

# Midterm Exam II

## EEL 5542 – Fall 2002

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Name: \_\_\_\_\_  
(please print your name)

### ***Instructions***

For each problem show your work in detail and circle your final answer. Also start each problem on a new sheet. This exam consists of 5 problems; each is worth 20 points. When you turn in your exam, please staple the 3 pages of this document to your work. Midterm Exam I is due by Wednesday, November 21<sup>st</sup> 2001 at 12:00pm. For students that take this course from remote sites: please fax or send your work via mail by the aforementioned deadline. For all other students: please turn in your work to the department office (Room 407, CEBA-I building) by the aforementioned deadline and have one of the administrative assistants date your work and place it into my mailbox. If you have any questions concerning this exam, don't hesitate to get in touch with me. Please refer to my contact information at

[http://www.geocities.com/eel5542/contact\\_info.htm](http://www.geocities.com/eel5542/contact_info.htm)

Good Luck!

Please, read carefully, then date and sign the following statement:

*Pertaining to this take-home exam I have received no help from any other than the instructor of my class.*

Signature: \_\_\_\_\_

Date: \_\_\_\_\_

**Problem 1**

A WSS random process  $X(t)$  features a mean  $\mu$  and an autocorrelation of  $R_x(\tau)$ .

- a) Find an upper bound for the probability  $\Pr\{|X(t)-\mu|\geq e\}$ , where  $e>0$ .
- b) Find an upper bound for the probability  $\Pr\{|X(t+T)-X(t)|\geq e\}$ , where for  $e>0$ .  
In both cases the upper bound is a function of autocorrelation function values and  $e$

**Problem 2**

Assume the  $X(t)$  is a WSS, zero mean, differentiable in the mean square sense random process.

- a) Show that  $X(t)$  and  $X'(t)=\frac{dX(t)}{dt}$  are uncorrelated.
- b) Let the output of a system be

$$Y(t) = X(t) + \frac{dX(t)}{dt}$$

Find the power spectrum of  $Y(t)$  and show that it is the sum of the power spectra of  $X(t)$  and  $X'(t)$ .

**Problem 3**

A WSS, zero mean, Gaussian random process  $X(t)$  acts as an input to a system giving an output of  $Y(t)=h(X(t))$ , where

$$h(x) = \begin{cases} +1 & \text{when } x \geq 0 \\ -1 & \text{when } x < 0 \end{cases}$$

- a) Show that  $E\{Y(t)\}=0$ .
- b) Next, show that the autocorrelation function of  $Y(t)$  is given as

$$R_Y(\mathbf{t}) = \Pr\{X(t+\mathbf{t})X(t) > 0\} - \Pr\{X(t+\mathbf{t})X(t) < 0\}$$

#### **Problem 4**

Let  $X_1(t)$  and  $X_2(t)$  be two jointly WSS and jointly Gaussian random processes. Each process acts as an input to a different linear time invariant system.  $X_1(t)$  enters a system with impulse response function  $h_1(t)$  and transfer function  $H_1(f)=\mathcal{F}\{h_1(t)\}$  giving as an output a random process  $Y_1(t)$ . Similarly,  $X_2$  acts as an input for a system with impulse response function  $h_2(t)$  and transfer function  $H_2(f)=\mathcal{F}\{h_2(t)\}$  giving as an output a random process  $Y_2(t)$ . Here,  $\mathcal{F}\{ \}$  denotes the Fourier Transform operator.

- Find the cross-correlation and the cross-power spectral density of  $Y_1(t)$  and  $Y_2(t)$ .
- Show that  $Y_1(t)$  and  $Y_2(t)$  are jointly WSS and jointly Gaussian random processes.
- Assume that the transfer functions of the two systems have no overlapping spectra, that is,  $|H_1(f)||H_2(f)|=0$  for every  $f$ . Show that  $Y_1(t)$  and  $Y_2(t)$  are independent random processes.
- If  $X_1(t)$  and  $X_2(t)$  were non-stationary jointly Gaussian random processes, would the above results (b) and (c) still hold?

#### **Problem 5**

Consider a discrete time system described by the following difference equation

$$X_n = aX_{n-1} + W_n \quad n \geq 0$$

where  $|a|<1$  and  $W_n$  is white Gaussian noise with zero mean and variance of  $\sigma_w^2$ . Furthermore, the initial condition  $X_{-1}$  is normally distributed with mean  $m$  and variance  $\sigma_x^2$  and is independent of  $W_n$  for all values of  $n$ .

