

Inter American University of Puerto Rico  
Bayamón Campus  
School of Engineering  
Department of Electrical Engineering

**ELEN 3302 – Electric Circuits II**

**Problem Set 1 Solutions**

*Due Wednesday, August 25*

**Problem 1:**

- (A) Prove that  $e^{jx} = \cos x + j \sin x$  by using the Taylor series expansion of  $e^x$ ,  $\sin x$  and  $\cos x$ .

Taylor expansions:

$$e^x = \frac{x^0}{0!} + \frac{x^1}{1!} + \frac{x^2}{2!} + \frac{x^3}{3!} + \frac{x^4}{4!} + \frac{x^5}{5!} + \dots$$

$$\cos x = \frac{x^0}{0!} - \frac{x^2}{2!} + \frac{x^4}{4!} - \dots$$

$$\sin x = \frac{x^1}{1!} - \frac{x^3}{3!} + \frac{x^5}{5!} - \dots$$

Evaluate  $e^{jx}$ :

$$e^{jx} = \frac{(jx)^0}{0!} + \frac{(jx)^1}{1!} + \frac{(jx)^2}{2!} + \frac{(jx)^3}{3!} + \frac{(jx)^4}{4!} + \frac{(jx)^5}{5!} + \dots$$

$$e^{jx} = \frac{x^0}{0!} + j \frac{x^1}{1!} - \frac{x^2}{2!} - j \frac{x^3}{3!} + \frac{x^4}{4!} + j \frac{x^5}{5!} + \dots$$

$$e^{jx} = \left( \frac{x^0}{0!} - \frac{x^2}{2!} + \frac{x^4}{4!} - \dots \right) + j \left( \frac{x^1}{1!} - \frac{x^3}{3!} + \frac{x^5}{5!} - \dots \right)$$

$$e^{jx} = \cos x + j \sin x$$

- (B) Using the relation proved in the previous part, derive the following relationships:

$$\begin{aligned} \text{(i)} \quad \cos x &= \frac{1}{2}(e^{jx} + e^{-jx}) \\ \cos x &= \frac{\cos x + j \sin x + \cos(-x) + j \sin(-x)}{2} \\ \cos x &= \frac{\cos x + j \sin x + \cos x - j \sin x}{2} \\ \cos x &= \frac{2 \cos x}{2} \\ \cos x &= \cos x \end{aligned}$$

$$\begin{aligned} \text{(ii)} \quad \sin x &= \frac{j}{2}(e^{-jx} - e^{jx}) \quad (\text{Hint: Show that } 1/j = -j.) \\ \sin x &= \frac{j}{2}(\cos x - j \sin x - \cos x - j \sin x) \\ \sin x &= \frac{j}{2}(-2j \sin x) \\ \sin x &= -j^2 \sin x \\ \sin x &= \sin x \end{aligned}$$

$$\begin{aligned}
\text{(iii)} \quad \cos^2 x &= \frac{1}{2}(1 + \cos 2x) \\
\frac{(e^{jx} + e^{-jx})^2}{4} &= \frac{1}{2}(1 + \cos 2x) \\
\frac{e^{2jx} + e^{-2jx} + 2}{4} &= \frac{1}{2}(1 + \cos 2x) \\
\frac{2 \cos 2x + 2}{4} &= \frac{1}{2}(1 + \cos 2x) \\
\frac{1 + \cos 2x}{2} &= \frac{1}{2}(1 + \cos 2x) \\
\text{(iv)} \quad \sin x \sin y &= \frac{1}{2} \cos(x - y) - \frac{1}{2} \cos(x + y) \\
\frac{(e^{jx} - e^{-jx})}{2j} \frac{(e^{jy} - e^{-jy})}{2j} &= \frac{1}{2} \frac{(e^{j(x-y)} - e^{-j(x-y)})}{2} - \frac{1}{2} \frac{(e^{j(x+y)} - e^{-j(x+y)})}{2} \\
-\frac{1}{4}(e^{jx} - e^{-jx})(e^{jy} - e^{-jy}) &= \frac{1}{4}(e^{jx}e^{-jy} + e^{-jx}e^{jy} - e^{jx}e^{jy} - e^{-jx}e^{-jy}) \\
-\frac{1}{4}(e^{jx}e^{jy} - e^{jx}e^{-jy} - e^{-jx}e^{jy} + e^{-jx}e^{-jy}) &= \frac{1}{4}(e^{jx}e^{-jy} + e^{-jx}e^{jy} - e^{jx}e^{jy} - e^{-jx}e^{-jy}) \\
\text{(v)} \quad \sin(x + y) &= \sin x \cos y + \cos x \sin y \\
\frac{e^{j(x+y)} - e^{-j(x+y)}}{2j} &= \frac{e^{jx} - e^{-jx}}{2j} \cdot \frac{e^{jy} - e^{-jy}}{2} + \frac{e^{jx} + e^{-jx}}{2} \cdot \frac{e^{jy} - e^{-jy}}{2j} \\
\frac{e^{j(x+y)} - e^{-j(x+y)}}{2j} &= \frac{e^{j(x+y)} + e^{j(x-y)} - e^{-j(x-y)} - e^{-j(x+y)} + e^{j(x+y)} - e^{j(x-y)} - e^{-j(x-y)} - e^{-j(x+y)}}{2 \cdot 2j} \\
\frac{e^{j(x+y)} - e^{-j(x+y)}}{2j} &= \frac{2e^{j(x+y)} - 2e^{-j(x+y)}}{2 \cdot 2j} \\
\frac{e^{j(x+y)} - e^{-j(x+y)}}{2j} &= \frac{e^{j(x+y)} - e^{-j(x+y)}}{2j}
\end{aligned}$$

