8085

Microprocessor

Programs

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PROGRAMS FOR 8085 MICROPROCESSOR

PROGRAMS FOR LEARNERS

- 1. Store 8-bit data in memory
- 2. Exchange the contents of memory locations
- 3. Add two 8-bit numbers
- 4. Subtract two 8-bit numbers
- 5. Add two 16-bit numbers
- 6. Add contents of two memory locations
- 7. Subtract two 16-bit numbers.
- 8. Finding one's complement of a number
- 9. Finding Two's complement of a number
- 10. Pack the unpacked BCD numbers
- 11. Unpack a BCD number
- 12. **Execution format of instructions**
- 13. Right shift bit of data
- 14. Left Shifting of a 16-bit data
- 15. Alter the contents of flag register in 8085

PROGRAMS FOR BEGINNERS

- 16. Calculate the sum of series of numbers
- 17. Multiply two 8-bit numbers
- 18. Divide a 16 bit number by a 8-bit number
- 19. Find the negative numbers in a block of data.
- 20. Find the largest of given numbers
- 21. **Count number of one's in a number**
- 22. Arrange in ascending order
- 23. Calculate the sum of series of even numbers
- 24. Calculate the sum of series of odd numbers
- 25. Find the square of given number
- 26. Search a byte in a given number
- 27. Add two decimal numbers of 6 digit each
- 28. Add each element of array with the elements of another array
- 29. Separate even numbers from given numbers
- 30. Transfer contents to overlapping memory blocks

PROGRAMS FOR TRAINEES

- 31. Add parity bit to 7-bit ASCII characters
- 32. Find the number of negative, zero and positive numbers
- 33. Inserting string in a given array of characters
- 34. Deleting string in a given array of characters
- 35. Multiply two eight bit numbers with shift and add method
- 36. Divide 16-bit number with 8-bit number using shifting technique
- 37. Sub routine to perform the task of DAA
- 38. Program to test RAM
- 39. **Program to generate fibonacci number**
- 40. Generate a delay of 0.4 seconds
- 41. Arrange in DESCENDING Order
- 42. **Data transfer from one memory block to other memory block.**
- 43. Find the factorial of a number
- 44. Find the Square Root of a given number
- 45. Split a HEX data into two nibbles and store it

- 46. Add two 4-digit BCD numbers
- 47. <u>Subtraction of two BCD numbers</u>
- 48. Multiply two 2-digit BCD numbers

PROGRAMS FOR EXPERTS

a.PROGRAMS TO WORK WITH COUNTERS

- 49. Generate and display binary up counter
- 50. Generate and display BCD up counter with frequency 1Hz
- 51. Generate and display BCD down counter
- 52. Generate and display the contents of decimal counter
- 53. **Debug the delay routine**

b.PROGRAMS IN CODE CONVERSION

- 54. **<u>2-Digit BCD to binary conversion.</u>**
- 55. Binary to BCD conversion
- 56. Find the 7-segment codes for given numbers
- 57. Find the ASCII character
- 58. ASCII to Decimal Conversion
- 59. **HEX to Decimal conversion**
- 60. HEX to binary conversion

c.PROGRAMS IN INTERFACING & APPLICTIONS

- I. Interfacing with IC 8251(Serial Communcation/USART)
- 61. Output byte from SOD pin
- 62. Generate square wave from SOD pin
- 63. Receive ASCII character through SID pin
- 64. <u>Transmit message using 8251</u>
- 65. **<u>Receive message using 8251</u>**

II. Interfacing with IC 8255(Programmable Periperal Interface - PPI)

- 66. <u>Initialize 8255</u>
- 67. Blink port C bit 0 of 8255
- 68. Flashing of LEDs
- 69. Traffic Light Control
- 70. Stepper Motor Control
- 71. <u>Keyboard interface(64-key-matrix-keyboard)</u>
- 72. <u>Seven Segment Display Interface (Eight Digits)</u>

III. Interfacing with IC 8279 (Keyboard and Display Controller)

- 73. 8 x 8 Keyboard Interface(Without Interrupt signal)
- 74. 8 x 8 Keyboard Interface(With Interrupt signal)
- 75. <u>8 x 4 Matrix Keyboard Interface</u>
- 76. Interfacing of eight 7-segment digits
- 77. Interfacing of 4x4 matrix keyboard and 4 digit 7 segment display
- 78. Roll a message 'HELL0123'
- 79. Roll your NAME

1 Statement: Store the data byte 32H into memory location 4000H.

Program 1:

MVI A, 52H	: Store 32H in the accumulator
STA 4000H	: Copy accumulator contents at address 4000H
HLT	: Terminate program execution

Program 2:

LXI H	: Load HL with 4000H
MVI M	: Store 32H in memory location pointed by HL register pair
(4000H)	
HLT	: Terminate program execution

The result of both programs will be the same. In program 1 direct addressing instruction is used, whereas in program 2 indirect addressing instruction is used.

2 Statement: Exchange the contents of memory locations 2000H and 4000H

Program 1:

LDA 2000H MOV B A	: Get the contents of memory location 2000H into accumulator
I DA 4000H	' Get the contents of memory location 4000Hinto accumulator
STA 2000H	Store the contents of accumulator at address 2000H
MOV A R	· Get the saved contents back into A register
STA 4000H	: Store the contents of accumulator at address 4000H
Program 2:	
I XT H 2000H	· Initialize HI register pair as a pointer to memory
location 2000H	i initianze ne register pan as a pointer to memory
I XT D 4000H	: Initialize DF register pair as a pointer to memory
location 4000H	i initianze be register pan as a pointer to memory
MOV B, M	: Get the contents of memory location 2000H into B
register.	,
LDAX D	: Get the contents of memory location 4000H into A register.
ΜΟΥ Μ, Α	: Store the contents of A register into memory location
2000Н.	······································
MOV A, B	: Copy the contents of B register into accumulator.
STAX D	: Store the contents of A register into memory location
4000H.	·····//···//
HLT	: Terminate program execution.

In Program 1, direct addressing instructions are used, whereas in Program 2, indirect addressing instructions are used.

3 Statement: Add the contents of memory locations **4000H** and **4001H** and place the result in memory location **4002H**. *Sample problem*

(4000H) = 14H (4001H) = 89H Result = 14H + 89H = 9DH

Source program

LXI H 4000H	: HL points 4000H
MOV A, M	: Get first operand
INX H	: HL points 4001H
ADD M	: Add second operand
INX H	: HL points 4002H
MOV M, A	: Store result at 4002H
HLT	: Terminate program execution



4 Statement: Subtract the contents of memory location 4001H from the memory location 2000H and place the result in memory location 4002H. *Program - 4: Subtract two 8-bit numbers*

Sample problem:

(4000H)	= 51H
(4001H)	= 19H
Result	= 51H - 19H = 38H

Source program:

LXI H, 4000H	: HL points 4000H
MOV A, M	: Get first operand
INX H	: HL points 4001H
SUB M	: Subtract second operand
INX H	: HL points 4002H
MOV M, A	: Store result at 4002H.
HLT	: Terminate program execution



5 Statement: Add the 16-bit number in memory locations 4000H and 4001H to the 16-bit number in memory locations 4002H and 4003H. The most significant eight bits of the two numbers to be added are in memory locations 4001H and 4003H. Store the result in memory locations 4004H and 4005H with the most significant byte in memory location 4005H

Program - 5.a: Add two 16-bit numbers - Source Program 1

Sample problem:

(4000H) = 15H (4001H) = 1CH (4002H) = B7H (4003H) = 5AH Result = 1C15 + 5AB7H = 76CCH (4004H) = CCH (4005H) = 76H

Source Program	1:
LHLD 4000H	: Get first 16-bit number in HL
XCHG	: Save first I6-bit number in DE
LHLD 4002H	: Get second 16-bit number in HL
MOV A, E	: Get lower byte of the first number
ADD L	: Add lower byte of the second number
MOV L, A	: Store result in L register
MOV A, D	: Get higher byte of the first number
ADC H	: Add higher byte of the second number with CARRY
MOV H, A	: Store result in H register
SHLD 4004H	: Store I6-bit result in memory locations 4004H and 4005H.
HLT	: Terminate program execution

Program - 5b: Add two 16-bit numbers - Source Program 2

Source program 2:

LHLD 4000H	: Get first I6-bit number
XCHG	: Save first I6-bit number in DE
LHLD 4002H	: Get second I6-bit number in HL
DAD D	: Add DE and HL
SHLD 4004H	: Store I6-bit result in memory locations 4004H and 4005H.
HLT	: Terminate program execution

NOTE: In program 1, eight bit addition instructions are used (ADD and ADC) and addition is performed in two steps. First lower byte addition using ADD instruction and then higher byte addition using ADC instruction.In program 2, 16-bit addition instruction (DAD) is used.



6 Statement: Add the contents of memory locations 40001H and 4001H and place the result in the memory locations 4002Hand 4003H. *Sample problem:*

(4000H) = 7FH (400IH) = 89H Result = 7FH + 89H = 108H (4002H) = 08H (4003H) = 0IH

Source program:

LXI H, 4000H	:HL Points 4000H
MOV A, M	:Get first operand
INX H	:HL Points 4001H
ADD M	:Add second operand
INX H	:HL Points 4002H
MOV M, A	Store the lower byte of result at 4002H:
MVIA, 00	Initialize higher byte result with 00H:
ADC A	:Add carry in the high byte result
INX H	:HL Points 4003H
MOV M, A	Store the higher byte of result at 4003H:
HLT	:Terminate program execution
	FLOWCHART



7 Statement: Subtract the 16-bit number in memory locations 4002H and 4003H from the 16-bit number in memory locations 4000H and 4001H. The most significant eight bits of the two numbers are in memory locations 4001H and 4003H. Store the result in memory locations 4004H and 4005H with the most significant byte in memory location 4005H.

Sample problem

(4000H) = 19H (400IH) = 6AH (4004H) = I5H (4003H) = 5CH Result = 6A19H - 5C15H = OE04H (4004H) = 04H (4005H) = OEH

Source program:

LHLD 4000H	: Get first 16-bit number in HL
XCHG	: Save first 16-bit number in DE
LHLD 4002H	: Get second 16-bit number in HL
MOV A, E	: Get lower byte of the first number
SUB L	: Subtract lower byte of the second number
MOV L, A	: Store the result in L register
MOV Á, D	: Get higher byte of the first number
SBB H	: Subtract higher byte of second number with borrow
ΜΟΥ Η, Α	: Store I6-bit result in memory locations 4004H and 4005H.
SHLD 4004H	: Store I6-bit result in memory locations 4004H and 4005H.
HLT	: Terminate program execution.
	FLOWCHART



8 Statement: Find the I's complement of the number stored at memory location 4400H and store the complemented number at memory location 4300H. *Sample problem:*

(4400H) = 55H Result = (4300B) = AAB Source program:

LDA 4400B	: Get the number
СМА	: Complement number
STA 4300H	: Store the result
HLT	: Terminate program execution



9 Statement: Find the 2's complement of the number stored at memory location 4200H and store the complemented number at memory location 4300H. Sample problem:

(4200H) = 55H Result = (4300H) = AAH + 1 = ABH

Source program:

LDA 4200H	: Get the number
СМА	: Complement the number
ADI, 01 H	: Add one in the number
STA 4300H	: Store the result
HLT	: Terminate program execution



10 Statement: Pack the two unpacked BCD numbers stored in memory locations 4200H and 4201H and store result in memory location 4300H. Assume the least significant digit is stored at 4200H.

