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10035

Reg. No: \_\_\_\_\_

Name: \_\_\_\_\_

A P J ABDUL KALAM TECHNOLOGICAL UNIVERSITY

FIRST/SECOND SEMESTER EXAMINATION JULY 2016.  
BE I - ENGINEERING MECHANICS

Time : 3 Hours

Maximum Marks : 100

Part - A

Answer all the questions. Each question carries 5 Marks (8 X 5 = 40 Marks)

1. Explain the conditions of equilibrium of two force and three force members.
2. Calculate the reactions at A and B of the given loaded beam (Fig.1).

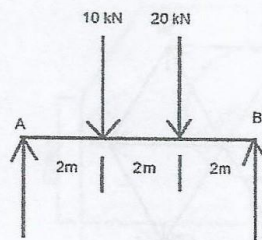


Fig.1

3. Locate the centroid of the 'T' section shown in Fig.2

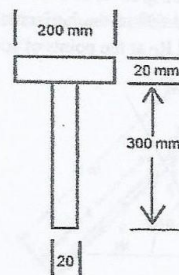


Fig.2

4. Define angle of friction, coefficient of friction and cone of friction.
5. State and explain D'Alembert's principle

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- 6. Explain the concepts of instantaneous centre with figure.
- 7. Explain the following terms with respect to a simple harmonic motion  
(a) amplitude (b) time period (c) frequency
- 8. How can we connect two springs in series? Draw a diagram. Stiffness of two springs are  $k_1$  and  $k_2$ . Then what will be the stiffness of the combined system in series? Arrive at the expression.

**Part - B**  
*Answer two questions from each SET*

**SET 1**

*Each question carries 10 Marks (2 X 10 = 20 Marks)*

- 9. Concurrent forces 1, 3, 5, 7, 9 and 11N are applied at the centre of regular hexagon acting towards its vertices as shown in Fig. 3. Determine the magnitude and direction of the resultant.

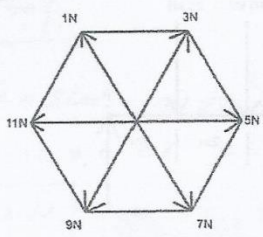


Fig.3

- 10. A ball of weight 120N rests in a right angled groove, as shown in Fig.4. The sides of the groove are inclined at an angle of  $30^\circ$  and  $60^\circ$  to the horizontal. If all the surfaces are smooth, then determine the reaction  $R_A$  and  $R_C$  at the points of contact.

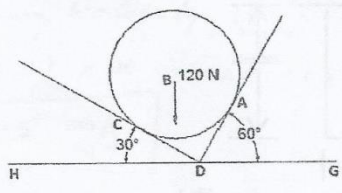


Fig.4

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11. A system of parallel forces is acting on a rigid bar as shown in Fig.5. Reduce this system to a) a single force b) a single force and a couple at A.

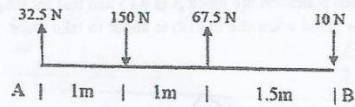


Fig.5

SET 2

Answer any 2 questions. Each question carries 10 Marks (2 X 10 = 20 Marks)

12. Find the centroid of the given Fig.6.

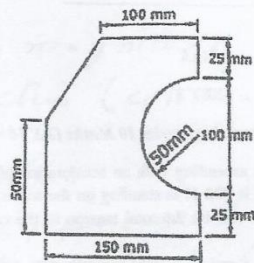


Fig.6

13. A uniform ladder of 4m length rests against a wall which it makes an angle  $45^\circ$  as shown in Fig.7. The coefficient of friction between the ladder and the wall is 0.4 and that between the ladder and floor is 0.5. If the man whose weight is on half of that of ladder ascends it, how high will he when the ladder slips?

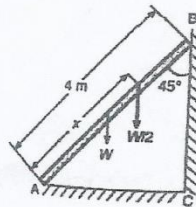


Fig.7

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14. Two blocks A and B of weights 500 N and 1000 N are placed on an inclined plane (Fig.8). The blocks are connected by a string to the parallel plane. The coefficient of friction between the inclined plane and the block A is 0.15 and that for the block B is 0.4. Find the inclination of the plane when the motion is about to take place. Also calculate the tension in the string.

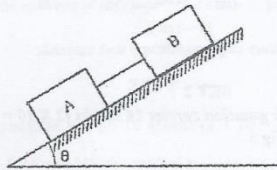


Fig.8

SET 3

Answer any 2 questions. Each question carries 10 Marks (2 X 10 = 20 Marks)

15. An elevator weighing 5000 N is ascending with an acceleration of  $3 \text{ m/s}^2$ . During this ascent its operator whose weight is 700 N is standing on the scales placed on the floor. What is the scale reading? What will be the total tension in the cables of the elevator during this motion?
16. A weight of 50N suspended from a spring vibrates vertically with amplitude of 8cm and a frequency of 1 oscillation per second. Find (a) the stiffness of the spring. (b) The maximum tension induced in the spring and (c) the maximum velocity of the weight
17. A weight of 100N suspended from a spring vibrates vertically with amplitude of 8cm and a frequency of 1 oscillation per second. Find
- The stiffness of the spring
  - The maximum tension induced in the spring
  - The maximum velocity of the weight

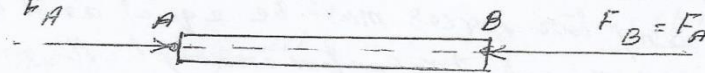
U.T.U. July 2016 B.E. 100 Engg. Mechanics  
part A.