- Show that  $X_n$  is not stationary in any sense.  
**Hint:** First solve the difference equation, which will give you  $X_n$  as a function of  $X_{-1}$  and lagged versions of  $W_n$  (that is,  $W_n, W_{n-1}$ , etc.).
- Show that  $X_n$  becomes WSS as  $n \rightarrow \infty$ .  
**Hint:** One of the things you have to show is that the autocorrelation  $R_x(n,m)$  of  $X_n$  depends only on the difference  $k=m-n$  as  $n \rightarrow \infty$ . Or you can show the same thing for the autocovariance  $C_x(n,m)$  of  $X_n$ , which is slightly easier (it involves less calculations). In any case though, be aware of the fact that by definition  $R_x(n,m) = R_x(m,n)$  as well as  $C_x(n,m) = C_x(m,n)$  for all  $n$  and  $m$ .
- If  $a \geq 1$ , is there any possibility that  $X_n$  might be stationary, when  $n \rightarrow \infty$ ? Why or why not?

d) Show that  $X_n$  becomes an AR(1) (first-order autoregressive) random process for  $n \rightarrow \infty$ .

**Hint:** If  $Y_n$  is an AR(1) process, then it is described by  $Y_n = \mathbf{b}Y_{n-1} + V_n$ , where  $|\mathbf{b}| < 1$  and  $V_n$  is a white Gaussian process with zero mean and variance  $\sigma^2$ . Most importantly, it satisfies  $E\{Y_n\} = 0$  and

$$R_Y(k) = \sigma^2 \frac{\mathbf{b}^{|k|}}{1 - \mathbf{b}^2}$$

e) Find the pdf of  $X_n$  as  $n \rightarrow \infty$  (determine type of pdf as well as what its parameters' values are).

**Note:** Baffled by the fact that a linear time-invariant (LTI) system with WSS input might give you a non-stationary output? The above equation describes a first-order *Gauss-Markov*, which resembles a first-order autoregressive (AR(1)) model except that the output  $X_n$  starts at  $n=0$  with some initial condition  $X_{-1}$  and therefore  $X_n$  may not be WSS.

⊗ Problem 1

Tchebycheff Inequality:  $\Pr\{|X - E\{X\}| \geq \varepsilon\} \leq \frac{\text{Var}(X)}{\varepsilon^2} \quad \forall \varepsilon > 0 \quad \textcircled{\text{T.I}}$

(a) We are given that  $E\{X(t)\} = \mu_x$  and  $\text{Var}(X(t)) = R_x(0) - \mu_x^2$

By applying T.I. we readily get

$$\Pr\{|X(t) - \mu_x| \geq \varepsilon\} \leq \frac{R_x(0) - \mu_x^2}{\varepsilon^2} \quad \forall \varepsilon > 0$$

(b) Let us define the R.P.  $Y(t) \triangleq X(t+T) - X(t) \quad \textcircled{1}$

$$\mu_Y = E\{Y(t)\} = E\{X(t+T)\} - E\{X(t)\} = \mu_x - \mu_x = 0 \quad \textcircled{2}$$

$$\begin{aligned} \text{Var}(Y(t)) &= E\{Y(t)^2\} \stackrel{\textcircled{1}}{=} E\{[X(t+T) - X(t)]^2\} = \\ &= E\{X^2(t+T)\} - 2E\{X(t)X(t+T)\} + E\{X^2(t)\} \quad \textcircled{3} \end{aligned}$$

Since  $X(t)$  is WSS  $\textcircled{4} \Rightarrow \text{Var}(Y(t)) = R_x(0) - 2R_x(T) + R_x(0) \Rightarrow$

$$\Rightarrow \text{Var}(Y(t)) = 2[R_x(0) - R_x(T)] \quad \textcircled{5}$$

Applying the T.I. for  $Y(t)$  we get

$$\Pr\{|Y(t) - E\{Y(t)\}| \geq \varepsilon\} \leq \frac{\text{Var}(Y(t))}{\varepsilon^2} \stackrel{\textcircled{1}}{\underset{\textcircled{2} \textcircled{5}}{\Rightarrow}}$$

$$\Rightarrow \Pr\{|X(t+T) - X(t)| \geq \varepsilon\} \leq \frac{2[R_x(0) - R_x(T)]}{\varepsilon^2} \quad \forall \varepsilon > 0$$

