

1  **DIMENSIONS OF THE SINE WAVE**

● **dimensions of sine waves**

◆ **Amplitude**

◆ **Phase**

◆ **Frequency/Period: $f = 1/T$ or $T = 1/f$**

Note: when a sine wave represents something in space, wavelength is used instead of period.

2  **Units of Measure For Frequency and Period**

● **Frequency (f)**

◆ Hz to kHz: Divide by 1,000

◆ kHz to Hz: Multiply by 1,000

● **Period (T)**

◆ s to ms: Multiply by 1,000

◆ ms to s: Divide by 1,000

● $f = 1/T$ and $T = 1/f$

3  **Important Phasic Relations**

● **Displacement (Elasticity)**

● **Velocity (Momentum; Damping)**

● **Acceleration**

● **Relations: ◆ c leads x by 90°**

◆ a leads c by 90° ,

and

◆ a leads x by 180°


4  **DIMENSIONS OF THE SINE WAVE**

● **(5) WAVELENGTH (λ)**

● **Two quantities are measured with respect to time**

◆ **Frequency (f)**

◆ **Speed of sound (s)**

5  **Wavelength**

● **Wavelength (λ) relates frequency and speed of sound**

● **λ = distance traveled during one period**

● **$\lambda = s/f$**

● **Examples**

◆ In air: $f = 1100$ Hz, $s = 340$ m / s; $\lambda = ?$

☑ $\lambda = 340 / 1100 = .3$ m

◆ In air: $f = 550$ Hz, $s = 340$ m / s; $\lambda = ?$

☑ $\lambda = 340 / 550 = .6$ m

6  **DAMPING/ Effects of Friction on Vibratory Motion**

● **Oscillating systems encounter opposition to motion: friction, or frictional resistance**

● **Friction limits velocity**

● **Amplitude of vibration diminishes over time**

● **Vibrations are damped**

7  **The Magnitude of Damping**

- In Figure,
 - ◆ Panel A: lossless system
 - ◆ Panel B: low-damped system
 - ◆ Panel C: high-damped system

8  **ACOUSTIC IMPEDANCE**

- System engages in SHM: it vibrates freely at its natural frequency (f_{nat})
- $f_{\text{nat}} = \sqrt{s/m}$
- What are the concepts involved in this oscillation?
 - elasticity / restoring force (spring)
 - inertia / momentum (mass)
 - friction / damping


9  **ACOUSTIC IMPEDANCE**

- Forces exist that oppose, or impede, motion: Impedance (Z)
- Total impedance has two components:
 - ◆ resistance R (friction)
 - ◆ reactance X
 - > mass reactance X_m (mass)
 - > compliant reactance X_c (spring)

10  **Impedance**

Resistance (R) Reactance (X)

- Friction, or frictional resistance, occurs: kinetic energy is transformed to thermal energy
 - Resistance measured in ohms (Ω)
 - Resistance is independent of frequency!
- Forces that oppose motion in a frequency selective way: frequency dependent
 - With X, energy is stored
 - With R, energy is dissipated from motion

11  **Two Components of Impedance**

- 1. Energy-dissipating: What is it?
 - Resistance (R), which is independent of frequency
- 2. Energy-storage: What is it?
 - Reactance (X), which is dependent on frequency
- Impedance: Complex sum of R & X

12  **Crucial Phasic Relations**

- Opposition to motion from Resistance is in phase with velocity
 - ◆ Resistance: in phase with c, M, and damping
- Opposition to motion from Compliance is in phase with elasticity; lags Resistance by 90°
 - ◆ Compliance: in phase with E and x
- Opposition to motion from Mass is in phase with acceleration;

♦ leads resistance by 90°

13 **Two Components of X:**

X_m and X_c

- When one reactance component stores energy, the other gives up energy
- They are 180° out of phase with one another
- They act in opposition to one another

14 **Mass Reactance: X_m**

- X_m is directly proportional to frequency
- At low frequencies,
 - ♦ X_m negligible; larger amplitude of vibration
- At high frequencies,
 - ♦ X_m large; smaller amplitude of vibration
- X_m

f

15 **Compliant Reactance: X_c**

- At low frequencies,
 - ♦ X_c large; smaller amplitude of vibration
- At high frequencies,
 - ♦ X_c negligible; larger amplitude of vibration
- X_c is inversely proportional to frequency

● X_c

f

16 **Mass Reactance (X_m) and Compliant Reactance (X_c)**

- What if $X_m = X_c$?
 - ♦ If $X_m = X_c$, $X = 0$
 - ♦ $Z = R$
 - ♦ Impedance is minimal
 - ♦ Amplitude of vibration is largest
 - ♦ f_{nat}

17 **Impedance (Z)**

(What to remember)

- R causes energy to be dissipated
ie. resistance from friction)
- X causes energy to be stored
 - ♦ X_m leads R by 90°
ie. Reactance from mass
 - ♦ X_c lags R by 90°
ie. Reactance from compliance (spring)
 - ♦ X_m leads X_c by 180°