1. Explain the conditions of equilibrium of two force and three force members

Ans: A body is said to be in equilibrium when all the forces exerted on the body are in balance

1)  $\sum F = 0$ ,  $\sum F_x = 0$ ,  $\sum F_y = 0$

$\sum F = 0, \sum M = 0$

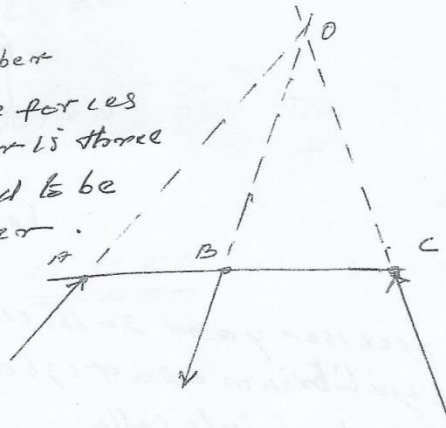


2) The sum of moments of all the forces acting on the body about any point is zero,  $\sum M = 0$

Two force member

Two forces: same magnitude, opposite direction  
Same line of action (collinear)

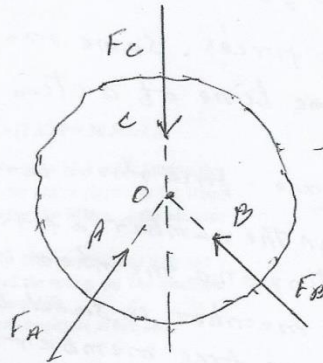
Three-force member  
when the number of forces acting on a member is three the member is said to be a three force member.



Three forces are concurrent

$\sum M_0 = 0$

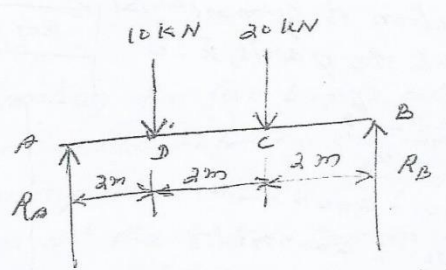
For a three force body to be in equilibrium all the three forces must be concurrent forces (Line of action of all the forces must meet at a single point). The magnitude of the forces  $F_A$ ,  $F_B$  and  $F_C$  should be such that  $\sum F$  should be zero. For this the resultant of any two forces must be equal and opposite to the third force. For example the magnitude of force  $F_C$  should be equal and opposite to the resultant of the other two forces  $F_A$  and  $F_B$ .



The necessary and sufficient conditions for the equilibrium of a rigid body can be expressed analytically

$$\sum F_x = 0, \sum F_y = 0 \text{ and } \sum M = 0$$

2) Calculate the reactions at A and B of the given loaded beam



Solution

Consider the free body diagram of beam as shown

$R_A = 13.33 \text{ kN}$ $R_B = 16.67 \text{ kN}$
--

∴ ∑ F<sub>v</sub> = 0

$$R_A - 10 - 20 + R_B = 0$$

$$R_A + R_B = 30 \quad \text{---(1)}$$

∴ ∑ M = 0, taking moment about A

$$10 \times 2 + 20 \times 4 - R_B \times 6 = 0$$

$$20 + 80 - 6R_B = 0$$

$$\therefore R_B = \frac{100}{6} = 16.67 \text{ kN}$$

$$R_A + R_B = 30$$

$$R_A + 16.67 = 30$$

$$R_A = 30 - 16.67 = \underline{\underline{13.33 \text{ kN}}}$$

3) Locate the centroid of the T section shown with  
 since the section is symmetrical with respect to the y axis,  $\bar{x} = 0$

$$\bar{y} = \frac{a_1 y_1 + a_2 y_2}{a_1 + a_2}$$

$$a_1 = 300 \times 20 = 6000 \text{ mm}^2$$

$$a_2 = 200 \times 20 = 4000 \text{ mm}^2$$

$$y_1 = \frac{300}{2} = 150 \text{ mm}$$

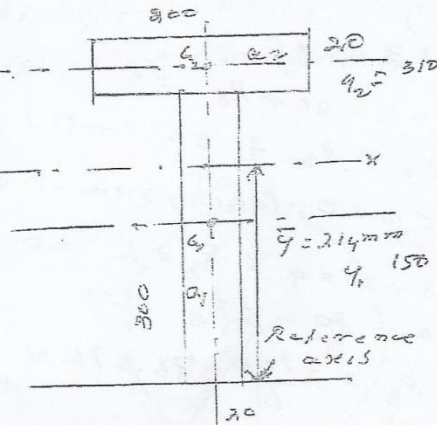
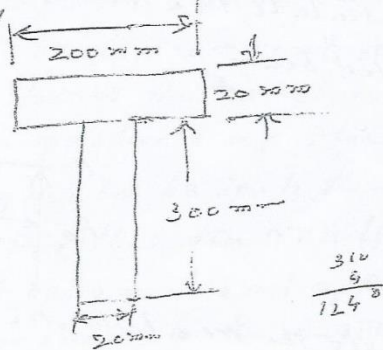
$$y_2 = 300 + \frac{20}{2} = 310 \text{ mm}$$

$$\therefore \bar{y} = \frac{6000 \times 150 + 4000 \times 310}{6000 + 4000}$$

$$= \frac{900 + 1240}{10}$$

$$= 90 + 124 = 214 \text{ mm}$$

$$\bar{y} = 214 \text{ mm}$$





4) Define angle of friction, coefficient of friction and cone of friction

✓ Coefficient of friction :-

The magnitude of limiting friction bears a constant ratio to the normal reaction between the two surfaces i.e. the limiting friction is proportional to the normal reaction at the contact surface.