⊙ Problem 2

$$\begin{aligned} \text{(a) We need to show } E\{X(t)X'(t)\} &= E\{X(t)\}E\{X'(t)\} \\ \text{But } E\{X'(t)\} &= \mu_{x'} = \frac{d}{dt} E\{X(t)\} \\ X(t) \text{ is WSS } \Rightarrow E\{X(t)\} &= \mu_x = \text{constant} \end{aligned} \left. \vphantom{\begin{aligned} \text{(a) We need to show } E\{X(t)X'(t)\} &= E\{X(t)\}E\{X'(t)\} \\ \text{But } E\{X'(t)\} &= \mu_{x'} = \frac{d}{dt} E\{X(t)\} \\ X(t) \text{ is WSS } \Rightarrow E\{X(t)\} &= \mu_x = \text{constant} \end{aligned}} \right\} \Rightarrow E\{X'(t)\} = 0$$

$\Rightarrow$  Therefore it suffices to show that  $E\{X(t)X'(t)\} = 0$  ④

By definition  $R_{xx'}(0) = E\{X(t)X'(t)\}$  ①

We also know that  $R_{xx'}(z) = -\frac{dR_x(z)}{dz}$  ②

One of the properties of  $R_x(z)$  is that  $R_x(0) \geq R_x(z) \forall z$ , which means that  $R_x(z)$  has a maximum at  $z=0$ .

Since  $R_x(z)$  is a continuous function of  $z$ , a necessary condition for  $R_x(z)$  to have a maximum at  $z=0$  is

$$\left. \frac{dR_x(z)}{dz} \right|_{z=0} = 0 \quad \text{③}$$

①, ②, ③  $\Rightarrow E\{X(t)X'(t)\} = 0$   $\stackrel{\text{④}}{\Rightarrow} X(t)$  and  $X'(t)$  are uncorrelated.

(b)  $Y(t)$  is the output of a Linear Time Invariant (LTI) system in steady state (the effect of initial conditions, if any, has already diminished) due to a WSS input  $X(t)$ . This implies that  $Y(t)$  is WSS.

Following a similar rationale,  $X'(t)$  is also WSS and  $X(t), X'(t)$  are jointly WSS.

Therefore,

$$\begin{aligned} E\{Y(t)Y(t+\tau)\} &= R_Y(\tau) & \textcircled{4} \\ E\{X(t)X'(t+\tau)\} &= R_{XX'}(\tau) & \textcircled{5} \\ E\{X'(t)X'(t+\tau)\} &= R_{X'}(\tau) & \textcircled{6} \end{aligned}$$

← depend only on  $\tau$

We first start calculating

$$\begin{aligned} R_Y(\tau) &= E\{Y(t)Y(t+\tau)\} \\ Y(t) &= X(t) + X'(t) \end{aligned} \Rightarrow R_Y(\tau) = E\{X(t)X(t+\tau)\} + E\{X(t)X'(t+\tau)\} + E\{X'(t)X(t+\tau)\} + E\{X'(t)X'(t+\tau)\} \Rightarrow$$

$$\textcircled{4} \textcircled{5} \textcircled{6} \Rightarrow R_Y(\tau) = R_X(\tau) + R_{XX'}(\tau) + R_{X'X}(\tau) + R_{X'}(\tau) \quad \textcircled{7}$$

However, we can easily show that

$$\begin{aligned} R_{YX}(\tau) &= R_{XY}(-\tau) \\ Y &= X' \end{aligned} \Rightarrow R_{X'X}(\tau) = R_{XX'}(-\tau) \quad \textcircled{8}$$

Also, we know that  $R_{xx}'(\tau) = -\frac{dR_x(\tau)}{d\tau}$

But  $R_x(\tau) = R_x(-\tau)$  (even function), therefore its derivative

$\frac{dR_x(\tau)}{d\tau}$  must be an odd function. Thus,  $R_{xx}'(-\tau) = -R_{xx}'(\tau)$  ②

$$\textcircled{7} \stackrel{\textcircled{1}}{\Rightarrow} R_y(\tau) = R_x(\tau) + R_x'(\tau) \Rightarrow$$

$$\Rightarrow S_y(f) = \mathcal{F}\{R_y(\tau)\} = S_x(f) + S_x'(f) \quad \blacksquare$$

