$$

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The inverse of the z-transform

Example:

$$X(z) = \frac{1}{(1+z^{-1})(1-z^{-1})^2}$$

$$X(z) = \frac{1}{(1+z^{-1})(1-z^{-1})^2} = \frac{A_1}{(1+z^{-1})} + \frac{A_2}{(1-z^{-1})} + \frac{A_3 z^{-1}}{(1-z^{-1})^2}$$

Determine the coefficients. A_1 , A_2 , and A_3

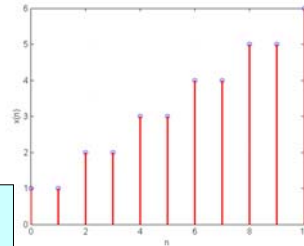
$$A_1 = (1+z^{-1})X(z) \Big|_{z^{-1}=-1} = \frac{1}{(1-z^{-1})^2} \Big|_{z^{-1}=-1} = \frac{1}{4}$$

$$A_3 = (1-z^{-1})^2 z X(z) \Big|_{z^{-1}=1} = \frac{z}{(1+z^{-1})} \Big|_{z^{-1}=1} = \frac{1}{2}$$

$$\begin{aligned} A_2 &= \frac{d}{dz} \left[(1-z^{-1})^2 z X(z) \right] \Big|_{z^{-1}=1} \\ &= \frac{d}{dz} \left[\frac{z}{(1+z^{-1})} \right] \Big|_{z^{-1}=1} = \frac{(1+z^{-1}) - z(-z^{-2})}{(1+z^{-1})^2} \Big|_{z^{-1}=1} = \frac{2+1}{2^2} = \frac{3}{4} \end{aligned}$$

$$X(z) = \frac{1}{4} \frac{1}{(1+z^{-1})} + \frac{3}{4} \frac{1}{(1-z^{-1})} + \frac{1}{2} \frac{z^{-1}}{(1-z^{-1})^2}$$

$$x(n) = \left[\frac{1}{4}(-1)^n + \frac{3}{4} + \frac{1}{2}n \right] u(n)$$



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The inverse of the z-transform

Distinct complex poles

Example

$$X(z) = \frac{1+z^{-1}}{1-z^{-1}+0.5z^{-2}}$$

Find inverse z-transform.

Partial Fraction

$$\begin{aligned} \frac{X(z)}{z} &= \frac{1+z^{-1}}{(1-p_1 z^{-1})(1-p_2 z^{-1})} = \frac{1+z^{-1}}{\left[1 - \left(\frac{1}{2} + j\frac{1}{2}\right)z^{-1}\right] \left[1 - \left(\frac{1}{2} - j\frac{1}{2}\right)z^{-1}\right]} \\ &= \frac{A_1}{\left[1 - \left(\frac{1}{2} + j\frac{1}{2}\right)z^{-1}\right]} + \frac{A_2}{\left[1 - \left(\frac{1}{2} - j\frac{1}{2}\right)z^{-1}\right]} \end{aligned}$$

Determine the coefficients.

$$A_1 = (1-p_1 z^{-1})X(z) \Big|_{z=p_1} = \frac{1+z^{-1}}{\left[1 - \left(\frac{1}{2} - j\frac{1}{2}\right)z^{-1}\right]} \Big|_{z^{-1}=\frac{1}{\frac{1}{2}+j\frac{1}{2}}} = \frac{1+\frac{1}{\frac{1}{2}+j\frac{1}{2}}}{1 - \left(\frac{1}{2} - j\frac{1}{2}\right)\frac{1}{\frac{1}{2}+j\frac{1}{2}}} = \frac{1}{2} - j\frac{3}{2}$$

The inverse of the z-transform

Example (cont)

$$A_2 = (1 - p_2 z^{-1})X(z) \Big|_{z=p_2} = \left[\frac{1 + z^{-1}}{1 - \left(\frac{1}{2} + j\frac{1}{2}\right)z^{-1}} \right] \Big|_{z^{-1} = \frac{1 - \frac{1}{2}}{\frac{1}{2} - j\frac{1}{2}}} = \frac{1 + \frac{1}{\frac{1}{2} - j\frac{1}{2}}}{1 - \left(\frac{1}{2} + j\frac{1}{2}\right)\frac{1}{\frac{1}{2} - j\frac{1}{2}}} = \frac{1}{2} + j\frac{3}{2}$$

$$X(z) = \frac{1 + z^{-1}}{1 - z^{-1} + 0.5z^{-2}} = \frac{\frac{1}{2} - j\frac{3}{2}}{1 - \left(\frac{1}{2} + j\frac{1}{2}\right)z^{-1}} + \frac{\frac{1}{2} + j\frac{3}{2}}{1 - \left(\frac{1}{2} - j\frac{1}{2}\right)z^{-1}}$$

$$A_1 = \frac{1}{2} - j\frac{3}{2} = \frac{\sqrt{10}}{2} e^{-j71.565}$$

$$A_2 = \frac{1}{2} + j\frac{3}{2} = \frac{\sqrt{10}}{2} e^{+j71.565}$$

$$A_1 = A_2^*$$

$$p_1 = \frac{1}{2} + j\frac{1}{2} = \frac{1}{\sqrt{2}} e^{+j\pi/4}$$

$$p_1 = p_2^*$$

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The inverse of the z-transform

Example (cont)

$$X(z) = \frac{1 + z^{-1}}{1 - z^{-1} + 0.5z^{-2}} = \frac{\frac{\sqrt{10}}{2} e^{-j71.565}}{1 - \frac{1}{\sqrt{2}} e^{j\pi/4} z^{-1}} + \frac{\frac{\sqrt{10}}{2} e^{j71.565}}{1 - \frac{1}{\sqrt{2}} e^{-j\pi/4} z^{-1}}$$

Inverse z-transform.

$$x(n) = \frac{\sqrt{10}}{2} e^{-j71.565} \left(\frac{1}{\sqrt{2}} e^{j\pi/4} \right)^n u(n) + \frac{\sqrt{10}}{2} e^{j71.565} \left(\frac{1}{\sqrt{2}} e^{-j\pi/4} \right)^n u(n)$$

$$x(n) = \sqrt{10} \left(\frac{1}{\sqrt{2}} \right)^n \left(\frac{1}{2} e^{j\left(\frac{\pi n}{4} - 71.565\right)} + \frac{1}{2} e^{-j\left(\frac{\pi n}{4} - 71.565\right)} \right) u(n)$$

$$x(n) = \sqrt{10} \left(\frac{1}{\sqrt{2}} \right)^n \cos\left(\frac{\pi n}{4} - 71.565\right) u(n)$$

```
>> n=0:20;
>> x=sqrt(10)*(1/sqrt(2)).^n.*cos(pi*n/4-0.397*pi);
>> stem(n,x)
```

