

# Applicability of electronic mapping for Environmental Design Researchers

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## [ Theoretical Background ]

The **core concept** of ecological analysis in Environment Behavior Research is the Behavior Setting.

**Definition:** *“An environment-behavior unit characterized by cyclical patterns of activity that occur within specific time intervals and spatial boundaries.”*

### Fundamental Methods

Longitudinal approach  
Naturalistic observation  
Field studies  
Direct recording of behavior  
Unobtrusive methods



[ Point of Emphasis ]

▶ [ Circulation Behavior Mapping ]

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[ What to Achieve ]

▶ [ Unobtrusive Survey Tool ]

▶ [ Reduce Margin of Error in Data ]

▶ [ Automated Precision Time Data ]

▶ [ Elongate Uniform Observation ]



# [ Types of Data to Retrieve ]

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- [ 01 ] : [ The length of traveled distance ]
- [ 02 ] : [ Trip counts between different locations ]
- [ 03 ] : [ Precision Time-sampling ]
- [ 04 ] : [ Accurate Circulation Mapping ]
- [ 05 ] : [ Trip counts between different nodes ]
- [ 06 ] : [ Time spent on the move ]
- [ 07 ] : [ Traffic Index ]
- [ 08 ] : [ Comparative Workload Analysis ]
- &
- [ 09 ] : [ Unaffected Behavior Pattern Data ]



# [ Circulation Behavior Mapping ]

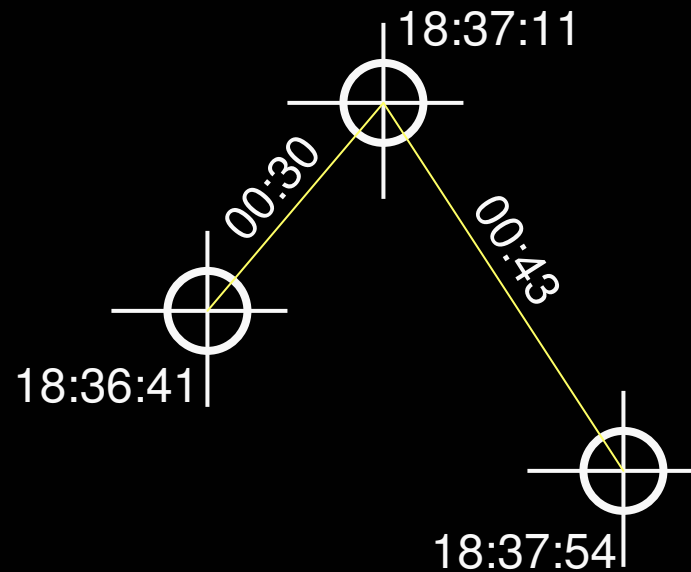
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Three Dimensions

[ 01 ] : [ Position ]

[ 02 ] : [ Path ]

[ 03 ] : [ Time ]



## [ Tools To Be Used ]

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### [ Hardware ]

[ 01 ] : [ RFID ]

[ 02 ] : [ Laser Scanning ]

[ 03 ] : [ Video Image Recognition ]

### [ Software ]

[ 01 ] : [ MATLAB as Language ]

[ 02 ] : [ CAD ]

[ 03 ] : [ AVI & MPEG movie files ]