Sample problem: (4200H) = 04 (4201H) = 09 Result = (4300H) = 94

Source program

LDA 4201H	: Get the Most significant BCD digit
RLC	
RLC	
RLC	
RLC	: Adjust the position of the second digit (09 is changed to 90)
ANI FOH	: Make least significant BCD digit zero
MOV C, A	: store the partial result
LDA 4200H	: Get the lower BCD digit
ADD C	: Add lower BCD digit
STA 4300H	: Store the result
HLT	: Terminate program execution

NOTE:

BCD NO.: The numbers "0 to 9" are called BCD (Binary Coded Decimal) numbers. A decimal number 29 can be converted into BCD number by splitting



11 Statement: Two digit BCD number is stored in memory location 4200H. Unpack the BCD number and store the two digits in memory locations 4300H and 4301H such that memory location 4300H will have lower BCD digit.

Sample problem

(4200H) = 58Result = (4300H) = 08 and (4301H) = 05Source program LDA 4200H : Get the packed BCD number : Mask lower nibble ANI FOH RRC RRC RRC : Adjust higher BCD digit as a lower digit RRC STA 4301H : Store the partial result LDA 4200H : .Get the original BCD number ANI OFH : Mask higher nibble STA 4201H : Store the result HLT : Terminate program execution Start Get the packed BCD number Mask lower BCD digit Adjust higher BCD digit to the lower BCD digit Store the adjusted result Get the original BCD number Mask higher BCD digit Store the result END

12 Statement:Read the program given below and state the contents of all registers after the execution of each instruction in sequence. *Main program:*

4000H	LXI SP, 27FFH
4003H	LXI H, 2000H
4006H	LXI B, 1020H
4009H	CALL SUB
400CH	HLT

Subroutine program:

4100H	SUB: PUSH B
4101H	PUSH H
4102H	LXI B, 4080H
4105H	LXI H, 4090H
4108H	SHLD 2200H
4109H	DAD B
410CH	РОР Н
410DH	POP B
410EH	RET

Ser.	Instructions			Regi	isters	conter	uts in 1	Hex			Memory locations
No.		A	в	с	D	E	н	L	SP	РС	(addresses are in HEX)
1	LXI SP ,27FF	x	x	x	x	x	x	x	27FF	4003	
2	LXI H,2000	x	x	x	x	х	20	00	27FF	4006	
3	LXI 8,1020	x	10	20	x	х	20	00	27FF	4009	
4	CALL SUB	x	10	20	x	х	20	00	27F O	4100	(27FE 40, 27FD -0C)
5	PU SH B	x	10	20	x	x	20	00	27 FB	4101	(27Fe-10, 27FB-20)
6	PU SH H	x	10	20	x	x	20	00	27F9	4102	(27FA 20, 27F9 -00)
7	LXI B,4080	x	40	80	x	х	20	00	27F9	4105	
8	LXI H,4090	х	40	80	х	х	40	90	27F9	4108	
9	DAD B	x	40	80	x	х	81	10	27F9	4109	
10	SHLD 2200	x	40	80	х	х	81	10	27F9	410C	(220010, 2201 - 81)
11	рор н	x	40	80	x	х	20	00	27 FB	4100	
12	POP B	x	10	20	x	х	20	00	27FD	410E	
13	RET	х	10	20	х	х	20	00	27FF	400C	
14	HLT	х	10	20	х	х	20	00	27FF	4000	

13 Statement:Write a program to shift an eight bit data four bits right. Assume that data is in register C. *Source program:*





Statement:Write a program to shift a 16 bit data, 1 bit right. Assume that data is in BC register pair. Source program:

MOV A, B RAR MOV B, A MOV A, C RAR MOV C, A HLT



14 Statement: Program to shift a 16-bit data 1 bit left. Assume data is in the HL register pair. Source program:

DAD H : Adds HL data with HL data HL= 1025 = 0001 0000 0010 0101 HL = 0001 0000 0010 0101 +HL = 0001 0000 0010 0101 Result = 0010 0000 0100 1010

15 Statement: Write a set of instructions to alter the contents of flag register in 8085.

PUSH PSW	: Save flags on stack
РОР Н	: Retrieve flags in 'L'
MOV A, L	: Flags in accumulator
СМА	: Complement accumulator
MOV L, A	: Accumulator in 'L'
PUSH H	: Save on stack
POP PSW	: Back to flag register
HLT	:Terminate program execution

16 Statement: Calculate the sum of series of numbers. The length of the series is in memory location 4200H and the series begins from memory location 4201H.

a. Consider the sum to be 8 bit number. So, ignore carries. Store the sum at memory location 4300H.

b. Consider the sum to be 16 bit number. Store the sum at memory locations 4300H and 4301H.

a. Sample problem

4200H = 04H 4201H = 10H 4202H = 45H 4203H = 33H 4204H = 22H Result = 10 +41 + 30 + 12 = H 4300H = H

Source program:

LDA 4200H	
ΜΟΥ Ϲ, Α	: Initialize counter
SUB A	: sum = 0
LXI H, 420IH	: Initialize pointer
BACK: ADD M	: SUM = SUM + data
INX H	: increment pointer
DCR C	: Decrement counter
JNZ BACK	: if counter 0 repeat
STA 4300H	: Store sum
HLT	: Terminate program execution

FLOWCHART



b. Sample problem

```
4200H = 04H

420IH = 9AH

4202H = 52H

4203H = 89H

4204H = 3EH

Result = 9AH + 52H + 89H + 3EH = H

4300H = B3H Lower byte

4301H = 0IH Higher byte
```

Source program:

LDA 4200H	
ΜΟΥ Ϲ, Α	: Initialize counter
LXI H, 4201H	: Initialize pointer
SUB A	:Sum low = 0
MOV B, A	: Sum high = 0
BACK: ADD M	: Sum = sum + data
JNC SKIP	
INR B	: Add carry to MSB of SUM
SKIP: INX H	: Increment pointer
DCR C	: Decrement counter
JNZ BACK	: Check if counter 0 repeat
STA 4300H	: Store lower byte
MOV A, B	-
STA 4301H	: Store higher byte
HLT	:Terminate program execution

17 Statement: Multiply two 8-bit numbers stored in memory locations 2200H and 2201H by repetitive addition and store the result in memory locations 2300H and 2301H.

Sample problem:

(2200H) = 03H (2201H) = B2H Result = B2H + B2H + B2H = 216H = 216H (2300H) = 16H (2301H) = 02H

Source program

LDA 2200H	
MOV E, A	
MVI D, 00	: Get the first number in DE register pair
LDA 2201H	
ΜΟΥ Ϲ, Α	: Initialize counter
LX I H, 0000 H	: Result = 0
BACK: DAD D	: Result = result + first number
DCR C	: Decrement count
JNZ BACK	: If count 0 repeat
SHLD 2300H	: Store result
HLT	: Terminate program execution



18 Statement:Divide 16 bit number stored in memory locations 2200H and 2201H by the 8 bit number stored at memory location 2202H. Store the quotient in memory locations 2300H and 2301H and remainder in memory locations 2302H and 2303H. Sample problem

```
(2200H) = 60H
   (2201H) = A0H
   (2202H) = I2H
        Result = A060H/12H = 8E8H Quotient and 10H remainder
   (2300H) = E8H
    (2301H) = 08H
   (2302H = 10H)
   (2303H) 00H
Source program
   LHLD 2200H
                       : Get the dividend
                      : Get the divisor
   LDA 2202H
   MOV C, A
   LXI D, 0000H
                        : Quotient = 0
BACK: MOV A, L
   SUB C
                      : Subtract divisor
   MOV L, A
JNC SKIP
                    : Save partial result
                    : if CY 1 jump
               : Subtract borrow of previous subtraction
   DCR H
SKIP: INX D
                        : Increment quotient
   MOV A, H
                  : Check if dividend < divisor
   CPI, 00
   JNZ BACK
                     : if no repeat
   MOV A, L
   CMP C
   JNC BACK
                       : Store the remainder
   SHLD 2302H
   XCHG
   SHLD 2300H
                        : Store the quotient
   HLT
                    : Terminate program execution
```



19 Statement: Find the number of negative elements (most significant bit 1) in a block of data. The length of the block is in memory location 2200H and the block itself begins in memory location 2201H. Store the number of negative elements in memory location 2300H Sample problem (2200H) = 04H(2201H) = 56H(2202H) = A9H(2203H) = 73H(2204H) = 82HResult = 02 since 2202H and 2204H contain numbers with a MSB of 1. Source program LDA 2200H MOV C, A : Initialize count MVI B, 00 : Negative number = 0 LXI H, 2201H : Initialize pointer : Get the number BACK: MOV A, M ANI 80H : Check for MSB JZ SKIP : If MSB = 1INR B : Increment negative number count SKIP: INX H : Increment pointer DCR C : Decrement count JNZ BACK : If count 0 repeat MOV A, B STA 2300H : Store the result HLT : Terminate program execution **FLOWCHART** Start Neg number = 0 Pointer = 2201H Count = (2200H) ls No MBS =1 Yes Neg number =Neg number+ 1 Pointer = Pointer + 1 Count = Count - 1ls No Count = 0 ? Yes (2300H) = Neg number End

20 Statement:Find the largest number in a block of data. The length of the block is in memory location 2200H and the block itself starts from memory location 2201H. Store the maximum number in memory location 2300H. Assume that the numbers in the block are all 8 bit unsigned binary numbers.

```
Sample problem
   (2200H) = 04
   (2201H) = 34H
   (2202H) = A9H
   (2203H) = 78H
   (2204H) = 56H
        Result = (2202H) = A9H
Source program
        LDA 2200H
        MOV C, A
                         : Initialize counter
        XRA A
                          : Maximum = Minimum possible value = 0
        LXI H, 2201H
                        : Initialize pointer
   BACK: CMP M
                             : Is number> maximum
        JNC SKIP
                         : Yes, replace maximum
        MOV A, M
   SKIP: INX H
        DCR C
        JNZ BACK
                          : Store maximum number
        STA 2300H
        HLT
                        : Terminate program execution
```



21 Statement:Write a program to count number of I's in the contents of D register and store the count in the B register. *Source program:*



22 Statement:Write a program to sort given 10 numbers from memory location 2200H in the ascending order. *Source program:*

MVI B, 09	: Initialize counter
START	: LXI H, 2200H: Initialize memory pointer
MVI C, 09H	: Initialize counter 2
BACK: MOV A, M	: Get the number
INX H	: Increment memory pointer
СМР М	: Compare number with next number
JC SKIP	: If less, don't interchange
JZ SKIP	: If equal, don't interchange
MOV D, M	
MOV M, A	
DCX H	
MOV M, D	
INX H	: Interchange two numbers
SKIP:DCR C	: Decrement counter 2
JNZ BACK	: If not zero, repeat
DCR B	: Decrement counter 1
JNZ START	
HLT	: Terminate program execution