⊙ Problem 3

(a) Due to  $h(x)$ ,  $Y(t)$  can take only two values:  $\pm 1$

Therefore

$$E\{Y(t)\} = 1 \cdot \Pr\{Y(t) = 1\} + (-1) \Pr\{Y(t) = -1\} \quad (1)$$

$$\text{However } \Pr\{Y(t) = 1\} = \Pr\{X(t) \geq 0\} = 1 - F_{X(t)}(0) \quad (2)$$

$$\Pr\{Y(t) = -1\} = \Pr\{X(t) < 0\} = F_{X(t)}(0^-) \quad (3)$$

where  $F_{X(t)}(x)$  is the CDF of  $X(t)$

$$(1), (2), (3) \Rightarrow E\{Y(t)\} = 1 - F_{X(t)}(0) - F_{X(t)}(0^-) \quad \left. \vphantom{(1), (2), (3)} \right\} \Rightarrow$$

$$\text{But } X(t) \text{ is a Gaussian RP. } \Rightarrow F_{X(t)}(0) = F_{X(t)}(0^-) = \frac{1}{2}$$

$$\Rightarrow E\{Y\} = 0 \quad \blacksquare$$

(b) By definition  $R_Y(\tau) = E\{Y(t)Y(t+\tau)\} \quad (4)$

Again, due to  $h(\cdot)$ ,  $Y(t)Y(t+\tau)$  can only take values  $\pm 1$

Therefore

$$(4) \Rightarrow E\{Y(t)Y(t+\tau)\} = 1 \cdot \Pr\{Y(t)Y(t+\tau) > 0\} + (-1) \cdot$$

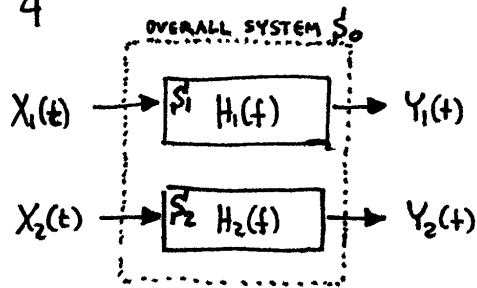
$$\Pr\{Y(t)Y(t+\tau) < 0\} \quad (5)$$

$$\text{However } \Pr\{Y(t)Y(t+\tau) < 0\} = \Pr\{X(t)X(t+\tau) < 0\} \quad (6)$$

$$\Pr\{Y(t)Y(t+\tau) > 0\} = \Pr\{X(t)X(t+\tau) > 0\} \quad (7)$$

$$(4), (5), (6), (7) \Rightarrow R_Y(\tau) = \Pr\{X(t)X(t+\tau) > 0\} - \Pr\{X(t)X(t+\tau) < 0\} \quad \blacksquare$$

⊙ Problem 4



(a)  $Y_1(t)$  and  $Y_2(t)$  can be thought to be the output of an LTI system  $S_0$  in steady state (there's no effect due to initial conditions, if any) due to the inputs  $X_1(t)$  and  $X_2(t)$ .

Therefore, since  $X_1(t), X_2(t)$  jointly WSS,  $Y_1(t), Y_2(t)$  are also jointly WSS. Thus,

$$R_{Y_1 Y_2}(t, t+z) = R_{Y_1 Y_2}(z) \quad \leftarrow \text{depends only on } z, \text{ not on } t.$$

$$\left. \begin{aligned} R_{Y_1 Y_2}(z) &= E\{Y_1(t)Y_2(t+z)\} \\ Y_1(t) &= h_1(t) * X_1(t) = \int_{-\infty}^{+\infty} h_1(u)X_1(t-u)du \\ Y_2(t) &= h_2(t) * X_2(t) = \int_{-\infty}^{+\infty} h_2(v)X_2(t+z-v)dv \end{aligned} \right\} \Rightarrow$$

$$\begin{aligned} \Rightarrow R_{Y_1 Y_2}(z) &= \int_{-\infty}^{+\infty} \int_{-\infty}^{+\infty} h_1(u)h_2(v) E\{X_1(t-u)X_2(t+z-v)\} dudv = \\ &= \int_{-\infty}^{+\infty} \int_{-\infty}^{+\infty} h_1(u)h_2(v) R_{X_1 X_2}(z-v+u) dudv \Rightarrow \end{aligned}$$

$$\Rightarrow R_{Y_1 Y_2}(z) = h_1(z) * h_2(-z) * R_{X_1 X_2}(z-v+u) \quad \textcircled{1}$$

$$S_{Y_1 Y_2}(f) = \mathcal{F}\{R_{Y_1 Y_2}(\tau)\} \stackrel{\textcircled{1}}{\Rightarrow} S_{Y_1 Y_2}(f) = H_1(f) H_2^*(f) S_{X_1 X_2}(f) \quad \textcircled{2}$$