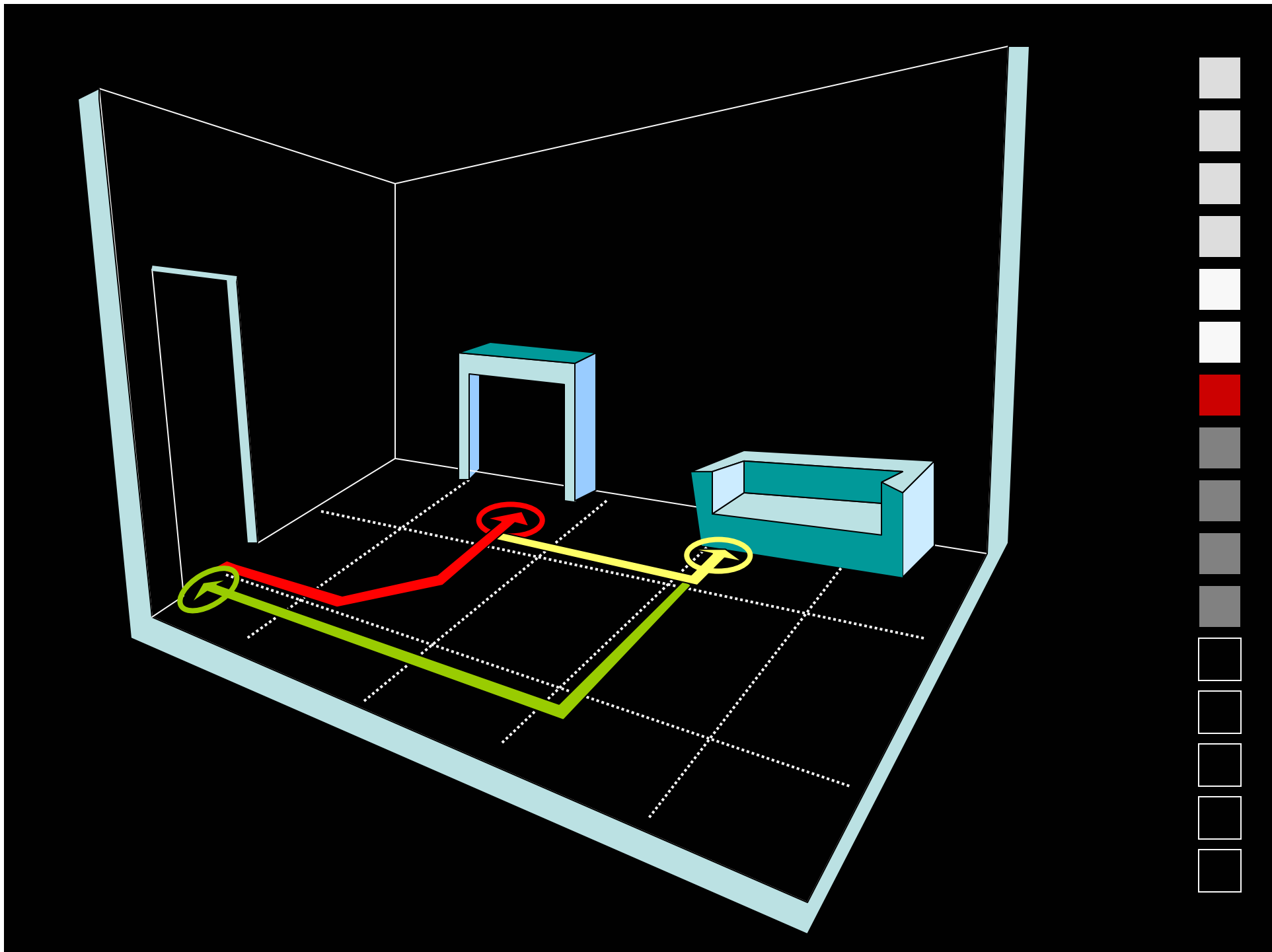
# [ Experiment Methodology ]

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## [ Steps ]