23 Statement:Calculate the sum of series of even numbers from the list of numbers. The length of the list is in memory location 2200H and the series itself begins from memory location 2201H. Assume the sum to be 8 bit number so you can ignore carries and store the sum at memory location 2210H. Sample problem:

2200H= 4H 2201H= 20H 2202H= I5H 2203H= I3H 2204H= 22H Result 22I0H= 20 + 22 = 42H = 42H

Source program:

LDA 2200H MOV C, A MVI B, 00H LXI H, 2201H	: Initialize counter : sum = 0 : Initialize pointer
BACK: MOV A, M	: Get the number
ANI OlH	: Mask Bit I to Bit7
JNZ SKIP	: Don't add if number is ODD
MOV A, B	: Get the sum
ADD M	: SUM = SUM + data
MOV B, A	: Store result in B register
SKIP: INX H	: increment pointer
DCR C	: Decrement counter
JNZ BACK	: if counter 0 repeat
STA 2210H	: store sum
HLT	: Terminate program execution



24 Statement:Calculate the sum of series of odd numbers from the list of numbers. The length of the list is in memory location 2200H and the series itself begins from memory location 2201H. Assume the sum to be 16-bit. Store the sum at memory locations 2300H and 2301H. Sample problem:

2200H = 4H 2201H= 9AH 2202H= 52H 2203H= 89H 2204H= 3FH Result = 89H + 3FH = C8H 2300H= H Lower byte 2301H = H Higher byte

Source program

LDA 2200H	
ΜΟΥ Ϲ, Α	: Initialize counter
LXI H, 2201H	: Initialize pointer
MVI E, 00	: Sum low = 0
MOV D, E	: Sum high = 0
BACK: MOV A, M	: Get the number
ANI OIH	: Mask Bit 1 to Bit7
JZ SKIP	: Don't add if number is even
MOV A, E	: Get the lower byte of sum
ADD M	: Sum = sum + data
MOV E, A	: Store result in E register
JNC SKIP	-
INR D	: Add carry to MSB of SUM
SKIP: INX H	: Increment pointer



25 Statement:Find the square of the given numbers from memory location 6100H and store the result from memory location 7000H. *Source Program:*



26 Statement: Search the given byte in the list of 50 numbers stored in the consecutive memory locations and store the address of memory location in the memory locations 2200H and 2201H. Assume byte is in the C register and starting address of the list is 2000H. If byte is not found store 00 at 2200H and 2201H. *Source program:*



27 Statement: Two decimal numbers six digits each, are stored in BCD package form. Each number occupies a sequence of byte in the memory. The starting address of first number is 6000H Write an assembly language program that adds these two numbers and stores the sum in the same format starting from memory location 6200H.

Source Program:

LXI H, 6000H	: Initialize pointer I to first number
LXI D, 6100H	: Initialize pointer2 to second number
LXI B, 6200H	: Initialize pointer3 to result
STC	-
СМС	: Carry = 0
BACK: LDAX D	: Get the digit
ADD M	: Add two digits
DAA	: Adjust for decimal
STAX.B	: Store the result
INX H	: Increment pointer 1
INX D	: Increment pointer2
INX B	: Increment result pointer
MOV A, L	
СРІ 06Н	: Check for last digit
JNZ BACK	: If not last digit repeat
HLT	: Terminate program execution



28 Statement: Add 2 arrays having ten 8-bit numbers each and generate a third array of result. It is necessary to add the first element of array 1 with the first element of array-2 and so on. The starting addresses of array I, array2 and array3 are 2200H, 2300H and 2400H, respectively. *Source Program:*



: Initialize memory pointer 1 : Initialize memory pointer 2 : Initialize result pointer : Get the number from array 2 : Add it with number in array 1 : Store the addition in array 3 : Increment pointer 1 : Increment pointer2 : Increment result pointer

: Check pointer 1 for last number : If not, repeat : Ston 29 Statement: Write an assembly language program to separate even numbers from the given list of 50 numbers and store them in the another list starting from 2300H. Assume starting address of 50 number list is 2200H. *Source Program:*



: Initialize memory pointer I : Initialize memory pointer2 : Initialize counter : Get the number : Check for even number : If ODD, don't store : Get the number : Store the number in result list : Increment pointer 2 : Increment pointer I : Decrement counter : If not zero, repeat : Stop
30 Statement: Write assembly language program with proper comments for the following:

A block of data consisting of 256 bytes is stored in memory starting at 3000H. This block is to be shifted (relocated) in memory from 3050H onwards. Do not shift the block or part of the block anywhere else in the memory. *Source Program:*

Two blocks (3000 - 30FF and 3050 - 314F) are overlapping. Therefore it is necessary to transfer last byte first and first byte last.

: Initialize counter
: Initialize source memory pointer 3l4FH
: Initialize destination memory pointer
: Get byte from source memory block
: Store byte in the destination memory block
: Decrement source memory pointer
: Decrement destination memory pointer
: Decrement counter
: If counter 0 repeat
: Stop execution

31 Statement: Add even parity to a string of 7-bit ASCII characters. The length of the string is in memory location 2040H and the string itself begins in memory location 2041H. Place even parity in the most significant bit of each character. *Source Program:*

LXI H, 2040H	
ΜΟΥ С ,Μ	: Counter for character
REPEAT:INX H	: Memory pointer to character
ΜΟΥ Α, Μ	: Character in accumulator
ORA A	: ORing with itself to check parity.
JPO PAREVEN	: If odd parity place
ORI 80H	even parity in D7 (80).
PAREVEN:MOV M , A	: Store converted even parity character.
DCR C	: Decrement counter.
JNZ REPEAT	: If not zero go for next character.
HLT	: Terminate program execution



32 Statement: A list of 50 numbers is stored in memory, starting at 6000H. Find number of negative, zero and positive numbers from this list and store these results in memory locations 7000H, 7001H, and 7002H respectively. *Source Program:*

: Initialize memory pointer
: Initialize number counter
: Initialize negative number counter
: Initialize zero number counter
: Get the number
: If number = 0
: Goto zeronum
: If MSB of number = 1i.e. if
number is negative goto NEGNUM
: otherwise increment positive number counter
•
: Increment zero number counter
: Increment negative number counter
: Increment memory pointer
: Increment number counter
: If number counter = 5010 then
: Store otherwise check next number
: Initialize memory pointer.
: Store negative number.
-
: Store zero number.
: Store positive number.
: Terminate execution



33 Statement:Write an 8085 assembly language program to insert a string of four characters from the tenth location in the given array of 50 characters. *Solution:*

Step 1: Move bytes from location 10 till the end of array by four bytes downwards.

Step 2: Insert four bytes at locations 10, 11, 12 and 13.

Source Program:

LXI H, 2l31H	: Initialize pointer at the last location of array.
LXI D, 2 35H	: Initialize another pointer to point the last location of
array after insertio)n.
AGAIN: MOV A, M	: Get the character
STAX D	: Store at the new location
DCX D	: Decrement destination pointer
DCX H	: Decrement source pointer
MOV A, L	: [check whether desired
СРІ 05Н	bytes are shifted or not]
JNZ AGAIN	: if not repeat the process
INX H	: adjust the memory pointer
LXI D, 2200H	: Initialize the memory pointer to point the string to be
inserted	
REPE: LDAX D	: Get the character
MOV M, A	: Store it in the array
INX D	: Increment source pointer
INX H	: Increment destination pointer
MOV A, E	: [Check whether the 4 bytes
CPI 04	are inserted]
JNZ REPE	: if not repeat the process
HLT	: stop

34 Statement:Write an 8085 assembly language program to delete a string of 4 characters from the tenth location in the given array of 50 characters. *Solution: Shift bytes from location 14 till the end of array upwards by 4 characters i.e. from location 10 onwards.*

Source Program:

LXI H, 2l0DH array.	Initialize source memory pointer at the 14thlocation of the:
LXI D, 2l09H arrav.	: Initialize destn memory pointer at the 10th location of the
ΜΟΥ Α, Μ	: Get the character
STAX D	: Store character at new location
INX D	: Increment destination pointer
INX H	: Increment source pointer
MOV A, L	: [check whether desired
CPI 32H	bytes are shifted or not]
JNZ REPE	: if not repeat the process
HLT	: stop

35 Statement:Multiply the 8-bit unsigned number in memory location 2200H by the 8-bit unsigned number in memory location 2201H. Store the 8 least significant bits of the result in memory location 2300H and the 8 most significant bits in memory location 2301H.

Sample problem:

(2200)	= 1100 (OCH)
(2201)	= 0101 (05H)
Multiplicand	= 1100 (1210)
Multiplier	= 0101 (510)
Result	= 12 x 5 = (6010)

Source program

: Initialize the memory pointer
: Get multiplicand
: Extend to 16-bits
: Increment memory pointer
: Get multiplier
: Product = 0
: Initialize counter with count 8
: Product = product x 2
: Is carry from multiplier 1 ?
: Yes, Product =Product + Multiplicand
: Is counter = zero
: no, repeat
: Store the result
: End of program



36 Statement:Divide the 16-bit unsigned number in memory locations 2200H and 2201H (most significant bits in 2201H) by the B-bit unsigned number in memory location 2300H store the quotient in memory location 2400H and remainder in 2401H.

Assumption: The most significant bits of both the divisor and dividend are zero.

Source program

MVI E, 00	: Quotient = 0
LHLD 2200H	: Get dividend
LDA 2300	: Get divisor
MOV B, A	: Store divisor
MVI C, 08	: Count = 8
NEXT: DAD H	: Dividend = Dividend x 2
MOV A, E	
RLC	
MOV E, A	: Quotient = Quotient x 2
MOV A, H	
SUB B	: Is most significant byte of Dividend > divisor
JC SKIP	: No, go to Next step
MOV H, A	: Yes, subtract divisor
INR E	: and Quotient = Quotient + 1
SKIP:DCR C	: Count = Count - 1
JNZ NEXT	: Is count =0 repeat
MOV A, E	
STA 2401H	: Store Quotient
Mov A, H	
STA 2410H	: Store remainder
HLT	: End of program.



37 Statement:Assume the DAA instruction is not present. Write a sub routine which will perform the same task as DAA. Sample Problem:

Execution of DAA instruction:

1. If the value of the low order four bits (03-00) in the accumulator is greater than 9 or if auxiliary carry flag is set, the instruction adds 6 '(06) to the low-order four bits.

2. If the value of the high-order four bits (07-04) in the accumulator is greater than 9 or if carry flag is set, the instruction adds 6(06) to the high-order four bits.