This constant of proportionality is called coefficient of friction

Limiting friction,  $F$  is proportional to the normal reaction  $R_N$

$$F \propto R_N$$

$$F = \mu R_N$$

$\mu = \frac{F}{R_N}$ ,  $\mu$  is the coefficient of friction at the contact surface

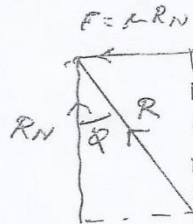
Angle of friction

It is the angle between the normal reaction at the contact surface and the resultant of normal reaction and limiting friction

It is denoted by  $\phi$

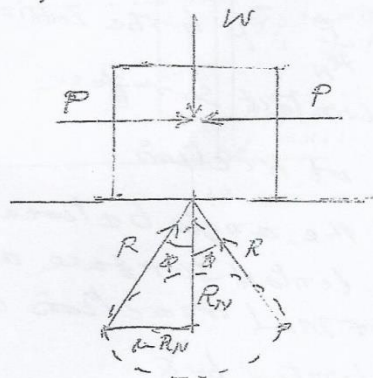
$$\tan \phi = \frac{F}{R_N} = \frac{\mu R_N}{R_N} = \mu$$

✓ Angle of friction  $\phi = \tan^{-1} \mu$



✓ Cone of friction

when the direction of external force is gradually changed the direction of resultant changes but the angle between the normal reaction and the resultant force will be the same. Thus <sup>when</sup> the direction of external force is gradually changed through  $360^\circ$ , the resultant  $R$  generates a right circular cone with semi cone angle equal to  $\phi$ . This cone is called friction cone or cone of friction. The axis of this cone will be the normal reaction and the generators are the resultant force and base radius equal to the limiting frictional force.



5. state and explain D'Alembert principle 7

- Application of Newton's second law of motion  
- A problem in dynamics can be converted into a static equilibrium problem using D'Alembert's principle

ie  $F = ma$  can be written as  $F - ma = 0$   
The term  $(-ma)$  is called inertial force

$$\therefore \boxed{F + (-ma) = 0}$$

The statement of the above equation is known as D'Alembert's principle which states that the resultant of a system of force acting on a body in motion is in dynamic equilibrium with inertial force

Every body has a tendency to continue its state of rest or of uniform motion. This tendency is called inertia

c) Explain the concepts of instantaneous centre with figure.

Concept of instantaneous centre

The motion of rotation and translation of a body, at a given instant, can be considered as that of pure rotation of the body about a point. This point about which the body can be assumed to be rotating at the given instant is called instantaneous centre of rotation. Since the velocity of this point at the given instant is zero, this point is called instantaneous centre of zero velocity.

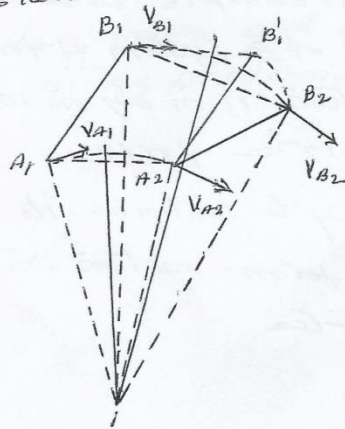


Fig- This point is not a fixed point, and when the body changes its position, the position of the instantaneous centre also changes. The locus of the instantaneous centre as the body goes on changing its position is called centroid.

properties of instantaneous centre are

- i. The magnitude of velocity of any point on a body is proportional to its distance from the instantaneous centre and is equal to the angular velocity times the distance.
- ii. The direction of velocity of any point on a body is perpendicular to the line joining that point and the instantaneous centre.

The above properties are used to locate the instantaneous centre of a body.

7. Explain the following terms with respect to a simple harmonic motion -  
 a. amplitude b. time period c. frequency.

Ans:

a. Amplitude: It is the distance between extreme and mean position of the particle executing SHM. It is the maximum displacement of the particle from the mean position.

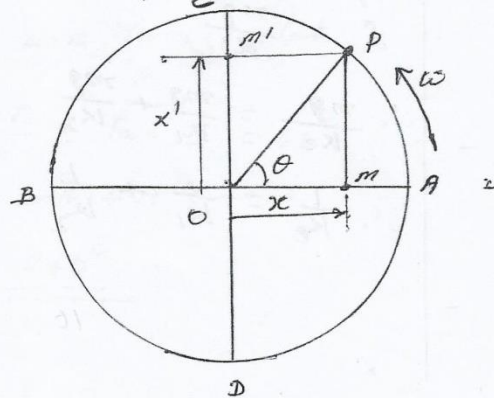
b. Time period: It is the time for one oscillation. It is denoted by  $t_p$ .

