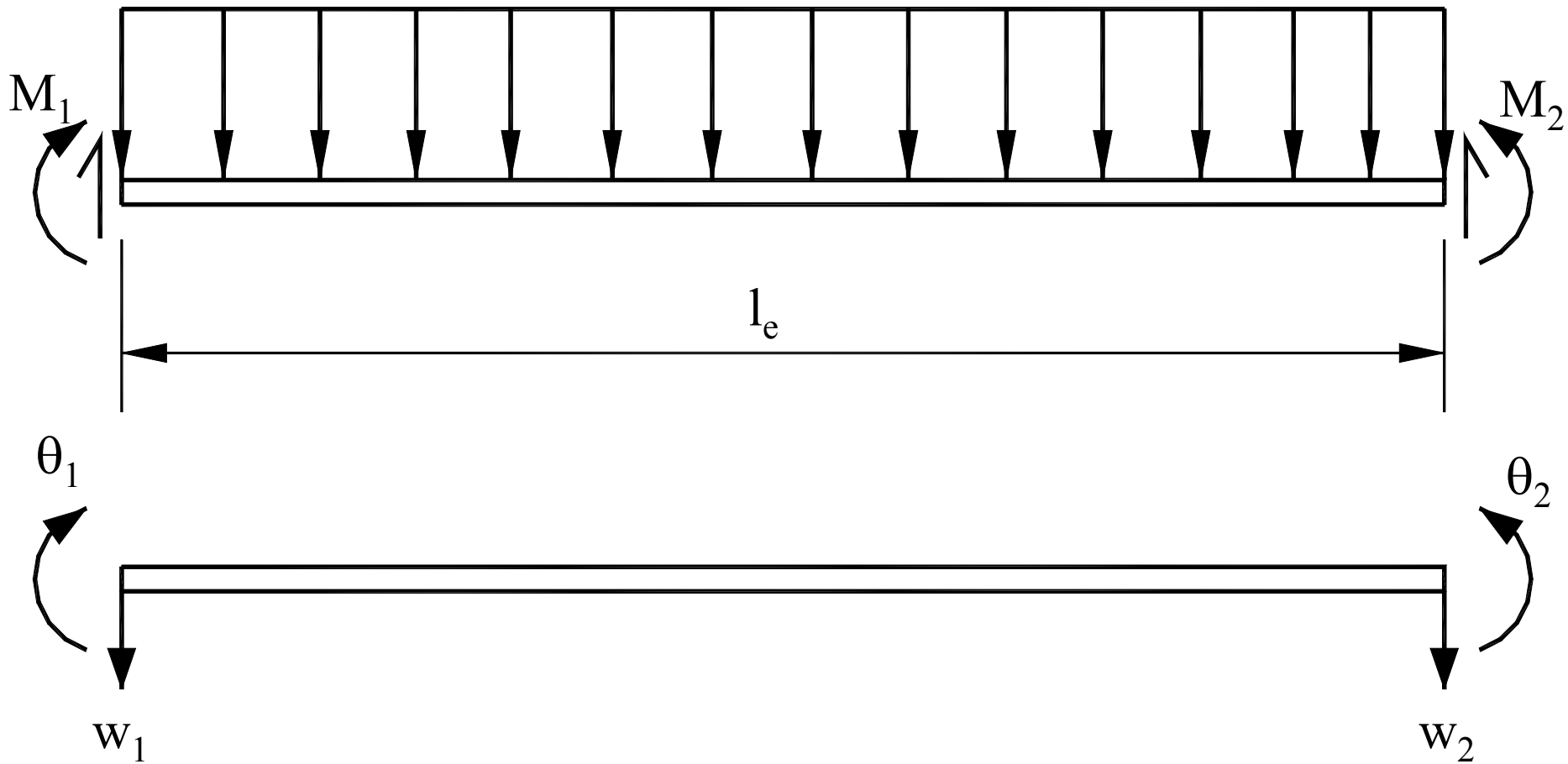


# EXERCISE

By using Potential Energy Approach, prove that the stiffness matrix for the beam element (loaded by uniform distributed load) is:

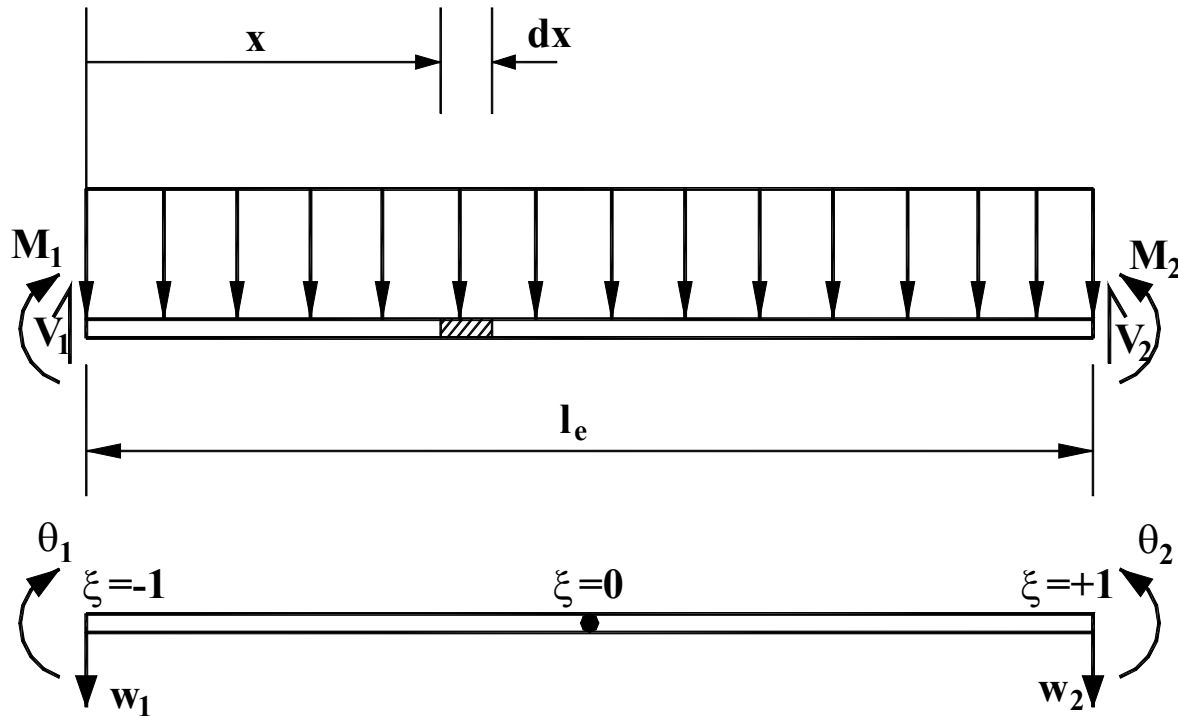
$$\mathbf{k}^e = \frac{EI}{l_e^3} \begin{bmatrix} 12 & 6l_e & -12 & 6l_e \\ 6l_e & 4l_e^2 & -6l_e & 2l_e^2 \\ -12 & -6l_e & 12 & -6l_e \\ 6l_e & 2l_e^2 & -6l_e & 4l_e^2 \end{bmatrix}$$

Use Hermite or cubic shape function to relate displacements in the element and nodal displacements.



**SOLUTION**

# HERMITE SHAPE FUNCTION



$$w(\xi) = H_1 w_1 + H_2 \theta_1 + H_3 w_2 + H_4 \theta_2$$

$$= H_1 w_1 + H_2 \left( \frac{dw}{d\xi} \right)_1 + H_3 w_2 + H_4 \left( \frac{dw}{d\xi} \right)_2$$

*Note: Alternative way*

# HERMITE SHAPE FUNCTION

$$H_1 = \frac{1}{4}(2 - 3\xi + \xi^3)$$

*Note: Alternative way*

$$H_2 = \frac{1}{4}(1 - \xi - \xi^2 + \xi^3)$$

$$H_3 = \frac{1}{4}(2 + 3\xi - \xi^3)$$

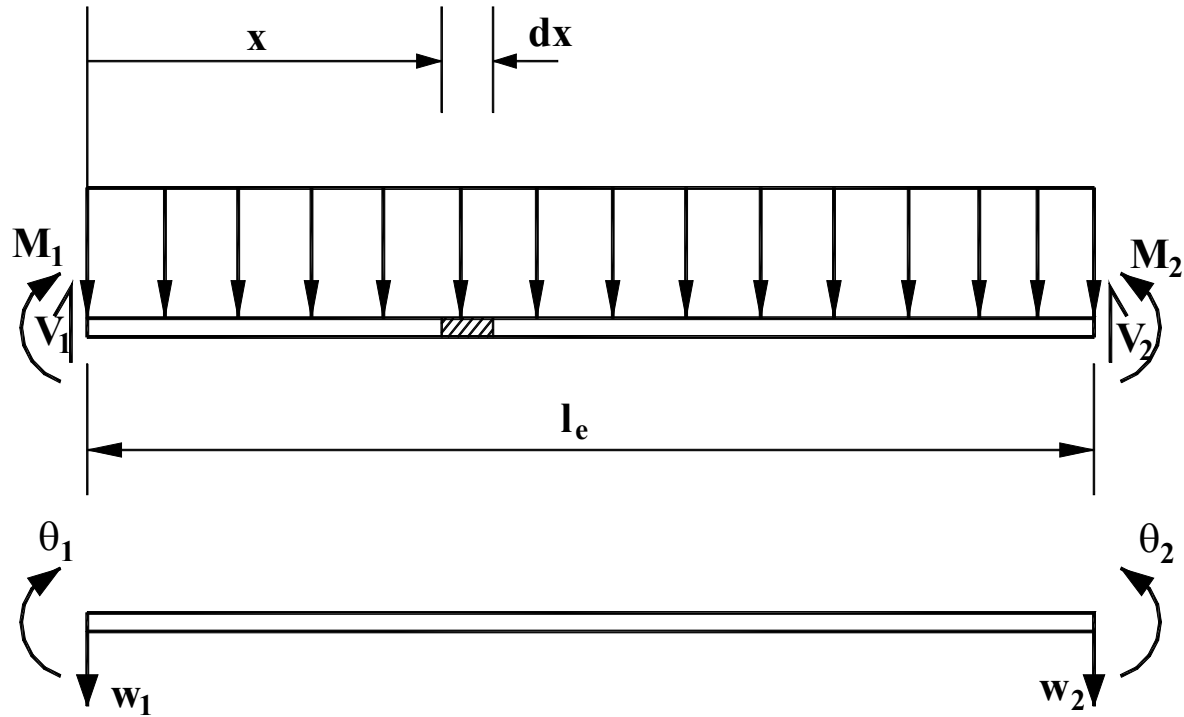
$$H_4 = \frac{1}{4}(-1 - \xi + \xi^2 + \xi^3)$$