Source Program:

LXI SP, 27FFH	: Initialize stack pointer
MOV E, A	: Store the contents of accumulator
ANI OFH	: Mask upper nibble
СРІ ОА Н	: Check if number is greater than 9
JC SKIP	: if no go to skip
MOV A, E	: Get the number
ADI 06H	: Add 6 in the number
JMP SECOND	: Go for second check
SKIP: PUSH PSW	: Store accumulator and flag contents in stack
POP B	: Get the contents of accumulator in B register and flag
register contents in	C register
MOV A, C	: Get flag register contents in accumulator
ANI 10H	: Check for bit 4
JZ SECOND	: if zero, go for second check
MOV A, E	: Get the number
ADI 06	: Add 6 in the number
SECOND: MOV E, A	: Store the contents of accumulator
ANI FOH	: Mask lower nibble
RRC	
RRC	
RRC	
RRC	: Rotate number 4 bit right
СРІ ОАН	: Check if number is greater than 9
JC SKIPI	: if no go to skip 1
MOV A, E	: Get the number
ADI 60 H	: Add 60 H in the number
JMP LAST	: Go to last
SKIP1: JNC LAST	: if carry flag = 0 go to last
MOV A, E	: Get the number
ADI 60 H	: Add 60 H in the number
LAST: HLT	

Note: To check auxiliary carry flag it is necessary to get the flag register contents in one of the registers and then we can check the auxiliary carry flag by checking bit 4 of that register. To get the flag register contents in any general purpose register we require stack operation and therefore stack pointer is initialized at the beginning of the source program.



38 Statement: To test RAM by writing '1' and reading it back and later writing '0' (zero) and reading it back. RAM addresses to be checked are 40FFH to 40FFH. In case of any error, it is indicated by writing 01H at port 10H. Source Program:

LXI H, 4000H	: Initialize memory pointer
BACK: MVI M, FFH	: Writing '1' into RAM
ΜΟΥ Α, Μ	: Reading data from RAM
CPI FFH	: Check for ERROR
JNZ ERROR	: If yes go to ERROR
INX H	: Increment memory pointer
ΜΟΥ Α, Η	
CPI SOH	: Check for last check
JNZ BACK	: If not last, repeat
LXI H, 4000H	: Initialize memory pointer
BACKI: MVI M, OOH	: Writing '0' into RAM
MOV A, M	: Reading data from RAM
СРІ ООН	: Check for ERROR
INX H	: Increment memory pointer
ΜΟΥ Α, Η	
CPI SOH	: Check for last check
JNZ BACKI	: If not last, repeat
HLT	: Stop Execution

39 Statement:Write an assembly language program to generate fibonacci number.

Source Program:

JNZ BACK

MVI D, COUNT	: Initialize counter
MVI B, 00	: Initialize variable to store previous number
MVI C, 01	: Initialize variable to store current number
MOV A, B	:[Add two numbers]
BACK: ADD C	:[Add two numbers]
MOV B, C	: Current number is now previous number
ΜΟΥ Ϲ, Α	: Save result as a new current number
DCR D	: Decrement count
JNZ BACK	: if count 0 go to BACK
HLT	: Stop.

40 Statement: Write a program to generate a delay of 0.4 sec if the crystal frequency is 5 MHz.

Calculation: In 8085, the operating frequency is half of the crystal frequency, *ie.Operating frequency* = 5/2 = 2.5 MHz Time for one T -state = Number of T-states required = $= 1 \times 106$ Source Program: LXI B, count: 16 - bit countBACK: DCX B: Decrement count MOV A, C ORA B : Logically OR Band C : If result is not zero repeat

41 Statement: Arrange an array of 8 bit unsigned no in descending order

Source Program:

START:MVI B, 00	; Flag = 0
LXI H, 4150	; Count = length of array
MOV C, M	
DCR C	; No. of pair = count -1
INX H	; Point to start of array
LOOP:MOV A, M	; Get kth element
INX H	
СМР М	; Compare to (K+1) th element
JNC LOOP 1	; No interchange if kth >= (k+1) th
MOV D, M	; Interchange if out of order
ΜΟΥ Μ, Α	;
DCR H	
MOV M, D	
INX H	
MVI B, 01H	; Flag=1
LOOP 1:DCR C	; count down
JNZ LOOP	;
DCR B	; is flag = 1?
JZ START	; do another sort, if yes
HLT	; If flag = 0, step execution

42 Statement: Transfer ten bytes of data from one memory to another memory block. Source memory block starts from memory location 2200H where as destination memory block starts from memory location 2300H. *Source Program:*

LXI H, 4150	: Initialize memory pointer
MVI B, 08	: count for 8-bit
MVI A, 54	
LOOP : RRC	
JC LOOP1	
MVI M, 00	: store zero it no carry
ЈМР СОММО	N
LOOP2: MVI M, 0	<i>1 : store one if there is a carry</i>
COMMON: INX H	-
DCR B :	check for carry
JNZ LOOP	
HLT	: Terminate the program

43 Statement: Program to calculate the factorial of a number between 0 to 8

Source program

LXI SP, 27FFH	; Initialize stack pointer
LDA 2200H	; Get the number
СРІ 02Н	; Check if number is greater than 1
JC LAST	, 2
MVI D, OOH	; Load number as a result
MOV É, A	,
DCR A	
MOV C,A	; Load counter one less than number
CALL FACTO	; Call subroutine FACTO
ХСНБ	; Get the result in HL
SHLD 2201H	: Store result in the memory
JMP END	, ,
LAST: LXI H, 000IH	; Store result = 01
END: SHLD 2201H	,
HLT	
Subroutine Program	
FACTO:LXI H, 0000H	4
MOV B, C	; Load counter
BACK: DAD D	,
DCR B	
JNZ BACK	; Multiply by successive addition
ХСНБ	; Store result in DE
DCR C	; Decrement counter
CNZ FACTO	; Call subroutine FACTO
RET	; Return to main program



44 Statement:Write a program to find the Square Root of an 8 bit binary number. The binary number is stored in memory location 4200H and store the square root in 4201H.

Source Program:

LDA 4200H	: Get the given data(Y) in A register
MOV B,A	: Save the data in B register
MVI C,02H	: Call the divisor(02H) in C register
CALL DIV	: Call division subroutine to get initial value(X) in D-
reg	
REP: MOV E,D	: Save the initial value in E-reg
MOV A, B	: Get the dividend(Y) in A-reg
MOV C,D	: Get the divisor(X) in C-reg
CALL DIV	: Call division subroutine to get initial value(Y/X) in D-
reg	
MOV A, D	: Move Y/X in A-reg
ADD E	: Get the((Y/X) + X) in A-reg
MVI C, 02H	: Get the divisor(02H) in C-reg
CALL DIV	: Call division subroutine to get ((Y/X) + X)/2 in D-
reg.This is XNEW	
MOV A, E	: Get Xin A-reg
CMP D	: Compare X and XNEW
JNZ REP	: If XNEW is not equal to X, then repeat
STA 4201H	: Save the square root in memory
HLT	: Terminate program execution
	· •

Subroutine:

DIV: MVI D, OOH	: Clear D-reg for Quotient
NEXT:SUB C	: Subtact the divisor from dividend
INR D	: Increment the quotient
СМР С	: Repeat subtraction until the
JNC NEXT	: divisor is less than dividend
RET	: Return to main program

Note: The square root can be taken y an iterative technique. First, an initial value is assumed. Here, the initial value of square root is taken as half the value of given number. Te new value of square root is computed by using an expression XNEW = (X + Y/X)/2 where, X is the initial value of square root and Y is the given number. Then, XNEW is compared wit initial value. If they are not equal then the above process is repeated until X is equal to XNEW after taking XNEW as initial value. (i.e., X \leftarrow XNEW)



Flowchart subroutine



45 Statement:Write a simple program to Split a HEX data into two nibbles and store it in memory *Source Program:*

LXI H, 4200H	: Set pointer data for array
MOV B,M	: Get the data in B-reg
MOV A, B	: Copy the data to A-reg
ANI OFH	: Mask the upper nibble
INX H	: Increment address as 4201
ΜΟΥ Μ,Α	: Store the lower nibble in memory
MOV A, B	: Get the data in A-reg
ANI FOH	: Bring the upper nibble to lower nibble position
RRC	
RRC	
RRC	
RRC	
INX H	
ΜΟΥ Μ,Α	: Store the upper nibble in memory
HLT	: Terminate program execution

46 Statement: Add two 4 digit BCD numbers in HL and DE register pairs and store result in memory locations, 2300H and 2301H. Ignore carry after 16 bit. *Sample Problem:*

(HL) =3629 (DE) =4738 Step 1 : 29 + 38 = 61 and auxiliary carry flag = 1 :.add 06 61 + 06 = 67 Step 2 : 36 + 47 + 0 (carry of LSB) = 7D

Lower nibble of addition is greater than 9, so add 6. 7D + 06 = 83 Result = 8367

Source program

MOV A, L	: Get lower 2 digits of no. 1
ADD E	: Add two lower digits
DAA	: Adjust result to valid BCD
STA 2300H	: Store partial result
MOV A, H	: Get most significant 2 digits of number
ADC D	: Add two most significant digits
DAA	: Adjust result to valid BCD
STA 2301H	: Store partial result
HLT	: Terminate program execution.



47 Statement: Subtract the BCD number stored in E register from the number stored in the D register. Source Program:

MVI A,99H	
SUB E	: Find the 99's complement of subtrahend
INR A	: Find 100's complement of subtrahend
ADD D	: Add minuend to 100's complement of subtrahend
DAA	: Adjust for BCD
HLT	: Terminate program execution

Note: When two BCD numbers are subtracted, we can use DAA instruction for ajusting the result to BCD. Therefore, the subtraction of BCD number is carried out 10's complement or 100's complement.

The 10's complement of a decimal number is equal to the 99's complement plus 1. The 99's complement of a number can be found by subtracting the number from 99.

The steps for finding 100's complement BCD subtraction are :

- Find the 100's complement of subtrahend
- Add two numbers using BCD adition

48 Statement: Write an assembly language program to multiply 2 BCD numbers *Source Program:*

MVI C, Multiplier	: Load BCD multiplier
MVI B, 00	: Initialize counter
LXI H, 0000H	: Result = 0000
MVI E, multiplicand	: Load multiplicand
MVI D, 00H	: Extend to 16-bits
BACK: DAD D	: Result Result + Multiplicand
MOV A, L	: Get the lower byte of the result
ADI, OOH	-
DAA	: Adjust the lower byte of result to BCD.
MOV L, A	: Store the lower byte of result
MOV Á, H	: Get the higher byte of the result
ACI, OOH	
DAA	: Adjust the higher byte of the result to BCD
ΜΟΥ Η, Α	: Store the higher byte of result.
MOV A, B	: [Increment
ADI 01H	: counter
DAA	: adjust it to BCD and
MOV B,A	: store it]
СМР С	: Compare if count = multiplier
JNZ BACK	: if not equal repeat
HLT	: Stop

49 Statement:Write a program for displaying binary up counter. Counter should count numbers from 00 to FFH and it should increment after every 0.5 sec. Assume operating frequency of 8085 equal to 2MHz. Display routine is available. *Source Program:*

LXI SP, 27FFH	: Initialize stack pointer
ΜVΙ C, ΟΟΗ	: Initialize counter
BACK: CALL Display	: Call display subroutine
CALL Delay	: Call delay subroutine
INR C	: Increment counter
MOV A, C	
СРІ ООН	: Check counter is > FFH
JNZ BACK	: If not, repeat
HLT	: Stop

Delay Subroutine:

Delay: LXI B, count: Initialize countBACK: DCXD: Decrement countMOV A, EORA D: Logically OR D and EJNZ BACK: If result is not 0 repeatRET: Return to main program

ie.Operating frequency = 2 MHz

Time for one T -state = $\frac{1}{2MHz} = 0.5 \mu sec$ Number of T-states required = $\frac{\text{Required Time}}{\text{Time required for 1 T- state}} = \frac{0.5 sec}{0.5 \mu sec}$ = 1 x 10⁶ 1 × 10⁶ = 10 + (count - 1) × 24 + 21 1 × 10⁶ - 31

count = $\frac{1 \times 10^6 - 31}{24} + 1 \gg 41666_{10}$ **count** = 41666_{10} = A2C2H



Program flowchart

Delay routine flowchart



50 Statement:Write a program for displaying BCD up counter. Counter should count numbers from 00 to 99H and it should increment after every 1 sec. Assume operating frequency of 8085 equal to 3MHz. Display routine is available.

