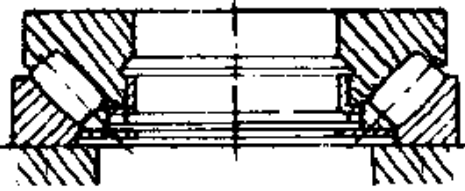
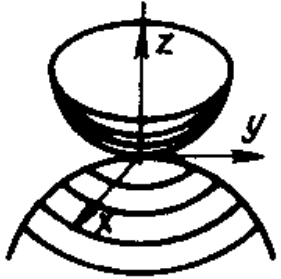
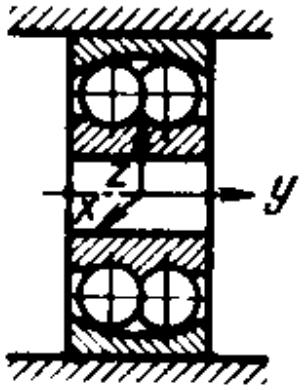
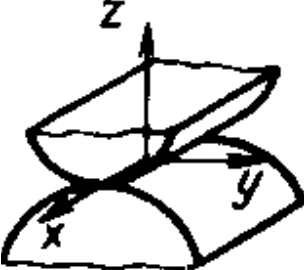
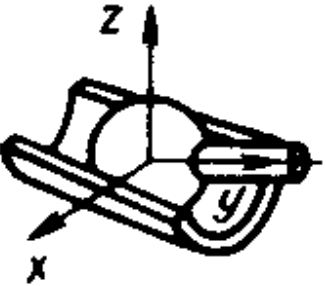
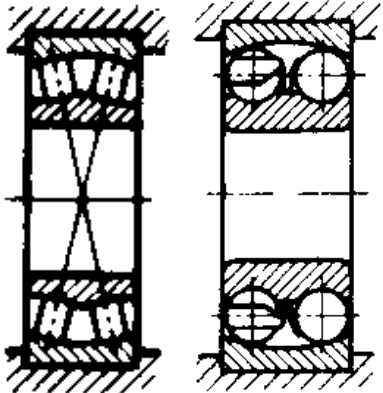
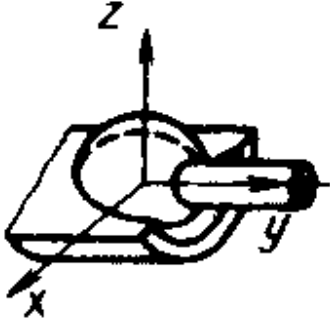
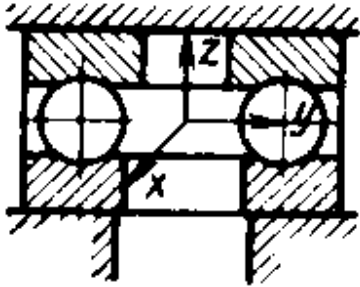
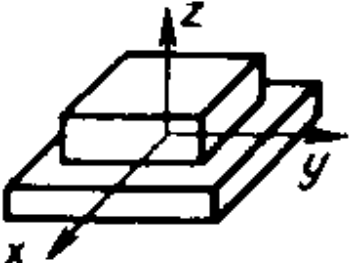
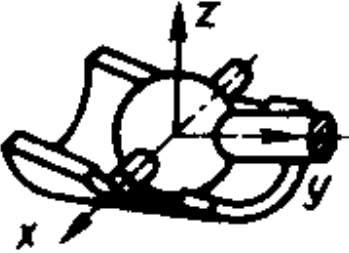
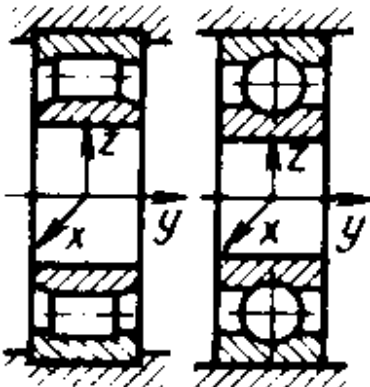
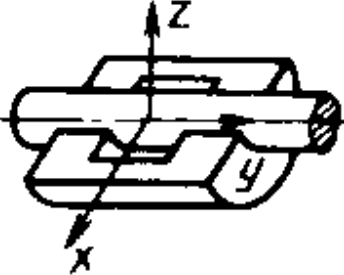
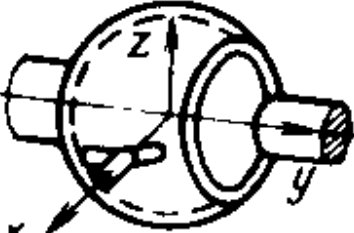
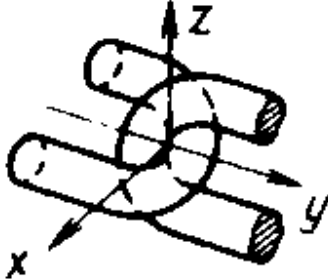
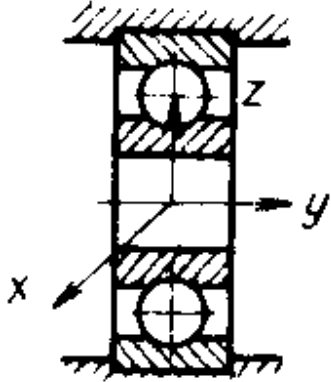
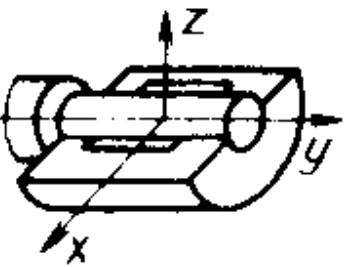
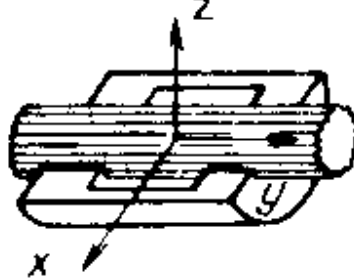
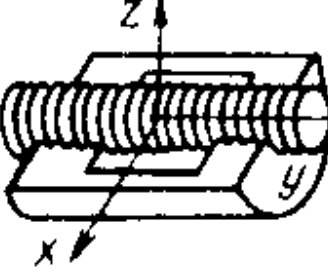