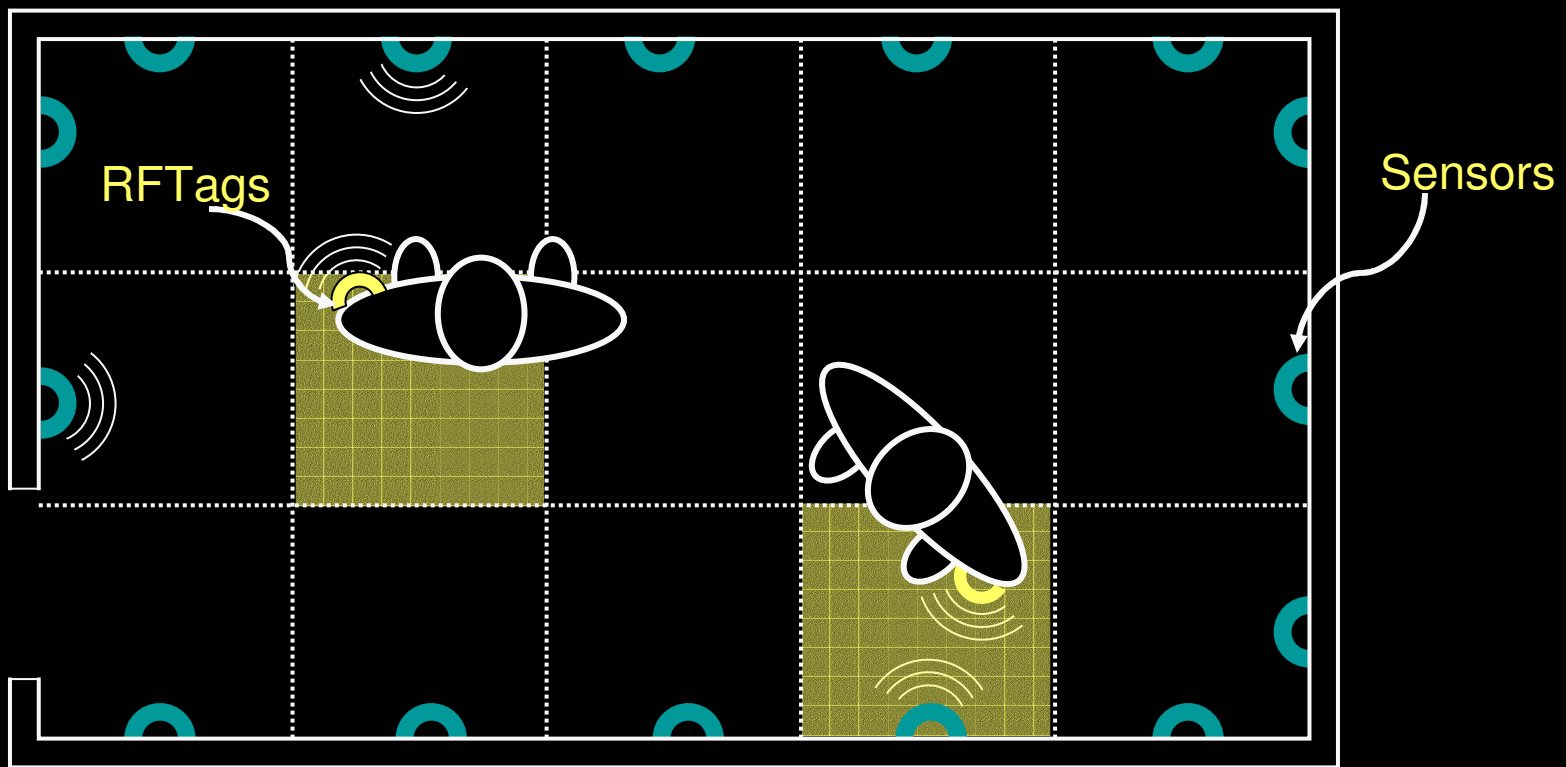
- [ 01 ] : [ Create Modeled Space with known DIMENSIONS ]
- [ 02 ] : [ Make a Mock-up Test Case with Control Samples ]
- [ 03 ] : [ Setup Video Capture, RFID Maze, & Laser Scanners in the Controlled Experimental Environment ]
- [ 04 ] : [ Collect Manual & Electronic Data Simultaneously ]
- [ 05 ] : [ Synthesize & Compare ]