Source Program:

LXI SP, 27FFH	: Initialize stack pointer
ΜVΙ C, ΟΟΗ	: Initialize counter
BACK: CALL Display	: Call display subroutine
CALL Delay	: Call delay subroutine
MOV A, C	
ADI A, O 1	: Increment counter
DAA	: Adjust it for decimal
ΜΟΥ C, A	: Store count
CPI ,00	: Check count is > 99
JNZ BACK	: If not, repeat
HLT	: Stop
Delay Subroutine:	

Delay:MVI B, Multiplier-count : Initialize multiplier count BACK 1:LXI D, Initialize Count BACK: DCX D : Decrement count MOV A, E ORA D : Logically OR D and E JNZ BACK : If result is not a, repeat DCR B : Decrement multiplier count JNZ BACK 1 : If not zero, repeat RET : Return to main program. **Operating Frequency : 3MHz**

Time for one T - state = $\frac{1}{3MHz} = 0.333 \mu sec$ $\frac{\text{Required Time}}{\text{Time required for 1 T- state}} = 3 \times 10^6$ $= \frac{1}{0.333 \mu sec}$ Let us take multiplier count = 3 No. of T states required by inner loop = $\frac{3 \times 10^6}{3} = 1 \times 10^6$ $1 \times 10^6 = 10 + (count - 1) \times 24 + 21$

$$1 \times 10^{\circ} = 10 + (count - 1) \times 24 + 2$$

count = $\frac{1 \times 10^{6} - 31}{24} + 1 \gg 41666_{10}$
count = 41666_{10}
= $A2C2H$



Source program flowchart

Routine flowchart



51 Statement:Write a program for displaying BCD down counter. Counter should count numbers from 99 to 00 and it should increment after every 1 sec. Assume operating frequency of 8085 equal to 3MHz. Display routine is available



Source Program2:

= 99 utine
utine
tine
ole
o skip
-
nt

52 Statement:Write assembly language program to with proper comments for the following: To display decimal decrementing counter (99 to 00) at port 05 H with delay of half seconds between .each count. Write as well the delay routine giving delay of half seconds. Operating frequency of microprocessor is 3.072 MHz. Neglect delay for the main program.

Source Program:

MVI C, 99H	: Initia	lize counter	
ANI OF CPI OF	: Mask high	her nibble	
JNZ SKIP MOV A, C SUI 06	: Subtract 6	5 to adjust decimal cour	nt
MOV D, A SKIP: MOV A, C			
OUT 05 [^]	: send cour	nt on output port	
CALL Delay	: Wait i	for 0.5 seconds	
DCR C	: decre	ment count	
MOV A, C			
CPI FF			
JNZ BACK	: If not z	zero, repeat	
HLT	: Stop exe	ecution	
Delay subroutine:			
Delay: LXI D, Coun	t		
Back: DCX D	: 6 T-	states	
MOV A, D	: 4 T-stat	tes	
ORA E	: 4 T-states		
JNZ Back	: 10 T-sta	ates	
RET			
		1	1
	1 T-state =	Operating frequency	3 072 X 10 ⁶
		Ohennend hedrened	J.072 11 10
	=	3.2552 x 10 ⁻⁷	
Number of T-state	s required =	$\frac{0.5 \sec}{3.2552 \times 10^{-7}} = 1.536$	ix 10 ⁶
1	1.536x 10 ⁶ =	10 + (count - 1) × 1	24 + 21
	count =	$\frac{1.536x\ 10^6\ -\ 31}{24}+\ 1$	= 63999.708
	count =	64000	
	=	FA00H	

53 Statement: The delay routine given below is in infinite loop, identify the error and correct the program. *Delay routine with error:*

Sol.: 1) The fault in the above program is at instruction JNZ L1. This condition always evaluates to be true hence loops keep on executing and hence infinite loop.

2) Reason for infinite looping: - The instruction DCX H decrease the HL pair count one by one but it does not affect the zero flag. So when count reaches to OOOOH in HL pair zero flag is not affected and JNZ L1 evaluates to be true and loop continues. Now HL again decrements below OOOOH and HL becomes FFFFH and thus execution continues.

3) The modification in the program is as follows:

DELAY	: LXI H, N	:Load 16 bit count
L1	: DCX H	: Decrement count
	MOV A, L	
	ORA H	: logically OR Hand L
	JNZ L1	: If result is not 0 repeat

54 Statement: Convert a 2-digit BCD number stored at memory address 2200H into its binary equivalent number and store the result in a memory location 2300H. *Sample Problem*

(2200H) = 67H $(2300H) = 6 \times OAH + 7 = 3CH + 7 = 43H$

Source Program:

LDA 2200H	: Get the BCD number
MOV B, A	: Save it
ANI OFH	: Mask most significant four bits
MOV C, A	: Save unpacked BCDI in C register
MOV A, B	: Get BCD again
ANI FOH	: Mask least significant four bits
RRC	: Convert most significant four bits into unpacked BCD2
RRC	
RRC	
RRC	
MOV B, A	: Save unpacked BCD2 in B register
XRA A	: Clear accumulator (sum = 0)
MVI D, OAH	: Set D as a multiplier of 10
Sum: ADD D	: Add 10 until (B) = 0
DCR B	: Decrement BCD2 by one
JNZ SUM	: Is multiplication complete? i if not, go back and add again
ADD C	: Add BCD1
STA 2300H	: Store the result
HLT	: Terminate program execution



55 Statement: Write a main program and a conversion subroutine to convert the binary number stored at 6000H into its equivalent BCD number. Store the result from memory location 6100H.

Sample Problem: (6000) H = 8AH

1.8AH ? 64H (Decimal 100)	:. Divide by 64H (Decimal 100)
8AH/64H ? Quotient = 1, Remainder = 26H	1
26H < 64H (Decimal 100)	:. Go to step 2 and Digit 2 = 1
2.26H ? OAH (Decimal 10)	:. Divide by OAH (Decimal 10)
26H/OAH ? Quotient = 3, Remainder = 08I	Н
OSH < OAH (Decimal 10)	:. Go to step 3 and Digit 1 =

3

3. Digit 0 = 08H

Source Program:

LXI SP, 27FFH	: Initialize stack pointer
LDA 6000H	: Get the binary number in accumulator
CALL SUBROUTINE	: Call subroutine
HLT	: Terminate program execution

Subroutine to convert binary number into its equivalent BCD number:

PUSH B	: Save BC register pair contents
PUSH D	: Save DE register pair contents
MVI B, 64H	: Load divisor decimal 100 in B register
MVI C, OAH	: Load divisor decimal 10 in C register
MVI D, 00H	: Initialize Digit 1
MVI E, 00H	: Initialize Digit 2
STEP1: CMP B	: Check if number < Decimal 100
JC STEP 2	: if yes go to step 2
SUB B	: Subtract decimal 100
INR E	: update quotient
JMP STEP 1	: go to step 1
STEP2: CMP C	: Check if number < Decimal 10
JC STEP 3	: if yes go to step 3
SUB C	: Subtract decimal 10
INR D	: Update quotient
JMP STEP 2	: Continue division by 10
STEP3: STA 6100H	: Store Digit 0
MOV A, D	: Get Digit 1
STA 6101H	: Store Digit 1
MOV A, E	: Get Digit 2
STA 6102H	: Store Digit 2
POP D	: Restore DE register pair
POP B	: Restore BC register pair
RET	: Return to main program



56 Statement: Find the 7-segment codes for given 5 numbers from memory location 6000H and store the result from memory location 7000H. Sample Problem: (6000) H = 8AH Source Program



57 Statement: Write an assembly language program to convert the contents of the five memory locations starting from 2000H into an ASCII character. Place the result in another five memory locations starting from 2200H.

Sample Problem (2000H) = 1 (2001H) = 2 (2002H) = 9 (2003H) = A (2004H) = B Result:(2200H) = 31 (2201H) = 32 (2202H) = 39 (2203H) = 41 (2204H) = 42

Source program:

LXI SP, 27FFH	: Initialize stack pointer
LXI H, 2000H	: Source memory pointer
LXI D, 2200H	: Destination memory pointer
MVI C, 05H	: Initialize the counter
BACK: MOV A, M	: Get the number
CALL ASCII	: Call subroutine ASCII
STAX D	: Store result
INX H	: Increment source memory pointer
INX D	: Increment destination memory pointer
DCR C	: Decrement count by 1
CJNZ	: if not zero, repeat
HLT	: Stop program execution subroutine ASCII
ASCII: CPI, OAH	: Check if number is OAR
JNC NEXT	: If yes go to next otherwise continue
ADI 30H	
JMP LAST	
NEXT: ADI 37H	
LAST: RET	: Return to main program

Subroutine:

Subroutine 'ASCII' converts a hexadecimal digit to ASCII.The digit is passed using accumulator and the result is stored in accumulator.Stack starts From 27FEH to 27FDH.

Note: The ASCII Code (American Standard Code for Information Interchange) is commonly used for communication. In such cases we need to convert binary number to its ASCII equivalent. It is a seven bit code. In this code number 0 through 9 are represented as 30 through 39 respectively and letters A through Z are represented as 41H through 5AH. Therefore, by adding 30H we can convert number into its ASCII equivalent and by adding 37H we can convert letter to its ASCII equivalent.





58 Statement: convert the ASCII number in memory to its equivalent decimal number

Source Program:

LXI	H, 4150	: Point to data
ΜΟΥ	А, М	: Get operand
SUI	30	: convert to decimal
CPI	0A	: Check whether it is valid decimal number
JC	LOOP	: yes, store result
MVI	A, FF	: No, make result=FF
LOOP: INX	H	
ΜΟΥ	М, А	
HLT		: (A) = (4151)

Note: The ASCII Code (American Standard Code for Information Interchange) is commonly used for communication. It is a seven bit code. In this code number 0 through 9 are represented as 30 through 39 respectively and letters A through Z are represented as 41H through 5AH. Therefore, by subtracting 30H we can convert an ASCII number into its decimal equivalent. **59 Statement: Convert the HEX number in memory to its equivalent decimal number**

Source Program:

LXI H, 4150	; Point to data
LXI B, 0000	; Initialize hundreds= 0, Tens=0
MOV A, M	; Get hex data to A
LOOP: SUI 64	,
JC LOOP 1	
INR B	; hundreds= hundreds+1
JMP LOOP	
LOOP 1: ADI 64	; if subtracted extra, add it clear carry flag
LOOP 2: SUI 0A	
JC LOOP 3	
INR C	; Tens=tens+1
JMP LOOP 2	
LOOP 3: ADI 0A	; If subtracted extra, add it again
INX H	; A = Units
MOV M, B	; store hundreds
MOV B, A	; Combine Tens in C &
MOV Á, C	; Units in A to form a
RLC	; Single 8-bit number
RLC	
RLC	
RLC	
ADD B	
INX H	
ΜΟΥ Μ, Α	; Store tens & Units
HLT	

Note: In this experiment the number is converted to its equivalent decimal number using the following logic.