(b)  $X_1(t)$  and  $X_2(t)$  are jointly Gaussian R.P.'s linearly transformed by system  $S_0$  in steady state, therefore  $Y_1(t)$ ,  $Y_2(t)$  are also jointly Gaussian R.P.'s.  $Y_1(t)$  and  $Y_2(t)$  are also jointly WSS (see part a)

(c) From  $\textcircled{2}$  we get 
$$\left. \begin{aligned} |S_{Y_1 Y_2}(f)| &= |H_1(f)| |H_2^*(f)| |S_{X_1 X_2}(f)| \\ |H_2^*(f)| &= |H_2(f)| \\ \text{By the hypothesis } |H_1(f)| |H_2(f)| &= 0 \quad \forall f \end{aligned} \right\} \Rightarrow$$

$$\Rightarrow |S_{Y_1 Y_2}(f)| = 0 \quad \forall f \Rightarrow R_{Y_1 Y_2}(\tau) = 0 \quad \forall \tau$$

$$\left. \begin{aligned} C_{Y_1 Y_2}(\tau) &= R_{Y_1 Y_2}(\tau) - E\{Y_1(t)\} E\{Y_2(t)\} \end{aligned} \right\} \Rightarrow$$

$$\Rightarrow C_{Y_1 Y_2}(\tau) = -E\{Y_1(t)\} E\{Y_2(t)\}$$

But we know that 
$$\left. \begin{aligned} E\{Y_1(t)\} &= H_1(0) E\{X_1(t)\} \\ E\{Y_2(t)\} &= H_2(0) E\{X_2(t)\} \end{aligned} \right\} \Rightarrow C_{Y_1 Y_2}(\tau) = -H_1(0) H_2(0) E\{X_1(t)\} E\{X_2(t)\} \quad \textcircled{3}$$

By the hypothesis  $|H_1(f)| |H_2(f)| = 0 \quad \forall f$ , therefore  $C_{Y_1 Y_2}(\tau) = 0 \Rightarrow$

$\Rightarrow Y_1(t), Y_2(t)$  uncorrelated  $\Rightarrow Y_1(t), Y_2(t)$  independent

Part (b)  $\Rightarrow Y_1(t), Y_2(t)$  jointly Gaussian

(d) The only result that will hold is that  $Y_1(t), Y_2(t)$  are still jointly Gaussian R.P.'s.

⊙ Problem 5

(a) We will solve the difference equation:

$$\left. \begin{array}{l} n=0 \quad X_0 = \alpha X_{-1} + W_0 \\ n=1 \quad X_1 = \alpha X_0 + W_1 \\ n=2 \quad X_2 = \alpha X_1 + W_2 \\ \vdots \\ \text{etc.} \end{array} \right\} \Rightarrow X_n = \alpha^{n+1} X_{-1} + \sum_{i=0}^n \alpha^i W_{n-i} \quad \textcircled{1}$$

$$\textcircled{1} \Rightarrow \left. \begin{array}{l} E\{X_n\} = \alpha^{n+1} E\{X_{-1}\} + \sum_{i=0}^n \alpha^i E\{W_{n-i}\} \\ W_n \text{ is white Gaussian noise} \Rightarrow W_n \text{ is WSS} \\ E\{W_n\} = 0 \\ \text{From the hypothesis } E\{X_{-1}\} = \mu \end{array} \right\} \Rightarrow$$

$$\Rightarrow E\{X_n\} = \alpha^{n+1} \mu \quad \textcircled{2}$$

We observe that  $E\{X_n\}$  depends on  $n$  (we assume  $\mu \neq 0$ ), therefore  $X_n$  is neither WSS or SSS R.P. ■

(b) From ③ we have:

$$\left. \begin{aligned} \textcircled{2} \Rightarrow \lim_{n \rightarrow +\infty} E\{X_n\} &= \mu \lim_{n \rightarrow +\infty} \alpha^{n+1} \\ |\alpha| < 1 \Rightarrow \lim_{n \rightarrow +\infty} \alpha^n &= 0 \end{aligned} \right\} \Rightarrow \lim_{n \rightarrow +\infty} E\{X_n\} = 0 \quad \textcircled{3}$$

Therefore,  $X_n$  is mean-stationary in the limit  $n \rightarrow +\infty$ .