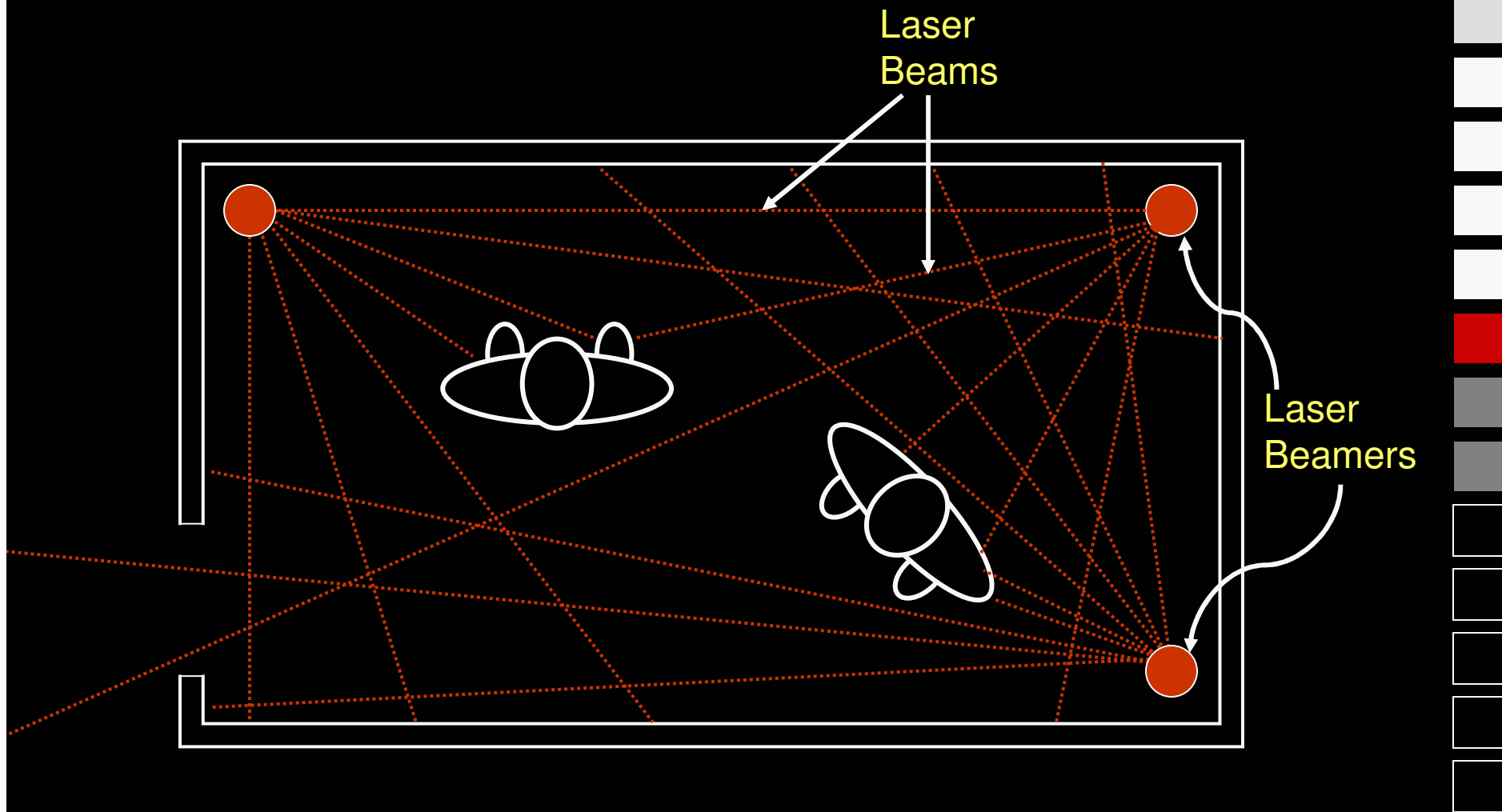
# [ RFID Conceptual Diagram ]

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# [ Laser Scanning Conceptual Diagram ]