First count the number of hundreds, the number of tens & units present in that hex number. Then add up to get the equivalent decimal number.

Converting A9 we get:

A9 /64=45 Hundreds = 01

Since 64(100 decimal) cannot be subtracted from 45 no. of hundreds = 01. Now count tens

45/0A=3B Tens = 01

Now from 09, 0A cannot be subtracted. Hence tens = 06 the decimal equivalent of A9 is 169.
60 Statement: Convert an 8 bit hex no to its binary form & store in memory. *Source Program:*

LXI H, 415	50 : Initialize memory pointer
MVI B, 08	: count for 8-bit
MVI A, 54	
LOOP : RRC	
JC LOOP1	
MVI M, 00	: store zero it no carry
ЈМР СОММ	10N
LOOP2: MVI M,	<i>01 : store one if there is a carry</i>
COMMON: INX H	
DCR B	: check for carry
JNZ LOOP	
HLT	: Terminate the program

61 Statement: Write a program to output contents of B register LSB to MSB on the SOD pin. *Source program:*

MVI C, 08H	: Initialize count with 8
MOV Å, B	
BACK: RRC	: Rotate B register contents right
MOV B, A	: Save contents of register B
JNC SKIP	: If no carry skip
Μ٧Ι Α, СОН	
SIM	: If carry, send high on SOD
JMP NEXT	
SKIP: MVI A, 40H	
SIM	: If no carry, send low on SOD.
NEXT: CALL DELAY	: Wait for specific time
DCR C	: Decrement count by 1
JNZ BACK	: if count = 0 Stop, if not repeat
HLT	: Stop program execution

Delay subroutine:



62 Statement: Write a program to output square wave of 1 kHz frequency on the SOD pinof 8085 for 5 seconds. Operating frequency of 8085 is 2 MHz. *Source program*

LXI SP, 27FFH	: Initialize stack pointer
LXI B, 1388H	: Initialize counter with count 5000.
BACK: MVI A, COH	
SIM	: Send high on SOD pin
CALL DELAY	: Wait for 0.5 msec
MVI A, 40H	: Send low on SOD pin
CALL DELAY	: wait for. 5 msec
DCX B	: Decrement count by 1
ΜΟΥ Α, C	
ORA B	: Check if count = 0
JNZ BACK	: If not, repeat
HLT	: Stop program execution

Delay subroutine:



63 Statement: An ASCII character is being received on SID pin of 8085. Write a program in assembly language of 8085 to assemble this character and store it in memory. Write comment for each instruction. *Source program:*

LXI SP, 27FFH	
LXI H, 2000H	: Memory pointer
RIM	: Read SID
ANI 80H	: Check D7 bit of Accumulator
CALL Delay	: 1/2 bit time delay for stop bit
MVI B, 08H	: Initialize bit counter
MVI D, 00H	: Clear data register
UP1: ALL Delay	: 1 bit time
RIM	: Read SID line
ANI 80H	: Mask bits B6 - Bo
ORA D	: OR data bit with previous bits
RRC	-
MOV D, A	: Store data bit at appropriate position
DCR B	
JNZ UP1	
RLC	: Shift left to correct result
ΜΟΥ Μ, Α	: Store result
RIM	: Read stop bit
ANI 80H	-
CZ error	: If not stop bit call error
HLT	: Terminate program.
Delay subroutine:	
Delay: LXI D, Count	
Back: DCX D	
MOV A, D	
ORA E	
JNZ Back	
RET	



64 Statement: Write a assembly program to transmit a message from an 8085 to a CRT terminal for the following requirements and draw the interfacing diagram.

i) A message of 50 characters is stored as ASCII characters (without parity) in memory locations starting at 2200H.

ii) Baud rate x 16

iii) Stop bits 2

Solution Description:

- CRT terminal uses normal RS 232C standard serial communication interface. Therefore, to transmit data to CRT it is necessary to have RS 232C interface at the sending end.
- Fig. shows the interfacing of 8251 with RS 232C to 8085.
- As shown in the Fig. three RS-232C signals (TxD, RxD are Ground) are used for serial communication between the CRT terminal and the 8085 system.
- Line drivers and receivers are used to transfer logic levels from TTL logic to RS-232C logic.
- For RS-232C the voltage level +3V to +15V is defined as logic 0 and voltage level from -3V to -15V is defined as logic 1.
- The line driver, MC 1488, converts logic 1 of TIL to approximately -9V and logic a of TIL to approximately +9V. These levels at the receiving end are again converted by the line receiver, MC1489, into TTL compatible logic.

I/O Map :

Register			Ad	dres	s lin	Address			
	A7	A ₆	As	A4	Α3	A ₂	A ₁	A	
Data Register	1	1	1	1	1	1	1	0	FEH
Control Register	1	1	1	1	1	1	1	1	FFH

Mode word necessary for the given specification is as follows :



Command word necessary for the given specification is as follows

B ₇	8 ₆	B ₅	B ₄	83	B ₂	8,	В ₀	
×	0	×	1	×	0	x	1	= 11 H
			Error reset		Receive disable		Transmit enable	

Status word necessary for the given specification is as follows



If bit 0 of the Status word is logic '1' then transmitter is ready to accept the character

Source program:



Fig-Schematic of interfacing an RS-232C terminal with an 8085 system using the 8251A



65 Statement: Write a assembly program to receive 25 bytes from an CRT terminal to 8085 for the following requirements.



If bit 1 of the status word is logic '1' then receiver is ready to give the character

Note: Reading of status word is necessary for checking the status of RxD line of 8085 that whether receiver is ready to give data or not.

Source program:

LXI H, 2300 H	: Initialize memory pointer
MVI Ć, FFH	: Initialize counter to accept 25 characters
MVI Á, OOH	-
OUT FFH	
OUT FFH	: Dummy mode word
OUT FFH	-
MVI A, 40H	: Reset command word
OUT FFH	: Reset 8251 A
MVI A, CAH	: Mode word initialization
OUT FFH	
MVI A, 14 H	: Command word initialization
OUT FFH	
CHECK: IN FFH	
ANI 02 H	: Check RxRDY
JZ CHECK	: Is RxRDY ? If not, check again
	-



- : Get the character
 - : save the character
 - : Increment memory pointer
 - : Decrement memory pointer
 - : Send character to the transmitter
 - : If not zero, accept next character
 - : Stop program execution

66 Statement:

Write a program to initialize 8255 in the configuration given below *Sample 1:*

Write a program to initialize 8255 in the configuration given below:

1. Port A: Simple input

2. Port B: Simple output

- 3. Port CL: Output
- 4. Port Cu: Input

Assume address of the control word register of 8255 as 83H.

Solution:



SOURCE PROGRAM 1:

MVI A, 98H	: Load control word
OUT 83H	: Send control word

Sample 2:

Write a program to initialize 8255 in the configuration given below: 1. Port A: Output with handshake

- 2. Port B: Input with handshake
- 3. Port CL: Output
- 4. Port Cu: Input

Assume address of the control word register of 8255 as 23H. Solution:



SOURCE PROGRAM 2: MVI A, AEH OUT 23H

: Load control word : Send control word

67 Statement: Write a program to blink Port C bit 0 of the 8255. Assume address of control word register of 8255 as 83H. Use Bit Set/Reset mode.

Control word to make Bit 0 high



. . . .



Source program:

BACK: MVI A, OIH OUT 83H CALL DELAY MVI A, OOH OUT 83H CALL Delay JMP BACK Delay subroutine:





68 Statement: Design a system (both Software and Hardware) that will cause 4 LEDs to flash 10 times when a push button switch is pressed. Use 8255. Assume persistence of vision to be 0.1 seconds. *Source program:*



69 Statement: Design a microprocessor system to control traffic lights. The traffic light arrangement is as shown in Fig. The traffic should be controlled in the following manner.

1) Allow traffic from W to E and E to W transition for 20 seconds. 2) Give transition period of 5 seconds (Yellow bulbs ON) 3) Allow traffic from N to 5 and 5 to N for 20 seconds 4) Give transition period of 5 seconds (Yellow bulbs ON) 5) Repeat the process.

HARDWARE FOR TRAFFIC LIGHT CONTROL



Fig. shows the interfacing diagram to control 12

electric bulbs. Port A is used to control lights on N-S road and Port B is used to control lights on W-E road. Actual pin connections are listed in Table 1 below.

Pins	Light	Pins	Light
PA ₀	R ₁	PB ₀	R ₃
PA ₁	Y ₁	PB1	Y ₃
PA ₂	G ₁	PB ₂	G ₃
PA3	R ₂	PB3	R ₄
PA4	.Y ₂	PB ₄	Y ₄
PA ₅	G ₂	PB5	G ₄

Table 1The electric bulbs are controlled by relays.The 8255 pins are used to control relay on-off action with the help of relay drivercircuits. The driver circuit includes 12 transistors to drive 12 relays. Fig. alsoshows the interfacing of 8255 to the system.

INTERFACING DIAGRAM



I/O MAP:

Ports / Control Register			Ado	ires	s li	nes			Address
0	A,	, A ₆	Α,	Α4	A ₃	A ₂	Α,	Aa	
Port A	1	0	0	0	0	0	0	0	80H
Port B	1	0	0	0	0	0	0	1	81H
Port C	1	0	0	0	0	0	1	0	82H
Control Register	1	0	0	0	0	0	1	1	83H

Table 2

SOFTWARE FOR TRAFFIC LIGHT CONTROL

Control word : For initialization of 8255.

BSR/IO	моі	DEA	PA	PCH	MODE B	PB	PCL	= 80H
1	0	0	0	Х	0	0	х	

Fig. Control word

ſ	To glow	PB7	P₿6	PB5	PB4	PB3	PB2	PB1	PB ₀	PA7	PA ₆	PAs	PA4	PA3	PA ₂	PA ₁	PA	Port B Output	Port A Output
	R ₁ ,R ₂ .G ₃	×	x	1	0	0	1	0	0	×	x	0	0	1	0	0	1	24H	09H
	Y ₁ ,Y ₂ ,Y ₃ and Y	x	x	0	1	0	0	1	0	x	x	0	1	0	0	1	0	12H	12H
	R ₃ ,R ₄ ,G ₁ and G ₂	x	×	0	0	1	0	0	1	x	×	1	0	0	1	0	0	09H	24H

: Call delay subroutine

: Call delay subroutine

: Call delay subroutine

Table shows the data bytes to be sent for specific combinations.