(C) A linear system has the output  $y(t) = e^{j3t}$  if the input is  $x(t) = e^{j2t}$ , and the output  $y(t) = e^{-j3t}$  if the input is  $x(t) = e^{-j2t}$ . Determine the output of the system if:

$$\begin{aligned}
\text{(i)} \quad x_1(t) &= \cos 2t \\
e^{j2t} &\Rightarrow e^{j3t} \\
e^{-j2t} &\Rightarrow e^{-j3t} \\
\cos 2t &= \frac{1}{2}e^{j2t} + \frac{1}{2}e^{-j2t} \Rightarrow \frac{1}{2}e^{j3t} + \frac{1}{2}e^{-j3t} = \cos 3t \\
\text{(ii)} \quad x_2(t) &= \cos[2(t - 1/2)] \\
e^{j2t} &\Rightarrow e^{j3t} \\
e^{-j2t} &\Rightarrow e^{-j3t} \\
\cos[2(t - \frac{1}{2})] &= \frac{1}{2}e^{j2t}e^{-j} + \frac{1}{2}e^{-j2t}e^j \Rightarrow \frac{1}{2}e^{j3t}e^{-j} + \frac{1}{2}e^{-j3t}e^j = \cos(3t - 1) = \cos[3(t - \frac{1}{3})] \\
\text{Note that even though the system is linear, it is not time-invariant, since a shift in the input of } 1/2 &\text{ produces a shift in the output of } 1/3.
\end{aligned}$$

## Problem 2:

(A) Consider a time-invariant system. Show that if input  $x(t)$  is periodic, then output  $y(t)$  must also be periodic. *Hint: Remember that periodicity is defined as  $x(t - T) = x(t)$  for some period  $T$ .*

From the problem statement,  $x(t) = x(t - T)$ . Furthermore, since the system is time-invariant, given any  $x(t) \rightarrow y(t)$ , then  $x(t - \tau) \rightarrow y(t - \tau)$  for any time shift  $\tau$ . Choose  $\tau = T$ . Then  $y(t) = y(t - T)$  if  $x(t) = x(t - T)$  because of time-invariance. Since  $x(t) = x(t - T)$  by periodicity of  $x(t)$ , it follows that  $y(t) = y(t - T)$ . Thus,  $y(t)$  is periodic.

- (B) Give an example of a time-invariant system and a nonperiodic input signal  $x(t)$  such that the corresponding output  $y(t)$  is periodic.

Consider the time-invariant system (as proven in class)  $y(t) = \sin[x(t)]$ . Let  $x(t) = t$  (nonperiodic). Then,  $y(t) = \sin t$ , which is a periodic signal.

**Problem 3:**

- (A) Consider the statement: The series interconnection of two linear time-invariant systems is a linear time-invariant system. True or false? Justify your answer.

Assume linear system  $S_1$  such that  $x(t) \rightarrow y(t)$ . Assume also linear system  $S_2$  such that  $y(t) \rightarrow z(t)$ . Then, choose a particular  $x_1(t)$  and  $x_2(t)$ . By our assumption,  $x_1(t) \rightarrow y_1(t) \rightarrow z_1(t)$ , and  $x_2(t) \rightarrow y_2(t) \rightarrow z_2(t)$ . Since  $S_1$  is linear,  $ax_1(t) + bx_2(t) \rightarrow ay_1(t) + by_2(t)$ . Similarly, since  $S_2$  is linear,  $ay_1(t) + by_2(t) \rightarrow az_1(t) + bz_2(t)$ . Hence, the series combination of  $S_1, S_2$  yields  $ax_1(t) + bx_2(t) \rightarrow az_1(t) + bz_2(t)$ , which proves the combined system is linear. An identical argument proves that the series combination of  $S_1$  and  $S_2$  is also time-invariant.