From figure

$$\theta = \omega t$$

For one oscillation:

$$t = t_p \text{ and } \theta = 2\pi$$



$$2\pi = \omega t_p$$

$$t_p = \frac{2\pi}{\omega}$$

### C. Frequency

The number of cycles per unit time is called frequency

If  $t_p$  is the time period in seconds and  $f$  is the frequency in Hz, then  $f = \frac{1}{t_p}$

Ans: In a spring mass model the springs can be attached to the mass in series

Two springs of stiffness  $k_1$  and  $k_2$  arranged in series. Let  $\delta_1$  and  $\delta_2$  be the elongation of each spring due to body of mass  $m$

static deflection of mass,  $\delta = \delta_1 + \delta_2$ . Let  $\delta_e$  be the static deflection of the same mass when it is attached to the single spring of stiffness  $k_e$ . For this single spring to be equivalent to the two springs in series, the req<sup>d</sup> condition is

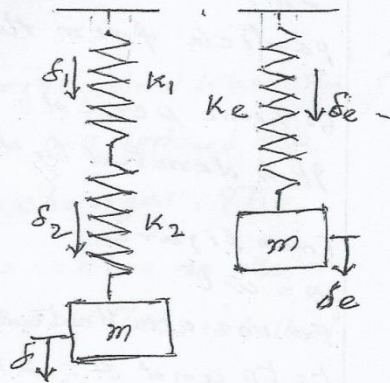
$$\delta_e = \delta = \delta_1 + \delta_2$$

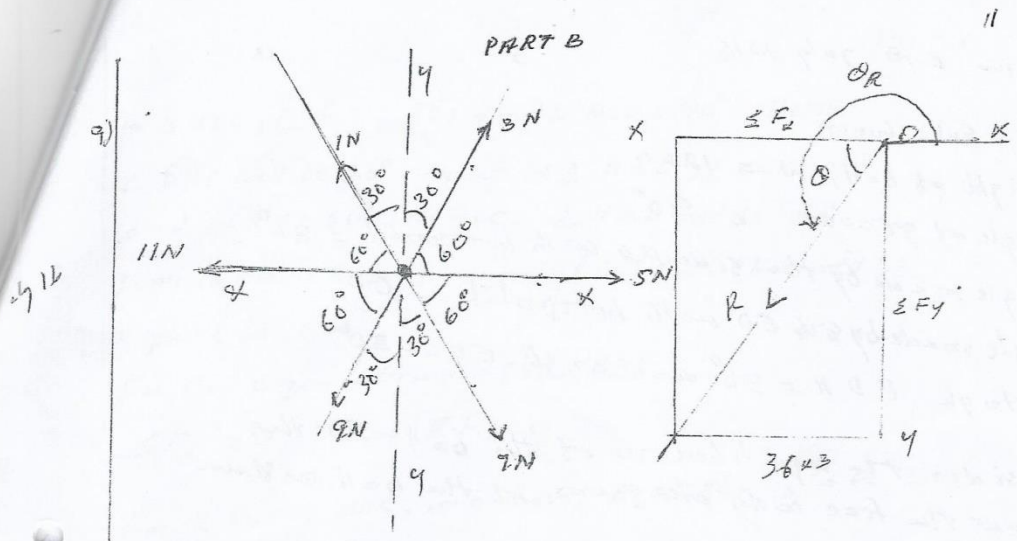
$$mg = k \delta$$

$$\delta = \frac{mg}{k}$$

$$\therefore \frac{mg}{k_e} = \frac{mg}{k_1} + \frac{mg}{k_2}$$

$$\therefore \frac{1}{k_e} = \frac{1}{k_1} + \frac{1}{k_2}$$





solution

Resolving the forces along x axis

$$\begin{aligned} \sum F_x &= 5 + 3 \cos 60 - 1 \cos 60 - 11 - 9 \cos 60 + 7 \cos 60 = 0 \\ &= -6 + (3 - 1 - 9 + 7) \cos 60 = -6 \text{ N} \end{aligned}$$

Resolving the forces along y axis

$$\begin{aligned} \sum F_y &= 3 \cos 30 + 1 \cos 30 - 9 \cos 30 - 7 \cos 30 \\ &= (4 - 16) \cos 30 = -12 \times \frac{\sqrt{3}}{2} = -6\sqrt{3} \end{aligned}$$

$$\text{Resultant } R = \sqrt{\sum F_x^2 + \sum F_y^2} = \sqrt{(-6)^2 + (-6\sqrt{3})^2}$$

$$R = \sqrt{36 + 108} = \sqrt{144} = 12 \text{ N}$$

Inclination of resultant with horizontal let

$$\theta = \tan^{-1} \left| \frac{\sum F_y}{\sum F_x} \right| = \tan^{-1} \frac{6\sqrt{3}}{6} = \tan^{-1} \sqrt{3} = 60^\circ$$

Inclination of resultant with +ve x axis

$$\theta_R = 180 + \theta = 180 + 60 = \underline{\underline{240^\circ}}$$

35100 e.m. July 2016

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P.10. Sol: Given

Weight of ball,  $w = 120\text{ N}$

Angle of groove =  $90^\circ$

Angle made by the side FD with horizontal =  $30^\circ$

Angle made by side ED with horizontal =  $60^\circ$

$\therefore$  Angle FDH =  $30^\circ$  and angle EDG =  $30^\circ$

Consider the equilibrium of the ball. For this draw the free body diagrams of the ball as shown in fig 1-b