Source program:

L

MVI A, 80H : Initialize 8255, port A and port B **OUT 83H (CR)** : in output mode START: MVI A, 09H OUT 80H (PA) : Send data on PA to glow R1 and R2 MVI A, 24H **OUT 81H (PB)** : Send data on PB to glow G3 and G4 MVI C, 28H : Load multiplier count (4010) for delay CALL DELAY MVI A, 12H OUT (81H) PA : Send data on Port A to glow Y1 and Y2 : Send data on port B to glow Y3 and Y4 OUT (81H) PB : Load multiplier count (1010) for delay MVI C, OAH CALL: DELAY MVI A, 24H : Send data on port A to glow G1 and G2 OUT (80H) PA MVI A, 09H : Send data on port B to glow R3 and R4 OUT (81H) PB MVI C, 28H : Load multiplier count (4010) for delay CALL DELAY MVI A, 12H : Send data on port A to glow Y1 and Y2 OUT PA OUT PB : Send data on port B to glow Y3 and Y4 MVI C, OAH : Load multiplier count (1010) for delay : Call delay subroutine CALL DELAY JMP START Del DEL

: Load count to give 0.5 sec delay
: Decrement counter
: Check whether count is 0
: If not zero, repeat
: Check if multiplier zero, otherwise repeat
: Return to main program

Assume Operating Frequency = 2 MHz

Time for one T - state =
$$\frac{1}{2MHz}$$
 = 0.5µsec
Count = $\frac{\text{Required Delay}}{\text{Time required for 1 loop}}$
= $\frac{0.5 \sec}{0.5 \, \mu \sec \times 24} \approx 1 \text{ loop needs 24T-states}$
= 41666₁₀ = A2C2H

70 Statement: Interface a Stepper Motor to the 8085 microprocessor system and write an 8085 assembly language program to control the Stepper Motor.

HARDWARE FOR STEPPER MOTOR CONTROL

A stepper motor is a digital motor. It can be driven by digital signal. Fig. shows the typical 2 phase motor rated 12V /0.67 A/ph interfaced with the 8085 microprocessor system using 8255. Motor shown in the circuit has two phases, with center-tap winding. The center taps of these windings are connected to the 12V supply. Due to this, motor can be excited by grounding four terminals of the two windings. Motor can be rotated in steps by giving proper excitation sequence to these windings. The lower nibble of port A of the 8255 is used to generate excitation signals in the proper sequence. These excitation signals are buffered using driver transistors. The transistors are selected such that they can source rated current for the windings. Motor is rotated by 1.80 per excitation.

INTERFACING SCHEME



SOFTWARE FOR STEPPER MOTOR CONTROL As port A is used as an output port, control word for 8255 is 80H.

Stepper Motor Control Program:

6000H Excite code DB 03H, 06H, 09H, OCH : This is the code sequence for clockwise

rotation

Subroutine to rotate a stepper motor clockwise by 360° - Set the counts:

MVI C, 32H START: MVI B, 04H LXI H, 6000H BACK1: MOV A, M OUT PORTA CALL DELAY INX H DCR B JNZ BACK I DCR C JNZ START RET : Set repetition count to 50*i*o : Counts excitation sequence : Initialize pointer : Get the Excite code : Send Excite code : Wait : Increment pointer : Repeat 4 times : Repeat 50 times

Delay subroutine:

71 Statement: Interface a 64-key matrix keyboard to the 8085 microprocessor using 8255. Write an 8085 assembly language program to initialize 8255 and to read the key code.

HARDWARE FOR MATRIX KEYBOARD INTERFACE

Fig. shows a matrix keyboard with 64 keys connected to the 8085 microprocessor using 8255. A matrix keyboard reduces the number of connections, thus the number of interfacing lines. In this example, the keyboard with 64 keys, is arranged in 8 x 8 (8 rows and 8 columns) matrix. This requires sixteen lines from the microprocessor to make all the connections instead of 64 lines if the keys are connected individually. The interfacing of matrix keyboard requires two ports: one input port and other output port. Rows are connected to the input port, port A and columns are connected to the output port, port B.

INTERFACING SCHEME



SOFTWARE FOR MATRIX KEYBOARD INTERFACE

Source program

MVI A, 90H: Initialize Port A as input and
OUT CROUT CR: Port B as OutputSTART: MVI A, 00: Make all scan lines zero
OUT PBBACK: IN PA: Check for key release
JNZ BACKCPI FF: Check for key release
CALL DELAYBACK 1: IN PA

CPI FF JZ BACK 1 CALL DELAY MVI L, 00H MVI C, 08H MVI B, FEH NEXTCOL: MOV A, B OUT PB MVI D, 08H IN PA NEXTROW: RRC JNC DISPLAY INR L DCR D JNZ NEXTROW MOV A, B RLC MOV B, A DCR C JNZ NEXTCOL JMP START

: Check for key press : If not, wait for key press : Wait for key debounce : Initialize key counter : Make one column low : Initialize row counter : Read return line status : Check for one row : If zero, goto display else continue : Increment key counter : Decrement row counter : Check for next row : Select the next column : Decrement column count : Check for last column if not repeat : Go to start

Delay subroutine:



72 Statement: Interface an 8-digit 7 segment LED display using 8255 to the 8085 microprocessor system and write an 8085 assembly language routine to display message on the display.

HARDWARE FOR EIGHT DIGIT SEVEN SEGMENT DISPLAY INTERFACE

Fig. shows the multiplexed eight 7-segment display connected in the 8085 system using 8255. In this circuit port A and port B are used as simple latched output ports. Port A provides the segment data inputs to the display and port B provides a means of selecting a display position at a time for multiplexing the displays. A0-A7 lines are used to decode the addresses for 8255. For this circuit different addresses are:

The register values are chosen in Fig. such that the segment current is 80 mA. This current is required to produce an average of 10 mA per segment as the displays are multiplexed. In this type of display system, only one of the eight display position is 'ON' at any given instant. Only one digit is selected at a time by giving low signal on the corresponding control line. Maximum anode current is 560 mA (7-segments x 80 mA = 560 mA), but the average anode current is 70 mA.

INTERFACING SCHEME



SOFTWARE FOR EIGHT DIGIT SEVEN SEGMENT DISPLAY INTERFACE

For 8255, Port A and B are used as output ports. The control word format of 8255 according to hardware connections is:

BSR	Mod	e A	PA	$\dot{P}_{\rm CU}$	Mode B	PB	PCL	
1	0	0	0	x	0	0	x	= 80 H

Fig. — Control word format for 8255

Source program:

SOFTWARE TO INITIALIZE 8255:

MVI	A, 80H	: Load control	word in AL
Ουτ	CR	: Load control	word in CR

SUBROUTINE TO DISPLAY MESSAGE ON MULTIPLEXED LED DISPLAY:

SET UP REGISTERS FOR DISPLAY:

MVI B, 08H	: load count
MVI C, 7FH	: load select pattern
LXI H, 6000B	: starting address of message

DISPLAY MESSAGE:

DISP 1: MOV A, C	: select digit
OUT PB	_
ΜΟΥ Α, Μ	: get data
OUT PA	: display data
CALL DELAY	: wait for some time
DISP 1: MOV A, C	
RRC	
ΜΟΥ Ϲ, Α	: adjust selection pattern
INX H	
DCR B	: Decrement count
JNZ DISP 1	: repeat 8 times
RET	-

Note: This "display message subroutine" must be called continuously to display the 7-segment coded message stored in the memory from address 6000H.

Delay subroutine:

73 Statement: Interface an 8 x 8 matrix keyboard to 8085 through 8279 in 2-key lockout mode and write an assembly language program to read keycode of the pressed key. The external clock frequency is 2MHz. Use I/O mapped I/O technique. (Dont use any Interrupts)



HARDWARE FOR 8 x 8 MATRIX KEYBOARD INTERFACE

SOFTWARE FOR 8 x 8 MATRIX KEYBOARD INTERFACE

I/O Map

Data/Control Register	Address lines								Address
	A ₇	A_6	A_5	A ₄	A ₃	A ₂	Α1	A ₀	
Data Register	1	0	0	0	0	0	0	0	80 H
Control Register	1	0	0	0	0	0	0	1	81 H

SOFTWARE FOR 8 x 8 MATRIX KEYBOARD INTERFACE

The three steps needed to write the software are: Step 1: Find keyboard/display command word.

0	0	0	D	D	ĸ	ĸ	ĸ	
0	0	0	х	х	0	0	0	= 00H

Step 2: Find program clock command word

				,	r -	F	F	
0	0	1	1	0	1	0	0	= 34H

Step 3: Find Read FIFO/sensor RAM command word.

			AI		A	A	A	
0	1	0	0	х	0	0	0	= 40H

Source program:

MVI A, 00H	: Initialize keyboard/display
OUT 81H	: in encoded scan keyboard-2 keylockout mode
MVI A, 34H	
OUT 81H	: Initialize prescaler count
BACK: IN 81H	: Read FIFO status word
ANI 07H	: Mask bit B3 to B7
JZ BACK	: If 0, key is not pressed wait for key press else read FIFO
RAM	
MVI A, 40H	: Initialize 8279 in read
OUT 81H	: FI FO RAM mode
IN 80H	: Read FIFO RAM (keycode)
HLT	: Stop program execution.

FLOWCHART



74 Statement: Interface an 8 x 8 matrix keyboard to 8085 through 8279 in 2-key lockout mode and write an assembly language program to read keycode of the pressed key. The external clock frequency is 2MHz. Use I/O mapped I/O technique.

HARDWARE FOR 8 x 8 MATRIX KEYBOARD INTERFACE(With Interrupt) Fig. shows the interfacing of 8 x 8 matrix keyboard in interrupt driven keyboard mode. In the interrupt driven mode interrupt line from 8279 is connected to the one of the interrupt input of 8085 except INTR. Here, INT line from 8279 is connected to the interrupt RST 7.5 of 8085. Other signal connections are same as in the non interrupt mode.



|--|

Data/Control Register	Address lines								Address
	A ₇	A_6	A_5	A ₄	A ₃	A ₂	Α1	A ₀	
Data Register	1	0	0	0	0	0	0	0	80 H
Control Register	1	0	0	0	0	0	0	1	81 H

SOFTWARE FOR 8 x 8 MATRIX KEYBOARD INTERFACE(With Interrupt)

The three steps needed to write the software are:

Step 1: Find keyboard/display command word.

0	0	0	D	D	ĸ	к	ĸ	
0	0	0	х	х	0	0	0	= 00H

Step 2: Find program clock command word

			P3-	Р	Ρ	P	Р	P	
	0	0	1	1	0	1	0	0	= 34H
S	Step 3	: Find	Read	FIFO/	senso	r RAM	comm	and v	vord.
				AI		Α	А	Α	_
	0	1	0	0	x	0	0	0	= 40H

Source program:

MVI A, OOH	: Initialize keyboard/display in encoded
OUT 81H	: scan keyboard 2 key lockout mode
MVI A, 34H	
OUT 81H	: Initialize prescaler count
MVI A, OBH	: Load mask pattern to enable RST 7.5
SIM	: mask other interrupts
EI	: Enable Interrupt
HERE: JMP HERE	: Wait for the interrupt

Interrupt Subroutine:

MVI A,	40H	: Initialize 8279 in read FIFO					
Ουτ	81H	: RAM mode					
IN 80H	1	: Read FIFO RAM (keycode)					
EI		: Enable Interrupt					
RET		: Return to main program					

Note: In the interrupt driven keyboard, when key is pressed, key code is loaded into FIFO RAM and interrupt is generated. This interrupt signal is used to tell CPU that there is a keycode in the FIFO RAM. CPU then initiates read command with in the interrupt service routine to read key code from the FIFO RAM.