- (B) Consider the statement: The series interconnection of two nonlinear systems is a nonlinear system. True or false? Justify your answer.

Consider the systems  $y(t) = x^3(t)$  and  $z(t) = \sqrt[3]{y(t)}$ . Both system are clearly nonlinear, yet their series interconnection yields the system  $z(t) = x(t)$ , which is obviously linear.

**Problem 4:** An even signal is a signal which satisfies the condition  $x_e(-t) = x_e(t)$ . An odd signal satisfies  $x_o(-t) = -x_o(t)$ . Any signal  $x(t)$  may be decomposed into even and odd parts using  $x_e(t) = [x(t) + x(-t)]/2$  and  $x_o(t) = [x(t) - x(-t)]/2$ .

- (A) Check that the equation for  $x_e(t)$  yields an even signal, and that the equation for  $x_o(t)$  yields an odd signal. Also check that  $x_e(t) + x_o(t) = x(t)$ .

$$x_e(t) = [x(t) + x(-t)]/2$$

$$x_e(-t) = [x(-t) + x(t)]/2 = x_e(t)$$

$$x_o(t) = [x(t) - x(-t)]/2$$

$$x_o(-t) = [x(-t) - x(t)]/2 = -[x(t) - x(-t)]/2 = -x_o(t)$$

$$x_e(t) + x_o(t) = [x(t) + x(-t)]/2 + [x(t) - x(-t)]/2 = [x(t) + x(-t) + x(t) - x(-t)]/2 = 2x(t)/2 = x(t)$$

(B) Show that

$$\int_{-\infty}^{+\infty} x_o(t) dt = 0$$

for any odd signal  $x_o(t)$ .

First, break the integral in two parts:

$$\int_{-\infty}^{+\infty} x_o(t) dt = \int_{-\infty}^0 x_o(t) dt + \int_0^{+\infty} x_o(t) dt$$

Let  $\tau = -t$ . Then  $d\tau = -dt$  and

$$= - \int_{+\infty}^0 x_o(-\tau) d\tau + \int_0^{+\infty} x_o(t) dt$$

Changing the limits,

$$= \int_0^{+\infty} x_o(-\tau) d\tau + \int_0^{+\infty} x_o(t) dt$$

Since  $x_o(-t) = -x_o(t)$ ,

$$= - \int_0^{+\infty} x_o(\tau) d\tau + \int_0^{+\infty} x_o(t) dt = 0$$

(C) Show that if  $x_1(t)$  is an odd signal and  $x_2(t)$  is an even signal, then  $x_1(t)x_2(t)$  is an odd signal.

$$x_1(-t)x_2(-t) = -x_1(t) \cdot x_2(t) = -x_1(t)x_2(t)$$

(D) Show that

$$\int_{-\infty}^{+\infty} x^2(t)dt = \int_{-\infty}^{+\infty} x_e^2(t)dt + \int_{-\infty}^{+\infty} x_o^2(t)dt$$

where  $x_e(t)$  and  $x_o(t)$  are the even and odd parts of  $x(t)$ .

Express  $x(t)$  as the sum of its even and odd parts:

$$\begin{aligned}\int_{-\infty}^{+\infty} x^2(t)dt &= \int_{-\infty}^{+\infty} [x_e(t) + x_o(t)]^2 dt = \int_{-\infty}^{+\infty} [x_e^2(t) + x_o^2(t) + 2x_e(t)x_o(t)]dt \\ &= \int_{-\infty}^{+\infty} x_e^2(t)dt + \int_{-\infty}^{+\infty} x_o^2(t)dt + 2 \int_{-\infty}^{+\infty} x_e(t)x_o(t)dt\end{aligned}$$

But  $x_e(t)x_o(t)$  yields an odd function such that

$$2 \int_{-\infty}^{+\infty} x_e(t)x_o(t)dt = 0$$

Therefore,

$$\int_{-\infty}^{+\infty} x^2(t)dt = \int_{-\infty}^{+\infty} x_e^2(t)dt + \int_{-\infty}^{+\infty} x_o^2(t)dt$$