Clase	1	2	3	4	Mov.
I	<p style="text-align: center;">T_z T_x, T_y, R_x, R_y, R_z</p>  <p style="text-align: center;">Rodamiento de empuje con rodillos esféricos (29300-29400)</p>	<p style="text-align: center;">T_z T_x, T_y, R_x, R_y, R_z</p>  <p style="text-align: center;">Puntiforme</p>			5
II	<p style="text-align: center;">T_x, T_z T_y, R_x, R_y, R_z</p>  <p style="text-align: center;">Rodamiento auto- alineante de doble hilera (1200-1300, 2200-2300, 11200-11300)</p>	<p style="text-align: center;">T_z, R_y T_x, T_y, R_x, R_z</p>  <p style="text-align: center;">Lineal</p>	<p style="text-align: center;">T_x, T_z T_y, R_x, R_y, R_z</p>  <p style="text-align: center;">Anular</p>		4

III'	<p style="text-align: center;"> T_x, T_y, T_z R_x, R_y, R_z </p>  <p style="text-align: center;">Rodamiento auto-alineante de doble hilera (21300-22200, etc. y 1200-1300, etc.)</p>	<p style="text-align: center;"> T_x, T_y, T_z R_x, R_y, R_z </p>  <p style="text-align: center;">Esférico</p>			3
III''	<p style="text-align: center;"> T_z, R_x, R_y T_x, T_y, R_z </p>  <p style="text-align: center;">Rodamiento de empuje de bolas (51100-51200-51300)</p>	<p style="text-align: center;"> T_z, R_x, R_y T_x, T_y, R_z </p>  <p style="text-align: center;">Plano</p>	<p style="text-align: center;"> T_x, T_z, R_y T_y, R_x, R_z </p>  <p style="text-align: center;">Anular con espiga</p>		3

IV	<p style="text-align: center;">T_x, T_z, R_x, R_z T_y, R_y</p>  <p>Rodamientos cilíndricos NU/N... 200-300-... 2200-2300 y radiales 200-300-600 620-630, 6000, 6200, etc</p>	<p style="text-align: center;">T_x, T_z, R_x, R_z T_y, R_y</p>  <p>Cilíndrico</p>	<p style="text-align: center;">T_x, T_y, T_z, R_y R_x, R_z</p>  <p>Esférico con espiga</p>	<p style="text-align: center;">T_x, T_y, T_z, R_y R_x, R_z</p>  <p>De cadena</p>	2
V	<p style="text-align: center;">T_x, T_y, T_z, R_x, R_z R_y</p>  <p>Radiales 200-300-600 620-630, 6000, 6200, etc</p>	<p style="text-align: center;">T_x, T_y, T_z, R_x, R_z R_y</p>  <p>Giratorio</p>	<p style="text-align: center;">T_x, T_z, R_x, R_y, R_z T_y</p>  <p>De translación</p>	<p style="text-align: center;">T_x, T_z, R_x, R_z $[R_y = f(T_y)]$</p>  <p>Helicoidal</p>	1