The forces acting on the isolated ball will be

- weight of the ball =  $120\text{ N}$  and acting vertically downwards
- Reaction  $R_C$  acting at C and normal to FD
- Reaction  $R_A$  acting at A and normal to DE

The reactions  $R_A$  and  $R_C$  will pass through B i.e. Centre of the ball. The angle made by  $R_A$  and  $R_C$  at point B will be obtained as shown in fig 1-b

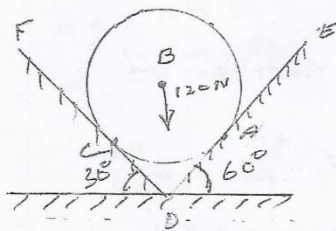


Fig 1-a

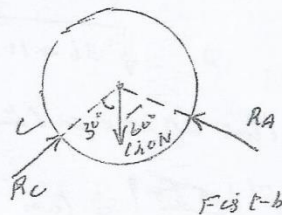


Fig 1-b

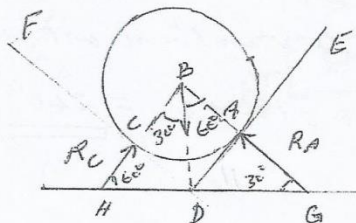


Fig 1-c

(12)



In  $\Delta HDC$ ,  $\angle CDH = 30^\circ$ , and  $\angle DCH = 90^\circ$ . Hence  $\angle DHC$  will be  $60^\circ$ . Now in  $\Delta HBL$ ,  $\angle BLH = 90^\circ$  and  $\angle LHA = 60^\circ$ . Hence  $\angle HBL$  will be  $30^\circ$  similarly  $\angle LBL$  may be calculated. This will be equal to  $60^\circ$

For the equilibrium of the ball

$$\sum F_x = 0 \quad \text{and} \quad \sum F_y = 0$$

For  $\sum F_x = 0$  use, we have  $R_c \sin 30 - R_A \cos 60 = 0$

$$\text{or } R_c \sin 30 = R_A \cos 60$$

$$\text{or } R_c = R_A \frac{\cos 60}{\sin 30} = R_A \times \frac{0.866}{0.5} = 1.732 R_A \quad -1$$

$$R_c = 1.732 R_A$$

For  $\sum F_y = 0$  we have  $120 - R_A \cos 60 - R_c \cos 30 = 0$

$$\text{or } 120 = R_A \cos 60 + R_c \cos 30$$

$$= R_A \times 0.5 + 1.732 R_A \times 0.866 = 2 R_A$$

$$\therefore R_A = \frac{120}{2} = 60 \text{ N} \quad \text{Ans}$$

Substituting this value in eqn. 1, we get

$$R_c = 1.732 \times 60 = 103.92 \text{ N} \quad \text{Ans}$$

$$R_A = 60 \text{ N}, \quad R_c = 103.92 \text{ N}$$

13. E.100 E.M July 2016

Q.11

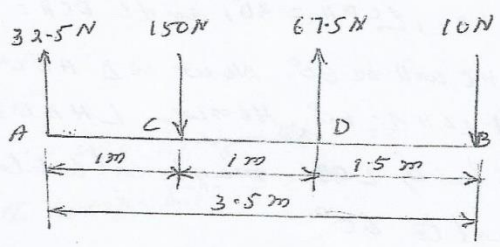


Fig 1-a

To find

- a) a single force
- b) a single force and a couple at A

P52-53: R.K. Bansal

Sol: Given

Forces at A, C, D and B are 32.5N, 150N, 67.5N and 10N respectively

Distance AC = 1m, CD = 1m, and BD = 1.5m

i. single force system: The single force system will consist only resultant force in magnitude and location. All the forces are acting in the vertical direction and hence their resultant R in magnitude is given by

$$R = 32.5 - 150 + 67.5 - 10 = -60 \text{ N}$$

Negative sign shows that resultant is acting vertically downwards

Let x = distance of resultant from A towards right. To find location of the resultant take the moments of all the forces about A, we get moment of resultant about A

= Algebraic sum of moments of all the forces about A.

$$\text{or } R \times x = -150 \times 1 + 67.5 \times 2 - 10 \times 3.5$$

(taking clock wise moment -ve and anticlockwise moment +ve)

$$\text{or } -60 \times x = -150 + 135 - 35 \quad [\because R = -60]$$

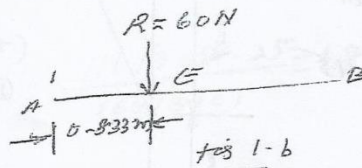
$$-60x = -150 + 135 - 35 = -50 \quad (14)$$

$$x = \frac{-50}{-60} = 0.833 \text{ m}$$

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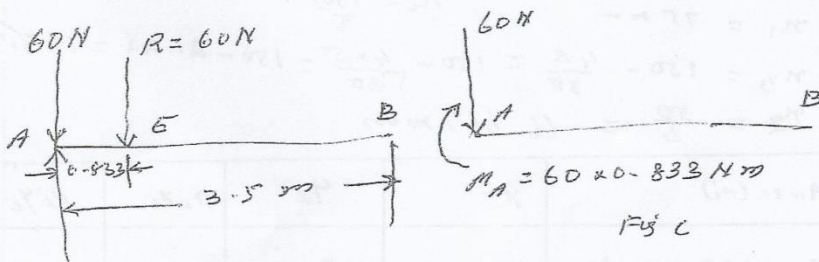
Hence the given system of parallel forces is equivalent to a single force  $60 \text{ N}$  acting vertically downwards at point  $E$  at a distance of  $0.833 \text{ m}$  from  $A$  shown in fig 1-b



b) A single force and a couple at  $A$ . The resultant force  $R$  acting at point  $E$  as shown in fig 1-b can be replaced by an equal force applied at point  $A$  in the same direction together with a couple. This is shown in fig 1-c