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## [ Sources of Resources/Support ]

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### Center for Spatial Information Systems

University of Tokyo

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Specializes in Movement Tracking by Laser Scanners  
and RFID Technology

*Ref.: Shibazaki Lab*

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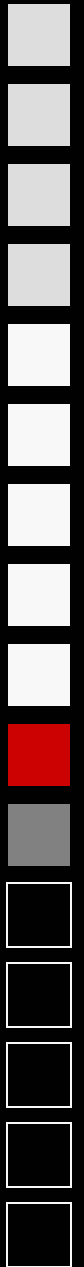
### Innovative IP Architecture Center

NTT Communications

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Specializes in Optical Flow Analysis and Face  
Recognition through Video Images

*Ref.: Hidetomo Sakaino, Senior Manager*



## [ Output of Experiment ]

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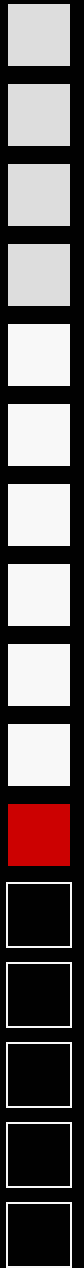
### Three Types of Maps will evolve:

[ 01 ] : Laser Scanning Map (RFID)

[ 02 ] : Video Image Analysis Map

[ 03 ] : In-Situ Manual Tracing Map

- The Pre-Experiment Mock Up Drawing Data will act as the Point of Reference for Comparison.





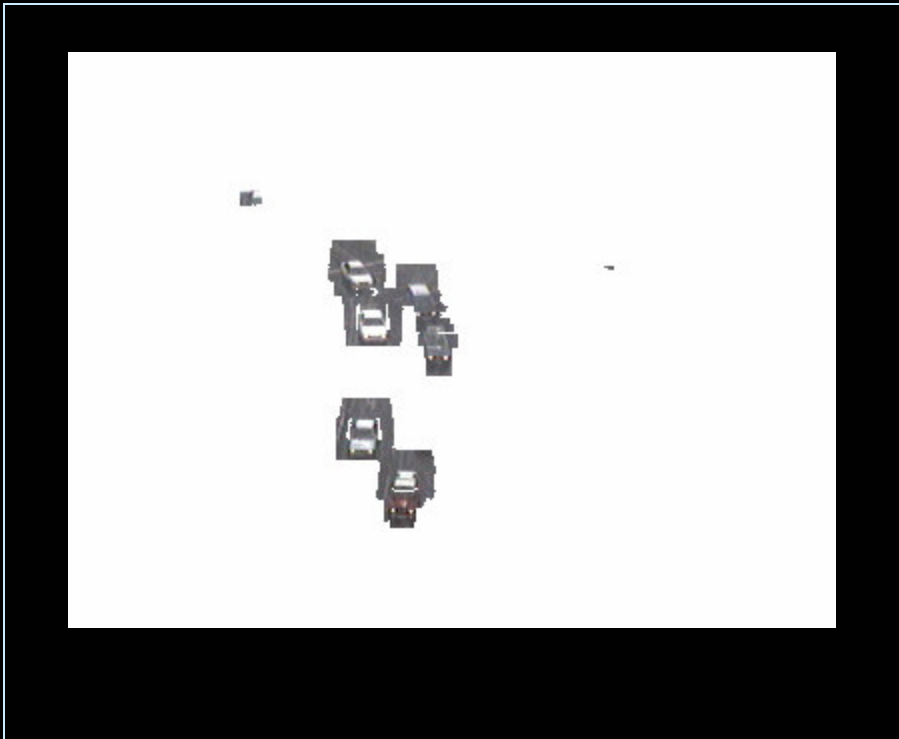
*Source: Hidetomo Sakaino*





*Source: Hidetomo Sakaino*





*Source: Hidetomo Sakaino*





Source: Hidetomo Sakaino



[ Thank You ]