FLOWCHART



75 Statement: Interface an 8 x 4 matrix keyboard to 8085 through 8279.



HARDWARE FOR INTERFACING 8x4 MATRIX KEYBOARD

NOTE: As keyboard is having 8 rows and 4 columns, only 4 scan lines are required and we can avoid external decoder to generate scan lines by selecting decoded scan keyboard mode.

SOFTWARE FOR INTERFACING 8x4 MATRIX KEYBOARD *Source program:*

MVI A, 00H	: Initialize keyboard/display in encoded
OUT 81H	: scan keyboard 2 key lockout mode
MVI A, 34H	
OUT 8 1H	: Initialize prescaler count
MVI A, OBH	: Load mask pattern to enable RST 7.5
SIM	: mask other interrupts
EI	: Enable Interrupt
HERE: JMP HERE	: Wait for the interrupt
Interrupt Subrouti	ne:
МVI А, 40Н	: Initialize 8279 in read FIFO
OUT 81H	: RAM mode
IN 80H	: Read FIFO RAM (keycode)
EI	: Enable Interrupt
RET	Return to main program

76 Statement:

Interface 8/7-segment digits (common cathode) to 8085 through 8279 and write an 8085 assembly language program to display 1 to 8 on the eight seven segment digits. External clock frequency is 3 MHz.

HARDWARE FOR EIGHT SEVEN SEGMENT DIGITS INTERFACE

Fig. shows the interfacing of eight 7-segment digits to 8085 through 8279. As shown in the figure eight display lines (Bo-B3 and Ao-A3) are buffered with the help of transistor and used to drive display digits. These buffered lines are connected in parallel to all display digits. So, SI and S2 lines are decoded and decoded lines are used for selection of one of the eight digits.



SOFTWARE FOR EIGHT SEVEN SEGMENT DIGITS INTERFACE To display 1 to 8 numbers on the eight 7-segment digits we have to load 7segment codes for 1 to 8 numbers in the corresponding display locations.

Number	h	g	f	е	d	с	b	a	Code
1	0	0	0	0	0	1	1	0	06
2	0	1	0	1	1	0	1	1	5B
3	0	1	0	0	1	1	1	1	4F
4	0	1	1	0	0	1	1	0	66
5	0	1	1	0	1	1	0	1	6D
6	0	1	1	1	1	1	0	1	7D
7	0	0	0	0	0	1	1	1	07
8	0	1	1	1	1	1	1	1	7F

Table - 7-Segment codes for common cathode display

The three steps needed to write the software are: Step 1: Find keyboard/display command word.

			0	0	is a	IX.		
0	0	0	0	0	0	0	0	= 00H

Step 2: Find program clock command word

Γ	0	0	1	P 1	P 1	P 1	P 1	. P	= 3EH
St	ep 3:	: Find	displa	y RAM	l comr	nand v	word.	Ao	
	1	0	0	1	0	0	0	0	= 90H
So	ource LX MV MV	progi I B, 6. /I C, 0 /I A, 0	ram: 200B 98H 90H		:In	nitializ : Initia : Initia	e look alize co alize k	up tal ountei eyboa	ole pointer r vrd/display

MVI C, 08H	: Initialize counter
MVI Á, OOH	: Initialize keyboard/display
OUT 8IH	: Mode
MVI A, 3EH	: Initialize prescaler count
OUT 8IH	
MVI A, 90H	: Initial size 8279 in write Display
OUT 8IH	: RAM-mode
BACK : MOV A, M	: Get the 7-segment code
ОИТ 80Н	: Write 7-segment code in display RAM
INX H	: Increment lookup table pointer
DCR C	: Decrement counter
JNZ BACK	: if count = 0 stop, otherwise go to back
HLT	: Stop program execution

LOOK UP TABLE

Memory Address	Contents
6200	66
6201	5B
6202	4F
6203	66
6204	6D
6205	7D
6206	07
6207	7F

FLOWCHART



77 Statement:

Interface 4 x 4 matrix keyboard and 4 digit 7-segment display and write an tssembly language program to read keycode of the pressed key and display same key on :he 7 segment display.

HARDWARE FOR 4x4 MATRIX KEYBOARD & 4 DIGIT 7 SEGMENT DISPLAY INTERFACE

Fig. shows interfacing diagram. Here, 4 scan lines are sufficient to scan matrix keyboard and to select display digits. Hence decoded mode is used.



Fig. — Keyboard and display interfacing in decoded mode using 8279 SOFTWARE FOR 4x4 MATRIX KEYBOARD & 4 DIGIT 7 SEGMENT DISPLAY

INTERFACE

The three steps needed to write the software are:

Step 1: Find keyboard/display command word.

		D	D	ĸ	ĸ	ĸ	
0 0	0	0	0	0	э	1	= 01H

Ste	ep 2	: Find _l	progra	m clo P	ck con P	nmand P	l word P	Ρ	
Γ	0	0	1	1	1	0	0	1	= 39H
Ste	ep 3	: Find I	Read F		AM co	mman A	d wor	d. A	_
	0	1	0	0	х	0	0	0	= 40H

Step 3: Find Write FIFO RAM command word.

		Al	A3	A ₂	A ₁	Ao	
1 0	0	0	0	0.	0	0	= 80H

Source program:

MVI A, 00H	: Initialize keyboard/display in encoded
OUT 81H	: scan keyboard 2 key lockout mode
MVI A, 34H	
OUT 81H	: Initialize prescaler count
MVI A, OBH	: Load mask pattern to enable RST 7.5
SIM	: mask other interrupts
EI	: Enable Interrupt
HERE: JMP HERE	: Wait for the interrupt

Interrupt service routine

MVI A, 40H	: Initialize 8279 in read FIFO RAM mode
OUT 81H	
IN 80H	: Get keycode
MVI H, 62H	: Initialize memory pointer to point
MOV L, A	: 7-Segment code
MVI A, 80H	: Initialize 8279 in write display RAM mode
OUT 81H	
MOV A, M	: Get the 7 segment code
ОИТ 80Н	: Write 7-segment code in display RAM
EI	: Enable interrupt
RET	: Return to main program
OUT 80H EI RET	<i>: Write 7-segment code in display RAM : Enable interrupt : Return to main program</i>

FLOWCHARTS

Source Program and Interrupt Service Routine



78 Statement: Write an assembly language program to roll message 'HELL0123' from right to left

HARDWARE FOR ROLLING HELLO123

Fig. shows the interfacing of eight 7-segment digits to 8085 through 8279. As shown in the figure eight display lines (Bo-B3 and Ao-A3) are buffered with the help of transistor and used to drive display digits. These buffered lines are connected in parallel to all display digits. So, SI and S2 lines are decoded and decoded lines are used for selection of one of the eight digits.



SOFTWARE FOR ROLLING HELLO123

To roll above message we have to load 7-segment codes for characters within the message and it is necessary to configure 8279 in right entry mode

Character	h	9	ť	e	d	ċ	b	a	Code
Н	0	1	1	1	0	1	1	0	76H
E	Ø	1	1	1	: 📲	0	0	1	79H
L	Ö	0	1	1	1	0	0	0	38H
L	0	0	1	1	1	0	0	0	38H
0	o	0	1	1	1	1	1	1	3FH
1	0	0	0	0	0	1	1	0	06H
2	0	1	Ö	1	1	0	1	1	5BH
3	0	1	0	0	1	1	1	1	4FH

Table - 7-segment codes for given message

The three steps needed to write the software are:



 $CD_0-CD_1 = 00$ (Blanking code)

Source program:

LXI B, 6200B	: Initialize lookup table pointer
MVI Ć, 08H	: Initialize counter
MVI Á, 10H	: Initialize keyboard/display in right entry mode
OUT SIH	: Mode
MVI A, 3EH	: Initialize prescaler count
Ουτ έιΗ	
MVI A, DOH	: Clear Display
	. ,
MVI A, 90H	: Initialize 8279 in write display
	: RAM mode
BACK : MOV A, M	: Get the 7-seament code
OUT 80H	: Write 7-segment code in display RAM
INX H	: Increment lookup table pointer
DCR C	: Decrement counter
JNZ BACK	: if count = 0 stop, otherwise go to back
HLT	: Stop program execution

= D0H
LOOK UP TABLE

Memory address	Contents
6200H	76H
6201H	79H
6202H	38H
6203H	38H
6204H	3FH
6205H	06H
6206H	58H
6207H	4FH

FLOWCHART



79 Statement: Write an assembly language program to your name from right to left

HARDWARE FOR ROLLING HELLO123

Fig. shows the interfacing of eight 7-segment digits to 8085 through 8279. As shown in the figure eight display lines (Bo-B3 and Ao-A3) are buffered with the help of transistor and used to drive display digits. These buffered lines are connected in parallel to all display digits. So, SI and S2 lines are decoded and decoded lines are used for selection of one of the eight digits



SOFTWARE FOR ROLLING THE NAME - J.BINU

To roll the above namewe have to load 7-segment codes for characters within the message and it is necessary to configure 8279 in right entry mode The three steps needed to write the software are:

Step 1: Find keyboard/display command word.

			D	D	ĸ	ĸ	к	
0	0	0	1	0	0	0	0	=10H

Step 2: Find program clock command word

		Р	Р	P	P	P	
0 0	1	1	1	1	1	0	= 3EH

Step 3: Find display RAM command word.

		AI	A 3	A 2	A 1	A ₀	
1 0	0	1	0	0	0	0	= 90H

Clear command word.

		vora.	CD_2	CD1	CD_0	CF	CA	
1	1	0	1	0	0	0	0	= D0H

 CD_0 - $CD_1 = 00$ (Blanking code)

Source program:

LXI B, 6200B	: Initialize lookup table pointer
MVI C, 08H	: Initialize counter
MVI A, 10H	: Initialize keyboard/display in right entry mode
OUT 8IH	: Mode
MVI A, 3EH	: Initialize prescaler count
OUT 8IH	
MVI A, DOH	: Clear Display
OUT 8IH	
MVI A, 90H	: Initialize 8279 in write display
OUT 81H	: RAM mode
BACK : MOV A, M	: Get the 7-segment code
OUT 80H	: Write 7-segment code in display RAM
INX H	: Increment lookup table pointer
DCR C	: Decrement counter
JNZ BACK	: if count = 0 stop, otherwise go to back
HLT	: Stop program execution

LOOK UP TABLE

Memory address	Contents
6200H	1FH
6201H	80H
6202H	BFH
6203H	06H
6204H	B7H
6205H	BEH
6206H	00H
6207H	ООН

FLOWCHART