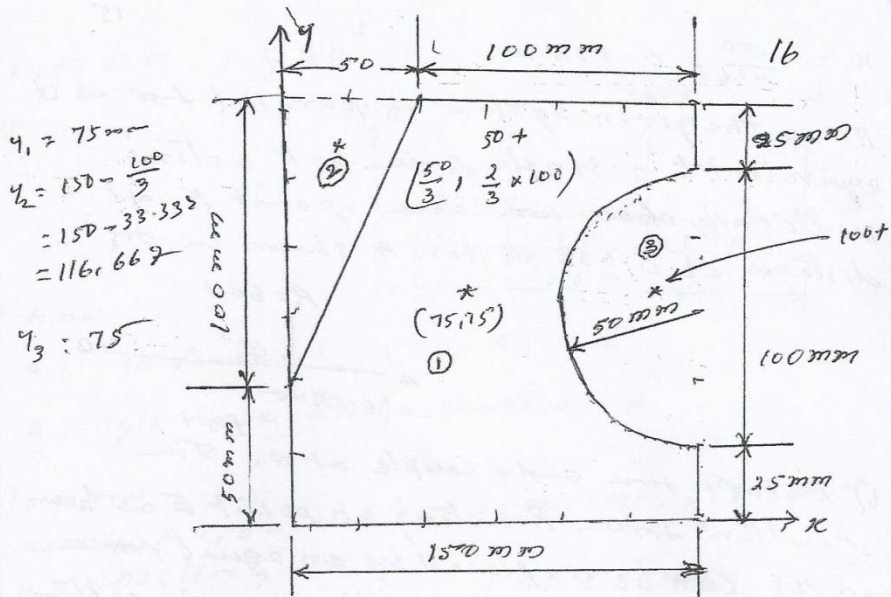
$$\begin{aligned} \text{The moment of the couple} &= 60 \times 0.833 \text{ Nm} \\ &\quad (\text{clockwise}) \\ &= \underline{\underline{-49.98 \text{ Nm}}} \end{aligned}$$

(-ve sign is due to clockwise)



15

12



Area 2 and 3 to be subtracted

To find centroid:

$A_1 = \text{Area of square} = 150 \times 150 = 22500 \text{ mm}^2$   
 $A_2 = \text{Area of Triangle} = \frac{1}{2} \times 50 \times 100 = 2500 \text{ mm}^2$   
 $A_3 = \text{Area of semi circle} = \frac{\pi R^2}{2} = \frac{\pi (50)^2}{2} = 3926.99 \text{ mm}^2$

$x_1 = 75 \text{ mm}$   
 $x_2 = 150 - \frac{4R}{3\pi} = 150 - \frac{4 \times 50}{3\pi} = 150 - 21.22 = 128.78 \text{ mm}$   
 $x_3 = \frac{50}{3} = 16.667 \text{ mm}$

Area ( $A_i$ )	$x_i$	$y_i$	$A_i x_i$	$A_i y_i$
$A_1 = 22500 \text{ mm}^2$	75 mm	75 mm	1687500	1687500
$A_2 = 2500 \text{ mm}^2$ (-)	16.667 mm	116.667 mm	41667.5	291667.5
$A_3 = 3926.99 \text{ mm}^2$ (-)	128.78	75 mm	505717.7	294524.25
			1607301	1101308.25

(16)

1140114.73

1101308.25

$$x_c = \frac{A_1 x_1 - A_2 x_2 - A_3 x_3}{A_1 - A_2 - A_3} =$$

$$= \frac{1687500 - 41667.5 - 505717.77}{22500 - 2500 - 3926.99} = \frac{1140114.73}{16073.01}$$

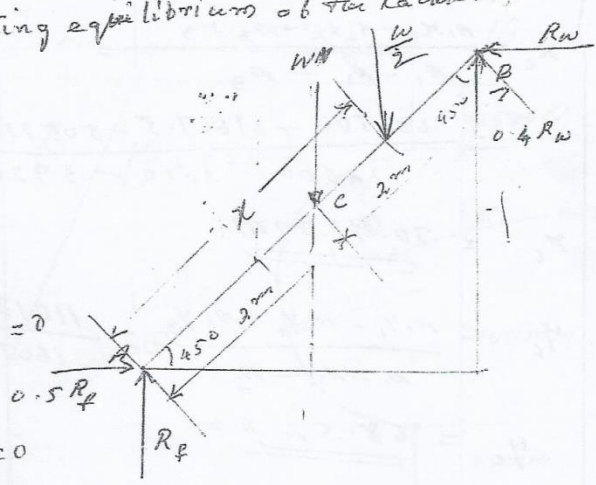
$$x_c = \underline{\underline{70.93 \text{ mm}}}$$

$$y_c = \frac{A_1 y_1 - A_2 y_2 - A_3 y_3}{A_1 - A_2 - A_3} = \frac{1101308.25}{16073.01} = 68.519 \text{ mm}$$

$$y_c = \underline{\underline{68.52 \text{ mm}}}$$

Centroid of the fig  $(x_c, y_c) = (\underline{\underline{70.93 \text{ mm}}, \underline{\underline{68.52 \text{ mm}}})$