# COORDINATE TRANSFORMATION

$$x = \frac{x_1 + x_2}{2} + \frac{x_2 - x_1}{2} \xi$$

gives  $dx = \frac{l_e}{2} d\xi$

# CUBIC SHAPE FUNCTION



$$\begin{aligned}
 w(x) &= N_1 w_1 + N_2 \theta_1 + N_3 w_2 + N_4 \theta_2 = \mathbf{Nw} \\
 &= N_1 w_1 + N_2 \left( \frac{dw}{dx} \right)_1 + N_3 w_2 + N_4 \left( \frac{dw}{dx} \right)_2
 \end{aligned}$$

# CUBIC SHAPE FUNCTION

$$N_1 = \frac{1}{l_e^3} (l_e^3 - 3l_e x^2 + 2x^3)$$

$$N_2 = \frac{1}{l_e^2} (l_e^2 x - 2l_e x^2 + x^3)$$

$$N_3 = \frac{1}{l_e^3} (3l_e x^2 - 2x^3)$$

$$N_4 = \frac{1}{l_e^2} (x^3 - l_e x^2)$$

$$dU = \frac{1}{2} \frac{M^2}{EI} dx$$

but  $M = EI \frac{d^2 w}{dx^2} = \mathbf{D} \mathbf{A} w$

$$\mathbf{D} = EI$$

$$\mathbf{A} = \frac{d^2}{dx^2}$$

$$dU = \frac{1}{2} \frac{M}{EI} M dx$$

$$= \frac{1}{2EI} \left( EI \frac{d^2 w}{dx^2} \right) M dx$$

$$= \frac{1}{2} \left( \frac{d^2 w}{dx^2} \right) M dx$$

$$= \frac{1}{2} (\mathbf{A} w)^T M dx$$

$$= \frac{1}{2} (\mathbf{A} \mathbf{N} w)^T M dx$$

$$w(x) = \mathbf{N} w$$

$$dU = \frac{1}{2} (\mathbf{A} \mathbf{N} w)^T \mathbf{D} \mathbf{A} w dx$$

$$= \frac{1}{2} (\mathbf{A} \mathbf{N} w)^T \mathbf{D} \mathbf{A} \mathbf{N} w dx$$

$$= \frac{1}{2} w^T (\mathbf{A} \mathbf{N})^T \mathbf{D} \mathbf{A} \mathbf{N} w dx$$

The total strain energy of the element is thus

$$U = \frac{1}{2} \int_0^{l_e} \mathbf{w}^T (\mathbf{AN})^T \mathbf{DAN} \mathbf{w} dx$$

or

$$U = \frac{1}{2} \int_0^{l_e} \mathbf{w}^T \mathbf{B}^T \mathbf{DB} \mathbf{w} dx \quad \text{where } \mathbf{B} = \mathbf{AN}$$

$$= \frac{1}{2} \mathbf{w}^T \left( \int_0^{l_e} \mathbf{B}^T \mathbf{DB} dx \right) \mathbf{w}$$

# EXTERNAL WORK

External work (element  $dx$ ),  $dW = qwdx$

Total external work over element, 
$$\begin{aligned} W &= \int_0^{l_e} qw^T dx \\ &= \int_0^{l_e} q(N\mathbf{w})^T dx \\ &= \int_0^{l_e} q\mathbf{w}^T N^T dx \\ &= q\mathbf{w}^T \int_0^{l_e} N^T dx \\ &= \mathbf{w}^T q \int_0^{l_e} N^T dx \end{aligned}$$

# POTENTIAL ENERGY APPROACH

$$\Pi = U - W$$