In order to show that  $X_n$  becomes WSS when  $n \rightarrow +\infty$ , we also need to show that  $R_X(m, m) = R_X(m-n)$  or alternatively (due to ③) that  $C_X(m, m) = C_X(m-n)$  in the limit  $n \rightarrow +\infty$ .

$$\begin{aligned} C_X(m, m) &= E\{[X_m - E\{X_m\}][X_m - E\{X_m\}]\} = \\ &= \alpha^{m+n+2} \sigma_x^2 + \sum_{i=0}^m \sum_{j=0}^m \alpha^{i+j} E\{W_{n-i} W_{m-j}\} \end{aligned} \quad \left. \right\} \Rightarrow$$

Since  $W_n$  is white noise  $E\{W_{n-i} W_{m-j}\} = \begin{cases} \sigma_w^2 & \text{when } i = j + n - m \\ 0 & \text{otherwise} \end{cases}$

$$\Rightarrow C_X(m, m) = \alpha^{m+n+2} \sigma_x^2 + \sigma_w^2 \alpha^{m-n} \sum_{i=0}^n \alpha^{2i} \quad \textcircled{4}$$

where we have assumed that  $m \geq n$ .

Since  $m \geq n \Rightarrow$  we can write  $m = n + k$  and ④ becomes

$$\textcircled{4} \Rightarrow C_X(m, n+k) = \alpha^{2(n+1)+k} \sigma_x^2 + \sigma_w^2 \alpha^k \sum_{i=0}^n \alpha^{2i} \quad \textcircled{5}$$

Taking the limit of ⑤ for  $n \rightarrow +\infty$  we get

$$\lim_{n \rightarrow +\infty} C_x(n, n+k) = \alpha^k \sigma_x^2 \lim_{n \rightarrow +\infty} \alpha^{2(n+1)} + \sigma_w^2 \alpha^k \lim_{n \rightarrow +\infty} \sum_{i=0}^n \alpha^{2i}$$

$$\left. \begin{aligned} &|\alpha| < 1 \Rightarrow \lim_{n \rightarrow +\infty} \alpha^n = 0 \\ &|\alpha| < 1 \Rightarrow \sum_{i=0}^{+\infty} [\alpha^2]^i = \frac{1}{1-\alpha^2} \end{aligned} \right\} \Rightarrow$$

$$\Rightarrow \lim_{n \rightarrow +\infty} C_x(n, n+k) = \frac{\sigma_w^2 \alpha^k}{1-\alpha^2} = C_x(k) \quad \text{for } k \geq 0$$

$$\left. \begin{aligned} &\text{For } E\{X_n\} = 0 \Rightarrow C_x(k) = C_x(-k) \end{aligned} \right\} \Rightarrow$$

$$\Rightarrow \lim_{n \rightarrow +\infty} C_x(n, n+k) = \frac{\sigma_w^2 \alpha^{|k|}}{1-\alpha^2} = C_x(k) \quad \forall k \quad \textcircled{6}$$

From ③ and ⑥ we conclude that  $X_n$  becomes WSS as  $n \rightarrow +\infty$ . ■

$$(c) \quad \text{If } \alpha \geq 1 \quad \left. \begin{aligned} &\lim_{n \rightarrow +\infty} \alpha^n = +\infty \\ &\textcircled{2} \end{aligned} \right\} \Rightarrow \lim_{n \rightarrow +\infty} E\{X_n\} = +\infty$$

therefore  $X_n$  cannot be stationary in any sense. ■

(d) Due to ③ and ⑤  $X_m$  is AR(1) R.P. with  $\sigma^2 = \sigma_w^2$  and parameter  $\theta = \alpha$ . ■

(e) Due to ①  $X_m$  is a Gaussian R.P.

$$\text{When } n \rightarrow +\infty \begin{cases} \text{③} \Rightarrow E\{X_m\} = 0 \\ \text{⑥} \Rightarrow \text{Var}\{X_m\} = C_x(0) = \frac{\sigma_w^2}{1-\alpha^2} \end{cases}$$

Hence,  $X_m$  is Gaussian with  $X_m \sim \mathcal{N}\left(0, \frac{\sigma_w^2}{1-\alpha^2}\right)$ . ■