13 Consider the limiting equilibrium of the ladder



4.2.0.16

For  $\Sigma F_H = 0$

$$0.5 R_f - R_w = 0$$

$$R_f = 2 R_w$$

For  $\Sigma F_y = 0$

$$R_f - 0.5W - W + 0.4 R_w = 0$$

$$2R_w - 1.5W + 0.4R_w = 0$$

$$R_w = \frac{1.5W}{2.4} = 0.625W$$

for  $\Sigma M = 0$ , taking moment about A

$$0.5W \times 2 \cos 45 + W \times 2 \cos 45 - 0.4 R_w \times 4 \cos 45 - R_w \times 4 \sin 45 = 0$$

$$(0.5W + 2W - 1.6 R_w) \cos 45 = 4 R_w \sin 45 \quad (\cos 45 = \sin 45)$$

$$0.5W + 2W - 1.6 \times 0.625W = 4 \times 0.625W \frac{\sin 45}{\cos 45}$$

$$0.5W + W = 2.5W$$

$$0.5W = 1.5W$$

$$x = \frac{1.5}{0.5} = 3$$

$$0.625W \quad 0.625W$$

$$0.5W \times x \cos 45 + W \times 2 \cos 45 - 0.4 R_w \times 4 \cos 45 - R_w \times 4 \sin 45 = 0$$

$$0.5W \times x + (2W - W) = \frac{2.5W \sin 45}{\cos 45} = 2.5W \tan 45$$

$$0.5x = 1.5$$

$$x = \frac{1.5}{0.5} = \underline{\underline{3 \text{ m}}}$$

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Sol: weight of first body

$$W_1 = 500 \text{ N}$$

weight of second body

$$W_2 = 1000 \text{ N}$$

coefficient of friction

for first body,  $\mu_1 = 0.15$

coefficient of friction for second body,  $\mu_2 = 0.40$

Let  $\theta =$  inclination of plane

$T =$  tension in chord the string

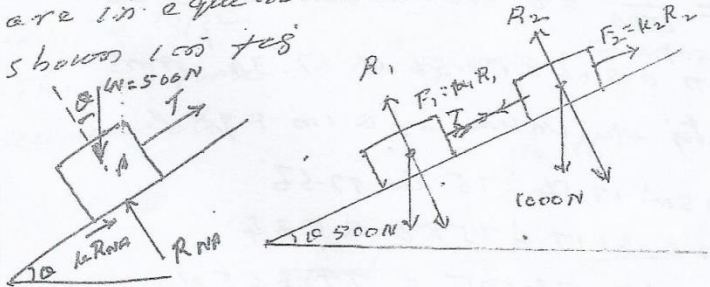
$R_1 =$  normal reaction for 1st body.

$R_2 =$  normal reaction for 2nd body

$F_1 =$  Force of friction between 1st body and plane  $= \mu_1 R_1$

$F_2 =$  Force of friction between 2nd body and plane  $= \mu_2 R_2$

As the motion of the two bodies is about to take place down the inclined plane, the force of friction  $F_1$  and  $F_2$  will be acting upward. The two bodies are in equilibrium under the action of forces shown in fig



Forces on the first body

Resolving forces along the plane

$$500 \sin \theta = T + F_1 = T + \mu_1 R_1 = T + 0.15 R_1 \quad \text{--- (1)}$$

Resolving forces normal to the plane

$$500 \cos \theta = R_1$$

Substituting the value of  $R_1$  in equation 1

$$500 \sin \theta = T + 0.15 \times 500 \cos \theta = T + 75 \cos \theta$$

$$500 \sin \theta = T + 75 \cos \theta$$

$$T = 500 \sin \theta - 75 \cos \theta \quad \text{--- ii}$$

Forces on the second body

Resolving forces along the plane

$$1000 \sin \theta + T = F_2 = \mu_2 F_2 = 0.40 R_2 \quad \text{--- iii}$$

Resolving forces normal to the plane

$$R_2 = 1000 \cos \theta$$

Substituting the value of  $R_2$  in eqn iii

$$1000 \sin \theta + T = 0.4 \times 1000 \cos \theta$$

$$T = 400 \cos \theta - 1000 \sin \theta \quad \text{--- iv}$$

Equating the values of  $T$  given by eqn ii & iv

$$500 \sin \theta - 75 \cos \theta = 400 \cos \theta - 1000 \sin \theta$$

$$500 \sin \theta + 1000 \sin \theta = 400 \cos \theta + 75 \cos \theta$$

$$1500 \sin \theta = 475 \cos \theta$$

$$\text{or } \frac{\sin \theta}{\cos \theta} = \frac{475}{1500} = 0.3166 \text{ or } \tan \theta = 0.3166$$

$$\therefore \theta = \tan^{-1} 0.3166 = 17.56^\circ \text{ or } 17^\circ 34' \text{ Ans}$$

Substituting the value of  $\theta$  in eqn ii

$$T = 500 \sin 17.56 - 75 \cos 17.56$$

$$T = 500 \times 0.3017 - 75 \times 0.9534$$

$$= 150.85 - 71.505 = 79.345 \text{ N}$$

$$T = \underline{\underline{79.345 \text{ N}}}$$



R-15 Sol. Given

Weight of the elevator,  $w_1 = 5000 \text{ N}$

Acceleration of the elevator,  $a = 3 \text{ m/s}^2$

Weight of the operator,  $w_2 = 700 \text{ N}$

When the operator is standing on the scale, placed on the floor of the elevator, the reading of the scale will be equal to the reaction  $R$  offered by the floor on the operator

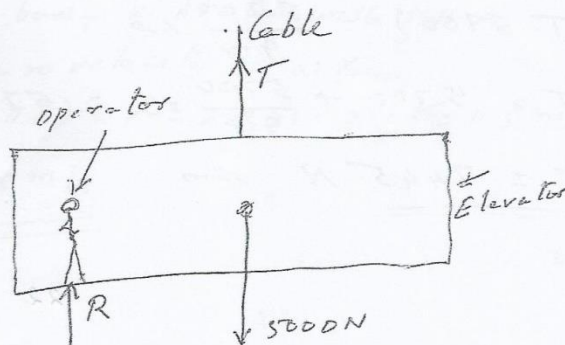
Hence let  $R$  = Reaction offered by floor on operator. This is also equal to the reading of scale

$T$  - total tension in the cables of elevator

Consider the motion of operator. The operator is moving upwards along with the elevator with an acceleration of  $3 \text{ m/s}^2$

$a = 3 \text{ m/s}^2$

The net force on the operator is acting upwards



Net upward force on operator = Reaction offered by floor on operator - weight of operator =  $(R - 700)$   
 Mass of operator =  $\frac{\text{weight of operator}}{g} = \frac{700}{9.8}$

Net force = Mass  $\times$  Acceleration

$$(R - 700) = \frac{700}{9.8} \times 3 \quad (\text{where acceleration} = 3 \frac{m}{s^2})$$

$$R = 700 + \frac{700}{9.8} \times 3 = 700 + 214.28 = \underline{914.28 \text{ N Ans}}$$

Total tension in the cables of elevator

Let  $T$  = Total tension in the cables of elevator

$W$  = Total weight (ie weight of elevator + weight of operator)

$$W = 5000 + 700 = 5700 \text{ N}$$

As the elevator with the operator is moving upwards with an acceleration,  $a = 3 \text{ m/s}^2$ , the net force will be acting on the elevator and operator in the upward direction

net upward force on elevator & operator = Total tension in the cables - total weight of elevator & operator

$$= (T - 5700)$$

$$\text{mass of elevator and operator} = \frac{\text{Total wt}}{g} = \frac{5700}{9.8}$$

Net force = mass  $\times$  acceleration

$$(T - 5700) = \frac{5700}{9.8} \times 3$$

$$T = 5700 + \frac{5700}{9.8} \times 3 = 5700 + 1745$$

$$\underline{T = 7445 \text{ N Ans}}$$

16) To find

i) stiffness of the spring,  $k = 4\pi^2 f^2 m$

ii) maximum tension in the spring =  $kx$

iii) For S.H.M. max. velocity =  $\omega x$

Given:  $m = \frac{W}{g} = \frac{50}{9.81} =$

$x = 8 \text{ cm} = 0.08 \text{ m}$

$f = 1 \text{ CPS}$

a)  $f = \frac{1}{2\pi} \sqrt{\frac{k}{m}}$

$f^2 = \frac{1}{4\pi^2} \times \frac{k}{m}$

$\therefore k = f^2 \times 4 \times \pi^2 \times m = 1 \times 4 \times \pi^2 \times \frac{50}{9.81}$

$k = \underline{\underline{201.22 \text{ N/m}}}$   $\left\{ \begin{array}{l} \therefore k - \text{stiffness of the} \\ \text{spring.} \end{array} \right.$

b) maximum tension in the spring =  $kx$   
 $= 201.22 \times 0.08 = \underline{\underline{16.1 \text{ N}}}$

c) since the body vibrates with S.H.M

The maximum velocity =  $\omega x$

$= (2\pi f) \times x = 2 \times \pi \times 1 \times 0.08 = 0.5 \text{ m/s}$

$V_{\text{max}} = 0.5 \text{ m/s}$

17) solutions

$$m = \frac{W}{g} = \frac{100}{9.81}$$

$$x = 8\text{cm} = 0.08\text{m}$$

$$f = 1\text{cps}$$

a) The stiffness of the spring, k

$$f = \frac{1}{2\pi} \sqrt{\frac{k}{m}} \quad ; \quad f^2 = \frac{1}{4\pi^2} \times \frac{k}{m}$$

$$k = f^2 \times 4\pi^2 \times m = 1 \times 4 \times \pi^2 \times \frac{100}{9.81} = 402.43$$

$$k = 402.43 \frac{N}{m}$$

b) maximum tension in the spring = kx

$$T_{\text{max}} = 402.43 \times 0.08 = 32.2\text{N}$$

$$T_{\text{max}} = 32.2\text{N}$$

c) Since the body vibrates with S.H.M

The maximum velocity,  $v_{\text{max}} = \omega x$

$$v_{\text{max}} = (2\pi f) \times x = 2\pi \times 1 \times 0.08 = 0.5\text{m/s}$$

$$v_{\text{max}} = 0.5\text{m/s}$$

